# An SMT-based Approach to Fair Termination Analysis

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### Fair Termination Analysis

- **Tair** Termination: No non-fair infinite execution sequence  $\sigma$ .
- PSPACE-complete for boolean programs.

### Fair Termination Analysis

- **F**air termination: No non-fair infinite execution sequence  $\sigma$ .
- PSPACE-complete for boolean programs.

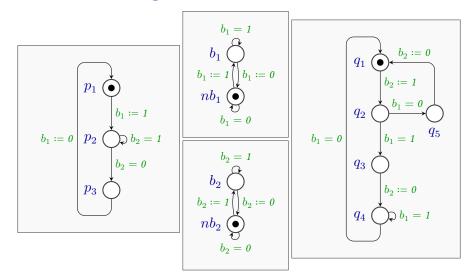
### **SMT-Based Approach**

- Incomplete method based on reduction to feasibility of linear arithmetic constraints.
- Strengthened with refinement cycle which adds mixed linear and boolean constraints.
- Similar method previously applied for safety properties (An SMT-based Approach to Coverability Analysis, CAV14).

### Lamport's 1-bit Algorithm for Mutual Exclusion

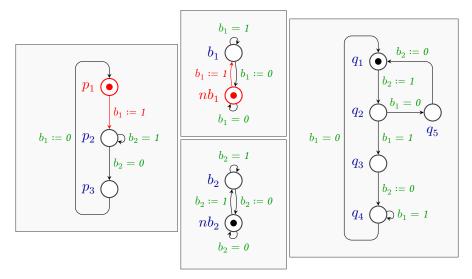
```
procedure Process 1
                                       procedure Process 2
   begin
                                       begin
     b_1 := 0
                                         b_2 := 0
     while true do
                                         while true do
      b_1 := 1
                                         b_2 := 1
                                    q_1:
p_1:
                                       if b_1 = 1 then
     while b_2 = 1 do skip od
                                    q_2:
p_2:
      (* critical section *)
                                             b_2 := 0
p_3:
                                    q_3:
                                             while b_1 = 1 do skip od
       b_1 := 0
                                    q_4:
     od
                                             goto q_1
                                           fi
   end
                                           (* critical section *)
                                    q_5:
                                           b_2 := 0
                                         od
                                       end
```

# Communicating Automata Model



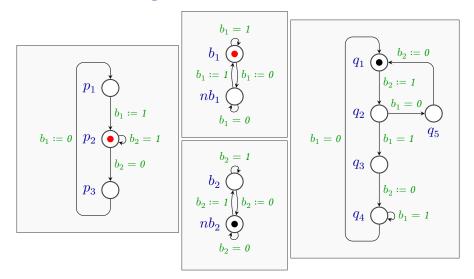
Property: If both processes are executed infinitely often, then the first process should enter the critical section  $(p_3)$  infinitely often.

# Communicating Automata Model



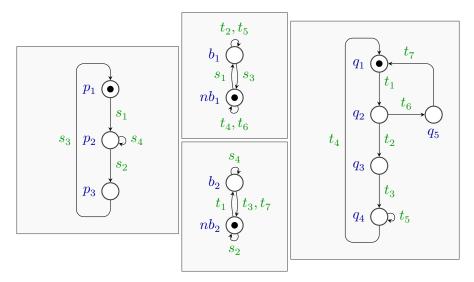
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# Communicating Automata Model



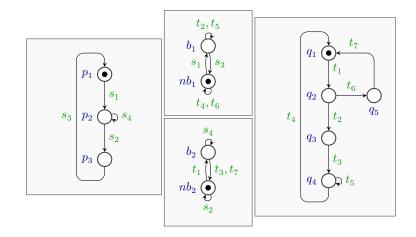
Property: If both processes are executed infinitely often, then the first process should enter the critical section  $(p_3)$  infinitely often.

### Abstract View of the Model

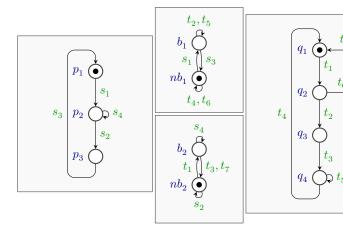


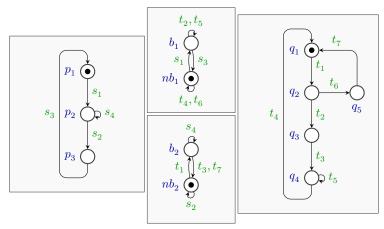
Property: For every infinite transition sequence  $\sigma$ , we have  $\varphi(\sigma) = \bigvee_{i=1}^4 (s_i \in \inf(\sigma)) \wedge \bigvee_{i=1}^7 (t_i \in \inf(\sigma)) \implies s_2 \in \inf(\sigma).$ 

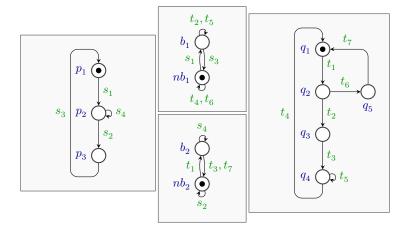
$$\{p_1, nb_1, nb_2, q_1\} \xrightarrow{t_1t_6t_7s_1t_1t_2t_3s_2t_5s_3t_4} \{p_1, nb_1, nb_2, q_1\}$$

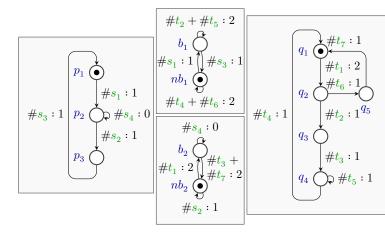


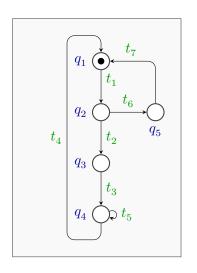
$$\begin{aligned} \{p_1, nb_1, nb_2, q_1\} &\xrightarrow{t_1t_6t_7s_1t_1t_2t_3s_2t_5s_3t_4} \{p_1, nb_1, nb_2, q_1\} \\ & \quad \#t_1 \quad \#t_2 \quad \#t_3 \quad \#t_4 \quad \#t_5 \quad \#t_6 \quad \#t_7 \quad \#s_1 \quad \#s_2 \quad \#s_3 \quad \#s_4 \end{aligned} \\ \#\sigma = \left( \right.$$

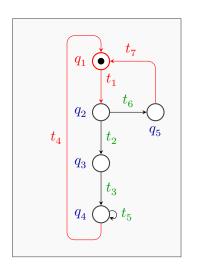




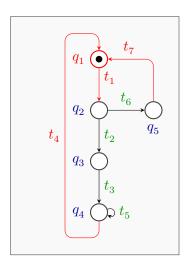




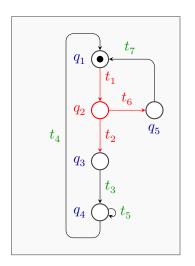




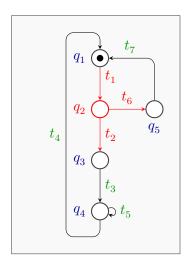
$$q_1: \qquad t_4+t_7=t_1$$



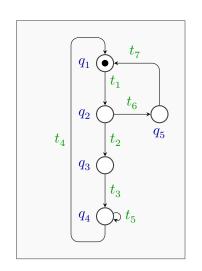
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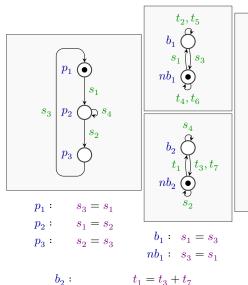


$$\begin{array}{ll} q_1: & & t_4+t_7=t_1 \\ q_2: & & t_1=t_2+t_6 \end{array}$$



$$\begin{array}{lll} q_1: & t_4+t_7=t_1 \\ q_2: & t_1=t_2+t_6 \\ q_3: & t_2=t_3 \\ q_4: & t_3=t_4 \\ q_5: & t_6=t_7 \end{array}$$





 $nb_2: t_3 + t_7 = s_1$ 

 $\begin{array}{lll} q_1: & t_4+t_7=t_1\\ q_2: & t_1=t_2+t_6\\ q_3: & t_2=t_3\\ q_4: & t_3=t_4\\ q_5: & t_6=t_7 \end{array}$ 

#### **Termination Constraints**

- Accumulate constraints in matrix form as  $C \cdot X = 0$ .
- If there is an infinite transition sequence  $\sigma$ , then the following constraints have a solution X:

$$\mathcal{C} :: \begin{cases} C \cdot X = 0 \\ X \ge 0 \\ X \ne 0 \end{cases}$$

- If the constraints have no solution, then the program is terminating.
- A solution X is *realizable* if there is a sequence  $\sigma$  with  $\#\sigma = X$ .

### **Fair Termination Constraints**

- Fairness condition given by boolean formula  $\varphi$  over  $t \in \inf(\sigma)$ .
- If the program is not fairly terminating, then there is an infinite transition sequence  $\sigma$  satisfying  $\sigma \models \neg \varphi$ .
- Add constraint  $\neg \varphi(X)$  to  $\mathcal C$  for fair termination constraints.

### Fairness for Lamport's Algorithm

$$\varphi(\sigma) = \bigvee_{i=1}^4 (s_i \in \inf(\sigma)) \land \bigvee_{i=1}^7 (t_i \in \inf(\sigma)) \implies s_2 \in \inf(\sigma)$$

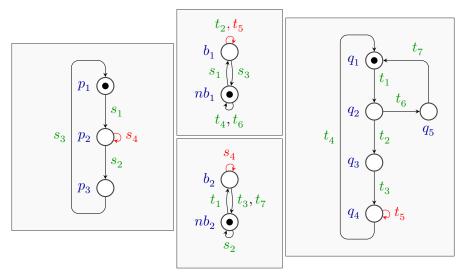
$$\neg \varphi(X) = (s_1 + s_2 + s_3 + s_4 > 0) \land 
(t_1 + t_3 + t_4 + t_5 + t_6 + t_7 > 0) \land 
(s_2 = 0)$$

### Fair Termination Constraints

# Fair Termination Constraints: Solution

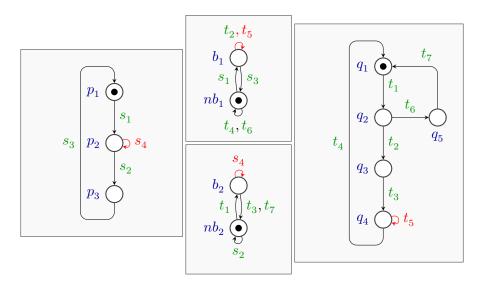
### Fair Termination Constraints: Solution

$$X = \begin{pmatrix} t_1 & t_2 & t_3 & t_4 & t_5 & t_6 & t_7 & s_1 & s_2 & s_3 & s_4 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$



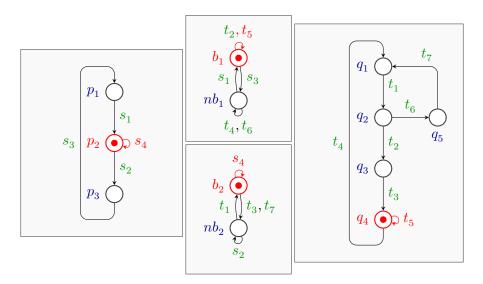
### Solution realizable?

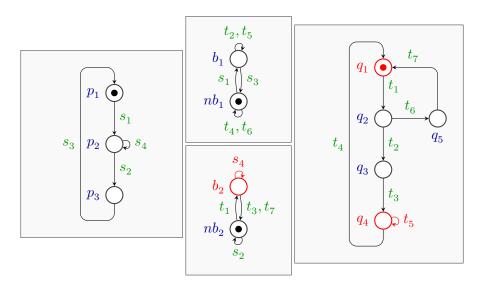
X realized by  $\sigma$  with  $\inf(\sigma) = \{s_4, t_5\}$ .

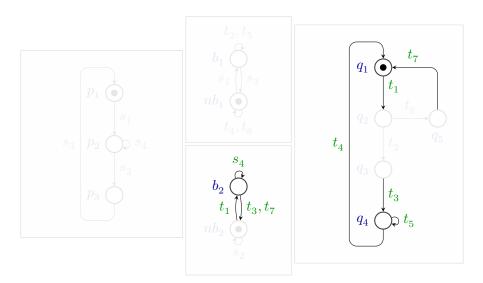


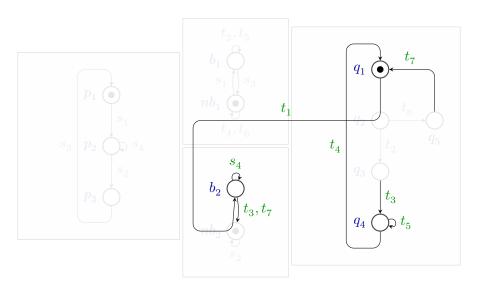
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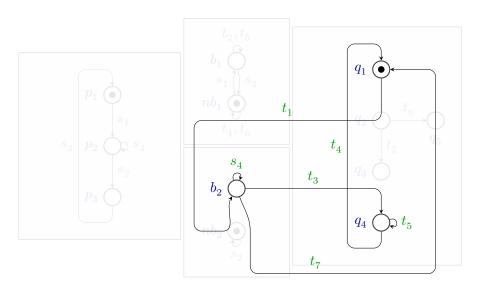
X realized by  $\sigma$  with  $\inf(\sigma) = \{s_4, t_5\}$ .





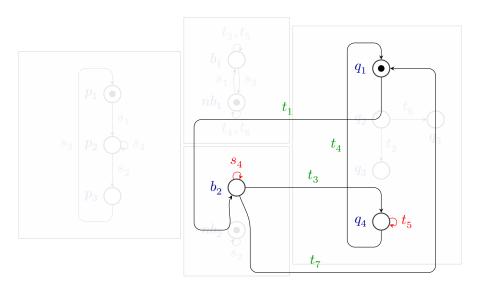






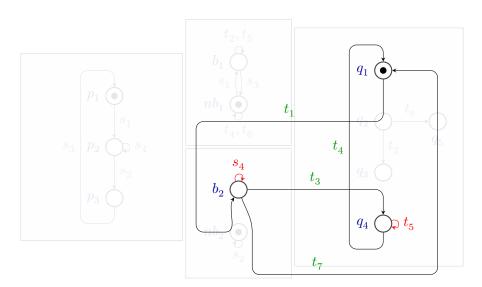
### Refinement Constraint

X realized by  $\sigma$  with  $\inf(\sigma) = \{s_4, t_5\}$ .



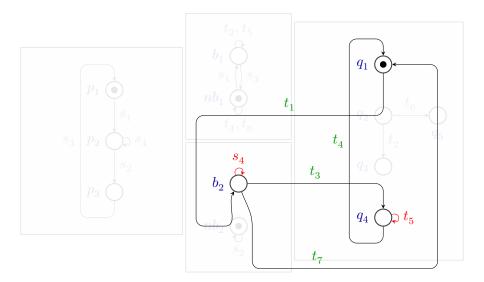
### Refinement Constraint

*X* not realizable  $\Rightarrow$  Generate refinement constraint  $\delta$ .



### Refinement Constraint

$$\delta = (s_4 = 0) \vee (t_5 = 0) \vee (t_1 + t_3 + t_4 + t_7 > 0)$$

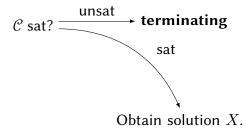


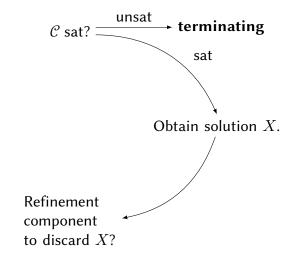
# Refinement Loop

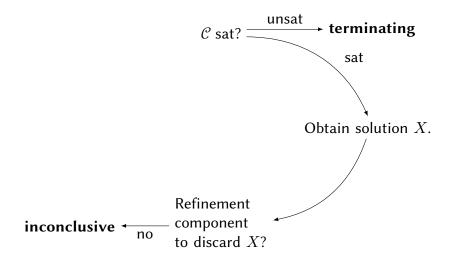
 $\mathcal C$  sat?

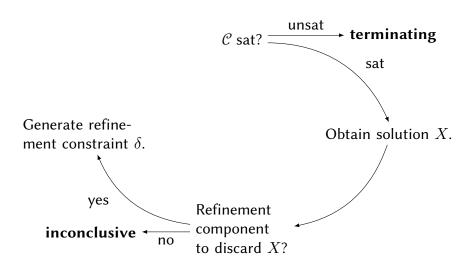
# Refinement Loop

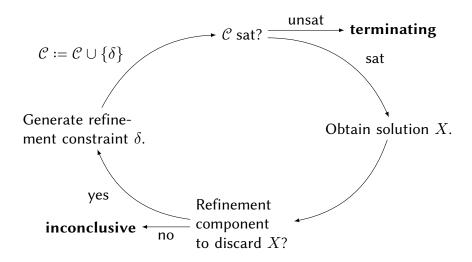
 $_{\mathcal{C} \text{ sat?}} \xrightarrow{\text{unsat}} \text{terminating}$ 









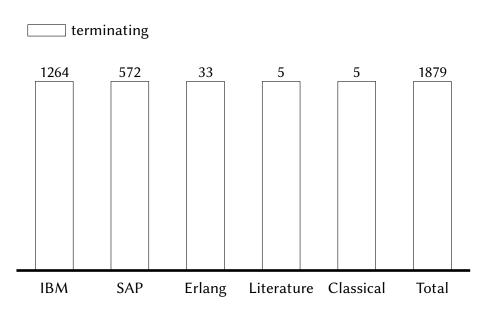


### **Experimental Evaluation**

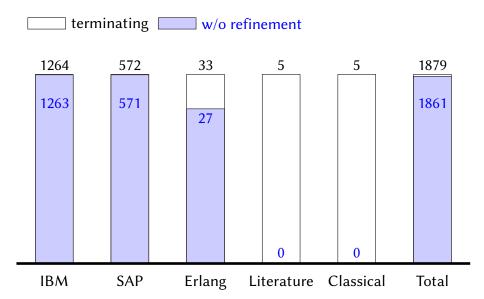
#### **Benchmarks**

- IBM/SAP Workflow nets from business process models
  - 1976 examples
  - 1836 terminating
- Erlang Models from the verification of Erlang programs
  - 50 examples, up to 66950 places and 213626 transitions
  - 33 terminating
- Literature Selected examples from the literature
  - 5 examples, with unbounded variables
  - All terminating
- Classical Classic asynchronous programs for mutual exclusion and distributed algorithms
  - 5 examples, scalable in number of processes
  - All fairly terminating

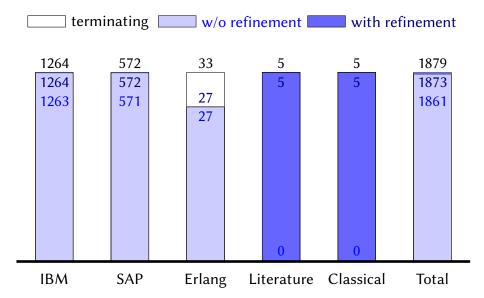
### Rate of Success



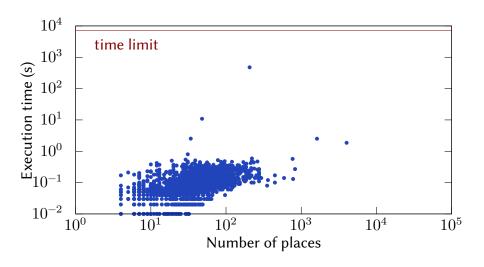
#### Rate of Success



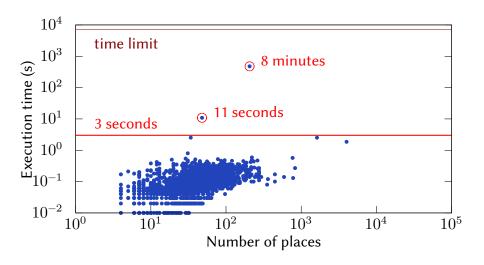
#### Rate of Success



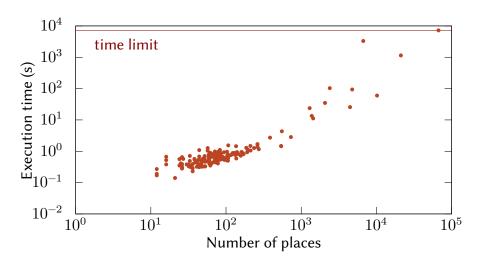
### Performance on Positive Examples



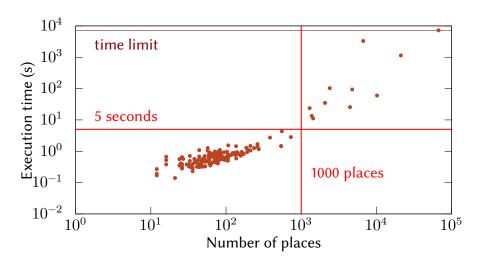
### Performance on Positive Examples



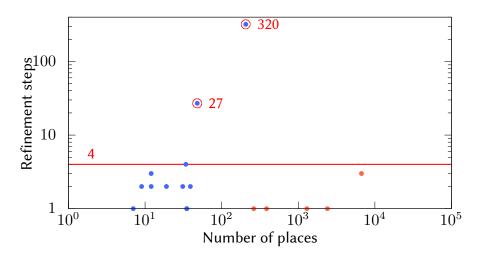
## Performance on Negative Examples



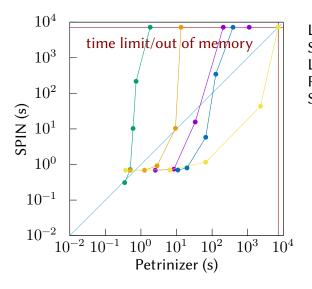
## Performance on Negative Examples



# **Refinement Steps**



### Comparison with SPIN on Scaled Classical Suite



Leader Election
Snapshot
Lamport
Peterson
Szymanski

### Summary

- Fast and effective technique for proving fair termination
- Incomplete, but high degree of completeness
- Large instances can be handled
- Constraints can be used as a certificate of fair termination