# Model Checking – Exercise sheet 7

### Exercise 7.1

Given two CTL formulas  $\phi_1$  and  $\phi_2$ , we write  $\phi_1 \Rightarrow \phi_2$  iff for every Kripke structure  $\mathcal{K}$  we have  $(\mathcal{K} \models \phi_1) \Rightarrow (\mathcal{K} \models \phi_2)$ . Furthermore, we define an *implication graph* as a directed graph whose nodes are CTL formulas, and that contains an edge from  $\phi_1$  to  $\phi_2$  iff  $\phi_1 \Rightarrow \phi_2$ . Let  $AP = \{p\}$ .

- (a) Draw an implication graph with the nodes: EFEFp, EGEGp, AFAFp, AGAGp.
- (b) For each implication  $\phi_1 \Rightarrow \phi_2$  obtained in (a), give a Kripke structure  $\mathcal{K}$  that satisfies  $\phi_2$  but not  $\phi_1$ , i.e. give a  $\mathcal{K}$  such that  $\mathcal{K} \models \phi_2$  and  $\mathcal{K} \not\models \phi_1$ .
- (c) Add the following CTL formulas to the implication graph obtained in (a):  $\mathbf{AFEF}p$ ,  $\mathbf{EFAF}p$ ,  $\mathbf{AGEG}p$ ,  $\mathbf{EGAG}p$ .
- (d) Complete the graph obtained in (c) with the nodes: AGAFp, AFAGp, AGEFp, EGAFp, AFEGp, EFAGp, EFEGp, EGEFp.

#### Exercise 7.2

Consider the following Kripke structure over  $AP = \{p, q\}$ :



- (a) Compute  $\llbracket \mathbf{E}\mathbf{G}q \rrbracket$  and  $\llbracket \mathbf{E}\mathbf{F}q \rrbracket$ .
- (b) Compute  $\llbracket \mathbf{A}\mathbf{G}\mathbf{A}\mathbf{F}p \rrbracket$  and  $\llbracket \mathbf{E}\mathbf{F}\mathbf{A}\mathbf{G}\neg q \rrbracket$ .

## Solution 7.1

Note that the " $\Rightarrow$ " relation is transitive, hence all transitive edges in (a), (b) and (d) are omitted.

(a)



(b) The following Kripke structure satisfies  $\mathbf{EG}p$ , but not  $\mathbf{AG}p$ :



The following Kripke structure satisfies  $\mathbf{AF}p$ , but not  $\mathbf{EG}p$ :



The following Kripke structure satisfies  $\mathbf{EF}p$ , but not  $\mathbf{AF}p$ :



(c)



(d)



## Solution 7.2

Let  $S = \{s_0, s_1, s_2, s_3, s_4, s_5, s_6, s_7\}.$ 

(a) • We compute the largest fixed point from the sequence

 $\pi^{0}(S), \pi^{1}(S), \pi^{2}(S), \dots$ where  $\pi^{0}(S) = S$  and  $\pi^{i+1}(S) = \llbracket q \rrbracket \cap pre(\pi^{i}(S))$ . We obtain  $\pi^{0}(S) = S,$  $\pi^{1}(S) = \{s_{0}, s_{4}, s_{5}, s_{7}\},$  $\pi^{2}(S) = \{s_{0}, s_{4}, s_{5}, s_{7}\}.$ 

Therefore,  $[\![\mathbf{E}\mathbf{G}q]\!] = \{s_0, s_4, s_5, s_7\}.$ 

• We compute the smallest fixed point from the sequence

$$\xi^0(\emptyset), \xi^1(\emptyset), \xi^2(\emptyset), \dots$$

where  $\xi^0(\emptyset) = \emptyset$  and  $\xi^{i+1}(\emptyset) = \llbracket q \rrbracket \cup pre(\xi^i(\emptyset))$ . We obtain

$$\begin{split} \xi^{0}(\emptyset) &= \emptyset, \\ \xi^{1}(\emptyset) &= \{s_{0}, s_{4}, s_{5}, s_{7}\}, \\ \xi^{2}(\emptyset) &= \{s_{0}, s_{4}, s_{5}, s_{6}, s_{7}\}, \\ \xi^{3}(\emptyset) &= \{s_{0}, s_{4}, s_{5}, s_{6}, s_{7}\}. \end{split}$$

Therefore,  $[\![\mathbf{EF}q]\!] = \{s_0, s_4, s_5, s_6, s_7\}.$ 

(b) • Note that  $\mathbf{AGAF}p \equiv \neg \mathbf{EFEG} \neg p$ . Let us first compute  $\llbracket \mathbf{EG} \neg p \rrbracket$  by computing the largest fixed point from the sequence  $\pi^0(S), \pi^1(S), \pi^2(S), \ldots$  We obtain

$$\pi^{0}(S) = S,$$
  

$$\pi^{1}(S) = \{s_{0}, s_{2}, s_{5}, s_{7}\},$$
  

$$\pi^{2}(S) = \{s_{7}\},$$
  

$$\pi^{3}(S) = \{s_{7}\}.$$

Therefore,  $\llbracket \mathbf{E}\mathbf{G}\neg p \rrbracket = \{s_7\}$ . In general,  $\llbracket \mathbf{E}\mathbf{F}\varphi \rrbracket$  is the set of states that can reach some state of  $\llbracket \varphi \rrbracket$ . By setting  $\varphi = \mathbf{E}\mathbf{G}\neg p$ , we obtain

$$\begin{bmatrix} \mathbf{AGAF}p \end{bmatrix} = \begin{bmatrix} \neg \mathbf{EFEG} \neg p \end{bmatrix}$$
$$= \boxed{\begin{bmatrix} \mathbf{EFEG} \neg p \end{bmatrix}}$$
$$= \overline{\{s_0, s_6, s_7\}}$$
$$= \{s_1, s_2, s_3, s_4, s_5\}.$$

• Note that  $\mathbf{EFAG} \neg q \equiv \mathbf{EF} \neg \mathbf{EF}q$ . By (a),  $\llbracket \mathbf{EF}q \rrbracket = \{s_0, s_4, s_5, s_6, s_7\}$ , and hence  $\llbracket \neg \mathbf{EF}q \rrbracket = \llbracket \mathbf{EF}q \rrbracket = \{s_1, s_2, s_3\}$ . In general,  $\llbracket \mathbf{EF}\varphi \rrbracket$  is the set of states that can reach some state of  $\llbracket \varphi \rrbracket$ . By setting  $\varphi = \neg \mathbf{EF}q$ , we obtain

$$\llbracket \mathbf{EFAG} \neg q \rrbracket = \llbracket \mathbf{EF} \neg \mathbf{EF} q \rrbracket = \{s_0, s_1, s_2, s_3, s_4, s_5\}.$$