

Model Checking – Sample Solution 11

Exercise 11.1

- (a) Yes. $H = \{(s_0, t_0), (s_1, t_1), (s_2, t_2), (s_3, t_2), (s_4, t_0)\}$.
- (b) No. If there exists a simulation H from \mathcal{K}_3 to \mathcal{K}_2 , then we know that $(u_0, t_0) \in H$. Since $u_0 \rightarrow u_1$, we have $(u_1, t_1) \in H$. However, $u_1 \rightarrow u_4$ and u_4 satisfies p , but no successors of t_1 satisfy p , so H cannot exist.
- (c) Yes. $H = \{(t_0, u_0), (t_1, u_1), (t_2, u_3)\}$.
- (d) Yes. $H = \{(s_0, u_0), (s_1, u_1), (s_2, u_3), (s_3, u_3), (s_4, u_0)\}$. Alternatively, we can also prove that \mathcal{K}_1 and \mathcal{K}_2 are bisimilar and use the result from (c).

Exercise 11.2

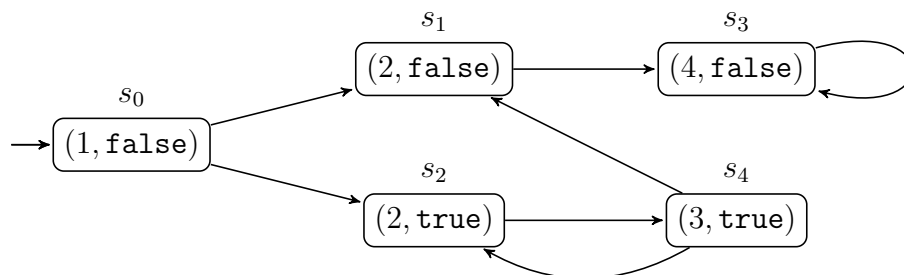
Let H_{13} be a bisimulation between \mathcal{K}_1 and \mathcal{K}_2 and H_{23} be a bisimulation between \mathcal{K}_2 and \mathcal{K}_3 . We define $H_{13} = \{(s, u) \mid \exists t : (s, t) \in H_{12} \wedge (t, u) \in H_{23}\}$ and show that H_{13} is a bisimulation between \mathcal{K}_1 and \mathcal{K}_3 .

First, we prove that H_{13} is a simulation from \mathcal{K}_1 to \mathcal{K}_3 . Basically, we need to prove that if $(s, u) \in H_{13}$ and $s \rightarrow_1 s'$, then there exists u' such that $u \rightarrow_3 u'$ and $(s', u') \in H_{13}$. From the definition of $(s, u) \in H_{13}$, we know that there exists t such that $(s, t) \in H_{12}$ and $(t, u) \in H_{23}$. Since $(s, t) \in H_{12}$ and $s \rightarrow_1 s'$, there must exist t' such that $t \rightarrow_2 t'$ and $(s', t') \in H_{12}$. Similarly, since $(t, u) \in H_{23}$ and $t \rightarrow_2 t'$, there must exist u' such that $u \rightarrow_3 u'$ and $(t', u') \in H_{23}$. Because $(s', t') \in H_{12}$ and $(t', u') \in H_{23}$, by the definition of H_{13} we have $(s', u') \in H_{13}$.

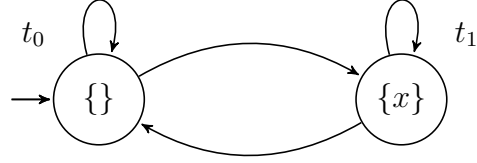
Analogously, we can prove that $\{(u, s) \mid (s, u) \in H_{13}\}$ is a simulation from \mathcal{K}_3 to \mathcal{K}_1 .

Exercise 11.3

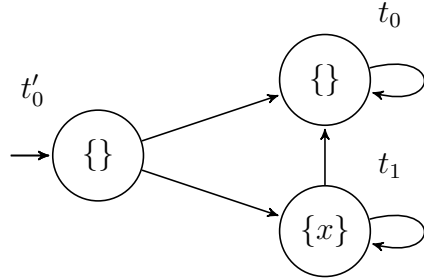
- (a) Each state of the following Kripke structure \mathcal{K} is a pair of a program location and a valuation of \mathbf{x} .



(b) Let $t_0 = [s_0] = \{s_0, s_1, s_3\}$ and $t_1 = [s_1] = \{s_2, s_4\}$. The abstraction \mathcal{K}' is as follows:



- (c) (i) $\mathcal{K}' \models \neg x \mathbf{W} x$
(ii) $\mathcal{K}' \not\models \mathbf{G}(\neg x \rightarrow \mathbf{X} \neg x)$. A counterexample in \mathcal{K}' is $t_0 t_1$, which corresponds to the run $s_0 s_2$ in \mathcal{K} . So, $\mathcal{K} \not\models \mathbf{G}(\neg x \rightarrow \mathbf{X} \neg x)$.
(iii) $\mathcal{K}' \not\models \mathbf{X}(\neg x \rightarrow \mathbf{G} \neg x)$. A counterexample in \mathcal{K}' is $t_0 t_0 t_1^\omega$. However, there are no corresponding runs in \mathcal{K} because such paths must start with $s_0 s_1$, but no successors of s_1 are in t_1 . Since $s_0 \in t_0$ and s_0 has a successor in t_1 , we can refine the abstraction to distinguish s_0 from s_1 . $t'_0 = \{s_0\}$ and $t_0 = \{s_1, s_3\}$, and construct a new Kripke structure \mathcal{K}'' as follows.



We have $\mathcal{K}'' \models \mathbf{X}(\neg x \rightarrow \mathbf{G} \neg x)$.