

Fundamental Algorithms

Solutions to Example Problems

1. Growth of functions

- (a) False. Intuitively, the notation $\mathcal{O}(n^2)$ tells us that B runs “at most as fast as” n^2 time (modulo constant factors) on all inputs. This, however, does not prevent the existence of *some* (if not all) inputs, on which B runs faster than $\mathcal{O}(n)$. For instance, if the run-time (with input n) of A is determined by $f(n) = 3n$ and for B by $g(n) = n^2$, then $f \in \mathcal{O}(n)$ and $g \in \mathcal{O}(n^2)$ but $f(n) > g(n)$ for $n \leq 2$.

$$(b) f(n) = \begin{cases} 0 & \text{if } n \leq 0; \\ 2n + (n-1) + \sum_{i=1}^{n-1} i = \frac{n^2 + 5n - 2}{2} & \text{otherwise.} \end{cases}$$

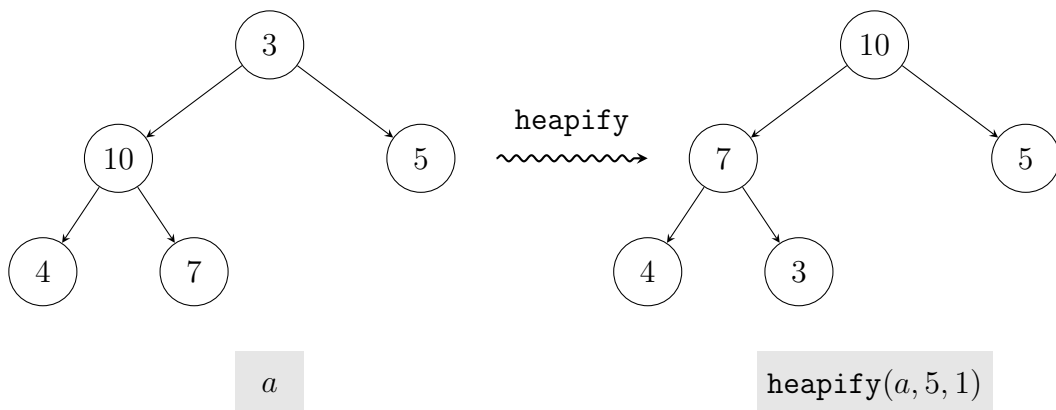
- (c) i. True. Choose $c = 3$ and $n_0 = 10$. Then for all $n \geq n_0$: $3n \leq 3n \log n$
 ii. False. We need to prove that $\forall c > 0 \forall n_0 \exists n \geq n_0 : \frac{3}{2}n < c(n^{3/2} - n)$. Consider the inequality:

$$\begin{aligned} \frac{3}{2}n &< c(n^{3/2} - n) \\ \frac{3}{2} &< c \cdot n(n^{1/2} - 1) \\ n &> \left(\frac{3}{2c} + 1\right)^2. \end{aligned}$$

Therefore, one can choose $n = \max\left(n_0, \left(\frac{3}{2c} + 1\right)^2\right)$ to prove that the statement above always holds.

2. Sorting

- (a) The array a is not a heap, because the number of the root is less than the numbers of its children. The array is a heap after a call to `heapify` with $i = 1$ and $k = 5$.



(b) There are two problems in the algorithm.

- i. The first problem occurs when `largest + 1` is greater than `k`. In that case, `largest + 1` must lie outside the slice `i . . . k`, and therefore the element `a[largest + 1]` in the first if-statement can be undefined. The mistake occurs, for instance, for any even-sized array `a` (say, of size `2n`) and `i = n`, `k = 2n`. The problem can be fixed by adding an extra guard to the if-statement as follows:

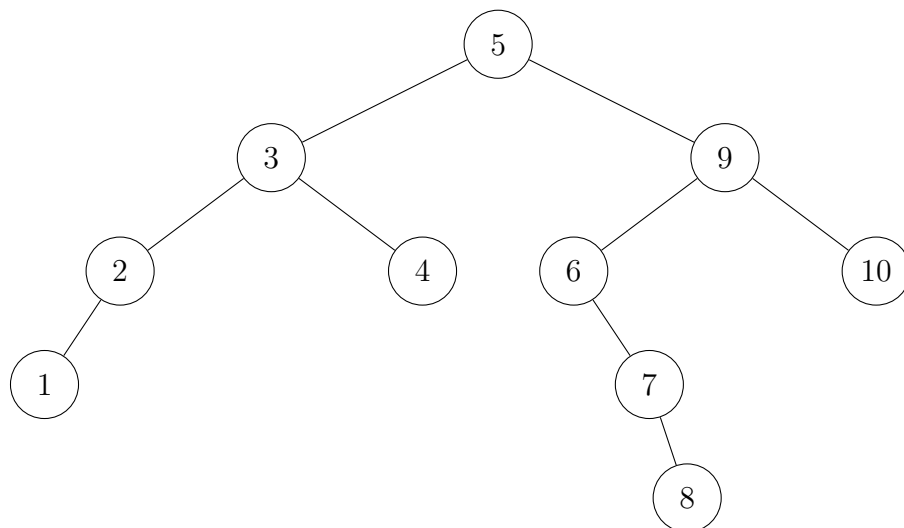
```
if largest + 1 ≤ k and a[largest + 1] > a[largest] then
```

- ii. There is another problem when the comparison in the second if-statement is false, i.e., the array `a` is already a heap. In that case, `i` is incorrectly set to `largest`, and therefore `a[i]` is wrongly set to `tmp` after the loop exits. For instance, if `a` is 8, 10, 5, 4, 7, `i` is 1, and `k` is 5, then the algorithm outputs 10, 10, 5, 4, 8. The bug can be fixed by immediately exiting the loop when the comparison fails, i.e., the second if-statement becomes:

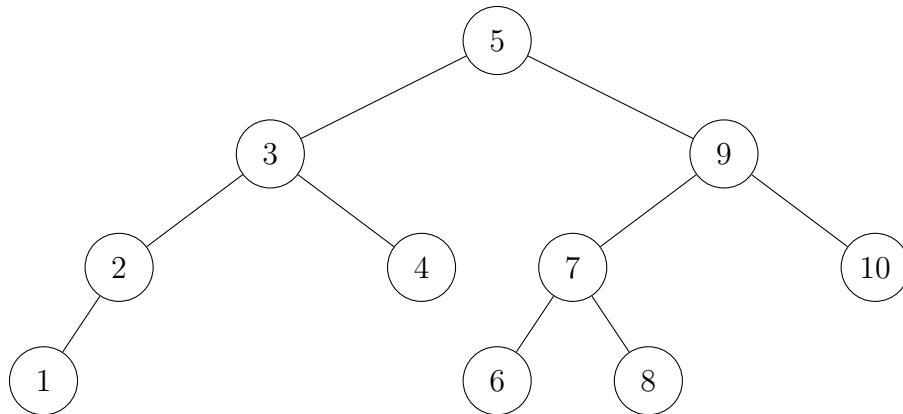
```
if a[largest] > tmp then
    a[i] := a[largest];
else
    break;
fi
```

3. Searching

(a)



- (b) The tree in (a) is not an AVL tree, since the node with value 6 violates the balancing property. This can be fixed by the a single “right-right” rotation, which results in the following tree.



- (c) Let t be a pointer to the ordered binary tree. Call the following procedure `fill(t, a, 1)` to fill the array, where the last two arguments are in-out parameters.

Procedure fill

Input: pointer t to an ordered binary tree, array a , index i

Output: fill the array a , starting from index i , with elements from the tree

if $t = \text{NIL}$ **then return** ;

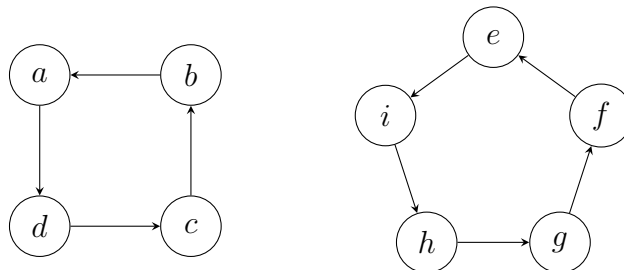
`fill`($t \rightarrow \text{.right}$, a , i);

$a[i] := t \rightarrow \text{.value}$; $i := i + 1$;

`fill`($t \rightarrow \text{.left}$, a , i);

4. Graphs

- (a) Consider the graph shown below. The desired numbering results from starting first at d and then i .



- (b) The proposal is wrong. Consider the following graph G , which (trivially) contains two SCCs. In pre-order numbering if node b is visited first, then b is labeled with 1 and a with 2. Then, when performing another search from the node with the lowest number, i.e. b , in G_R we wrongly conclude that a and b are in an SCC.



- (c) Recall that a heuristic function h is *monotone* if for all two adjacent nodes w and z , where $d(w, z)$ denotes the length of the actual shortest path between them, then

$$h(w) \leq d(w, z) + h(z) .$$

In both graphs, one can readily check that the property holds for each pair of nodes.