Complexity Theory

Jan Křetínský

Technical University of Munich Summer 2019

May 9, 2019

Lecture 8
PSPACE

Agenda

- succinctness
- QBF and GG
- PSPACE completeness
- QBF is **PSPACE**-complete
- Savitch's theorem

Succinctness vs Expressiveness

Some intuition:

- $5 \cdot 5$ is more succinct than 5 + 5 + 5 + 5 + 5
- ⇒ multiplication allows for more succinct representation of arithmetic expressions
 - but it is not more expressive

Succinctness vs Expressiveness

Some intuition:

- $5 \cdot 5$ is more succinct than 5 + 5 + 5 + 5 + 5
- ⇒ multiplication allows for more succinct representation of arithmetic expressions
 - but it is not more expressive

regular expressions

- regular expressions with squaring are more succinct than without
- example: strings over {1} with length divisible by 16
 - ((((00)²)²)²)* versus
 - (00000000000000)*
- but obviously squaring does not add expressiveness

More succinct means more difficult to handle

Non-deterministic finite automata

- NFAs can be exponentially more succinct than DFAs
- but equally expressive
- example: k-last symbol is 1
- complementation, equivalence are polynomial for DFAs and exponential for NFAs

Succinctness

Succinct Boolean formulas

Consider the following formula where $\psi = x \lor y \lor \overline{z}$

$$(x \land y \land \psi) \land (x \land \overline{y} \land \psi) \land (\overline{x} \land y \land \psi) \land (\overline{x} \land \overline{y} \land \psi)$$

Succinctness

Succinct Boolean formulas

Consider the following formula where $\psi = x \lor y \lor \overline{z}$

$$\begin{array}{c} (x \wedge y \wedge \psi) \\ \wedge & (x \wedge \overline{y} \wedge \psi) \\ \wedge & (\overline{x} \wedge y \wedge \psi) \\ \wedge & (\overline{x} \wedge \overline{y} \wedge \psi) \end{array}$$

Formula is satisfiable iff $\exists z \ \forall x \ \forall y.\psi$ is true, where variables range over $\{0, 1\}$.

Succinctness

Succinct Boolean formulas

Consider the following formula where $\psi = x \lor y \lor \overline{z}$

$$(x \land y \land \psi) \land (x \land \overline{y} \land \psi) \land (\overline{x} \land y \land \psi) \land (\overline{x} \land \overline{y} \land \psi)$$

Formula is satisfiable iff $\exists z \ \forall x \ \forall y.\psi$ is true, where variables range over $\{0, 1\}$.

⇒ Quantified Boolean Formulas

Quantified Boolean Formulas

Definition (QBF)

A quantified Boolean formula is a formula of the form

$$Q_1 x_1 Q_2 x_2 \dots Q_n x_n \varphi(x_1, \dots, x_n)$$

- where each $Q_i \in \{\forall, \exists\}$
- each x_i ranges over {0, 1}
- φ is quantifier-free

Quantified Boolean Formulas

Definition (QBF)

A quantified Boolean formula is a formula of the form

$$Q_1 x_1 Q_2 x_2 \dots Q_n x_n \varphi(x_1, \dots, x_n)$$

- where each $Q_i \in \{\forall, \exists\}$
- each x_i ranges over {0, 1}
- φ is quantifier-free
- wlog we can assume prenex form
- formulas are closed, i.e. each QBF is true or false
- QBF = { $\varphi \mid \varphi$ is a true QBF}
- if all $Q_i = \exists$, we obtain SAT as a special case
- if all $Q_i = \forall$, we obtain Tautology as a special case

QBF is in PSPACE

Polynomial space algorithm to decide QBF

 $abfsolve(\psi)$ if ψ is quantifier-free return evaluation of ψ if $\psi = Qx.\psi'$ if $\mathbf{O} = \mathbf{F}$ if $gbfsolve(\psi'[x \mapsto 0])$ return true if $gbfsolve(\psi'[x \mapsto 1])$ return true if $\mathbf{Q} = \mathbf{V}$ $b_1 = \text{qbfsolve}(\psi'[x \mapsto 0])$ $b_2 = \text{qbfsolve}(\psi'[x \mapsto 1])$ return $b_1 \wedge b_2$ return false

QBF is in PSPACE

Polynomial space algorithm to decide QBF

 $abfsolve(\psi)$ if ψ is quantifier-free return evaluation of ψ if $\psi = Qx.\psi'$ if $\mathbf{Q} = \mathbf{F}$ if $gbfsolve(\psi'[x \mapsto 0])$ return true if $gbfsolve(\psi'[x \mapsto 1])$ return true if $\mathbf{O} = \mathbf{V}$ $b_1 = \text{qbfsolve}(\psi'[x \mapsto 0])$ $b_2 = \text{gbfsolve}(\psi'[x \mapsto 1])$ return $b_1 \wedge b_2$ return false

- each recursive call can re-use same space!
- **qbsolve** uses at most $O(|\psi|^2)$ space

Generalized Geography

- children's game, where people take turn naming cities
- next city must start with previous city's final letter
- as in München → Nürnberg
- no repetitions
- lost if no more choices left

Generalized Geography

- children's game, where people take turn naming cities
- next city must start with previous city's final letter
- as in München → Nürnberg
- no repetitions
- lost if no more choices left

Formalization

Given a graph and a node, players take turns choosing an unvisited adjacent node until no longer possible.

 $GG = \{\langle G, u \rangle \mid \text{ player 1 has winning strategy from node } u \text{ in } G\}$

GG ∈ **PSPACE**

and here is the algorithm to prove it:

```
ggsolve(G, u)

if u has no outgoing edge return false

remove u and its adjacent edges from G to obtain G'

for each u_i adjacent to u

b_i = ggsolve(G', u_i)

return \bigvee_i \overline{b_i}
```

GG ∈ **PSPACE**

and here is the algorithm to prove it:

```
ggsolve(G, u)

if u has no outgoing edge return false

remove u and its adjacent edges from G to obtain G'

for each u_i adjacent to u

b_i = \text{ggsolve}(G', u_i)

return \bigvee_i \overline{b_i}
```

- stack depth 1 for recursion implies polynomial space
- QBF ≤_p GG

Agenda

- succinctness √
- QBF and GG \checkmark
- PSPACE completeness
- QBF is **PSPACE**-complete
- Savitch's theorem

PSPACE-completness

Definition (PSPACE-completeness)

Language *L* is **PSPACE-hard** if for every $L' \in \text{PSPACE } L' \leq_p L$. *L* is **PSPACE-complete** if $L \in \text{PSPACE}$ and *L* is **PSPACE-hard**.

QBF is PSPACE-complete

Theorem QBF is PSPACE-complete.

QBF is PSPACE-complete



- have already shown that QBF ∈ PSPACE
- need to show that every problem *L* ∈ PSPACE is polynomial-time reducible to QBF

• let *L* ∈ **PSPACE** arbitrary

- let *L* ∈ **PSPACE** arbitrary
- $L \in \text{SPACE}(s(n))$ for polynomial s

- let *L* ∈ **PSPACE** arbitrary
- $L \in \text{SPACE}(s(n))$ for polynomial s
- $m \in O(s(n))$: bits needed to encode configuration C

- let *L* ∈ **PSPACE** arbitrary
- $L \in \text{SPACE}(s(n))$ for polynomial s
- $m \in O(s(n))$: bits needed to encode configuration C
- exists Boolean formula $\varphi_{M,x}$ with size O(m) such that $\varphi_{M,x}(C, C') = 1$ iff $C, C' \in \{0, 1\}^m$ encode adjacent configurations; see Cook-Levin

- let *L* ∈ **PSPACE** arbitrary
- $L \in \text{SPACE}(s(n))$ for polynomial s
- $m \in O(s(n))$: bits needed to encode configuration C
- exists Boolean formula $\varphi_{M,x}$ with size O(m) such that $\varphi_{M,x}(C, C') = 1$ iff $C, C' \in \{0, 1\}^m$ encode adjacent configurations; see Cook-Levin
- define QBF ψ such that ψ(C, C') is true iff there is a path in G(M, x) from C to C'

- let $L \in PSPACE$ arbitrary
- $L \in \text{SPACE}(s(n))$ for polynomial s
- $m \in O(s(n))$: bits needed to encode configuration C
- exists Boolean formula $\varphi_{M,x}$ with size O(m) such that $\varphi_{M,x}(C, C') = 1$ iff $C, C' \in \{0, 1\}^m$ encode adjacent configurations; see Cook-Levin
- define QBF ψ such that ψ(C, C') is true iff there is a path in G(M, x) from C to C'
- $\psi(C_{start}, C_{accept})$ is true iff *M* accepts *x*

Define ψ inductively!

• $\psi_i(C, C')$: there is a path of length at most 2^i from C to C'

- $\psi_i(C, C')$: there is a path of length at most 2^i from C to C'
- $\psi = \psi_m$ and $\psi_0 = \varphi_{M,x}$

- $\psi_i(C, C')$: there is a path of length at most 2^i from C to C'
- $\psi = \psi_m$ and $\psi_0 = \varphi_{M,x}$

 $\psi_i(\boldsymbol{C},\boldsymbol{C}') = \exists \boldsymbol{C}''.\psi_{i-1}(\boldsymbol{C},\boldsymbol{C}'') \land \psi_{i-1}(\boldsymbol{C}'',\boldsymbol{C}')$

- $\psi_i(C, C')$: there is a path of length at most 2^i from C to C'
- $\psi = \psi_m$ and $\psi_0 = \varphi_{M,x}$

 $\psi_i(\boldsymbol{C},\boldsymbol{C}') = \exists \boldsymbol{C}''.\psi_{i-1}(\boldsymbol{C},\boldsymbol{C}'') \land \psi_{i-1}(\boldsymbol{C}'',\boldsymbol{C}')$

might be exponential size,

Define ψ inductively!

- $\psi_i(C, C')$: there is a path of length at most 2^i from C to C'
- $\psi = \psi_m$ and $\psi_0 = \varphi_{M,x}$

$$\psi_i(\boldsymbol{C},\boldsymbol{C}') = \exists \boldsymbol{C}''.\psi_{i-1}(\boldsymbol{C},\boldsymbol{C}'') \land \psi_{i-1}(\boldsymbol{C}'',\boldsymbol{C}')$$

might be exponential size, therefore use equivalent

$$\psi_i(C, C') = \exists C'' \cdot \forall D_1 \cdot \forall D_2. \\ ((D_1 = C \land D_2 = C'') \lor (D_1 = C'' \land D_2 = C')) \\ \Rightarrow \psi_{i-1}(D_1, D_2)$$

Size of ψ

$$\psi_i(C,C') = \exists C''.\forall D_1.\forall D_2. \\ ((D_1 = C \land D_2 = C'') \lor (D_1 = C'' \land D_2 = C')) \\ \Rightarrow \psi_{i-1}(D_1,D_2)$$

- C'' stands for m variables
- $\Rightarrow |\psi_i| = |\psi_{i-1}| + O(m)$
- $\Rightarrow |\psi| \in O(m^2)$

Observations and consequences

- GG is PSPACE-complete
- if PSPACE ≠ NP then QBF and GG have no short certificates
- note: proof does not make use of outdegree of G(M, x)
- ⇒ QBF is NPSPACE-complete
- \Rightarrow NPSPACE = PSPACE!
 - in fact, the same reasoning can be used to prove a stronger result

Savitch's Theorem

Theorem (Savitch)

For every space-constructible $s : \mathbb{N} \to \mathbb{N}$ with $s(n) \ge \log n$ NSPACE $(s(n)) \subseteq$ SPACE $(s(n)^2)$.

Let *M* be a NDTM accepting *L*. Let G(M, x) be its configuration graph of size $m \in O(2^{s(n)})$; each node is represented using log *m* space.

Let *M* be a NDTM accepting *L*. Let G(M, x) be its configuration graph of size $m \in O(2^{s(n)})$;

each node is represented using $\log m$ space.

M accepts *x* iff there is a path of length at most *m* from C_{start} to C_{accept} .

Let *M* be a NDTM accepting *L*. Let G(M, x) be its configuration graph of size $m \in O(2^{s(n)})$;

each node is represented using $\log m$ space.

M accepts *x* iff there is a path of length at most *m* from C_{start} to C_{accept} .

Consider the following algorithm reach(u,v,i) to determine whether there is a path from u to v of length at most 2^{i} .

- for each node z of M
 - b₁ = reach(u, z, i − 1)
 - b₂ = reach(z, v, i − 1)
 - return $b_1 \wedge b_2$

Let *M* be a NDTM accepting *L*. Let G(M, x) be its configuration graph of size $m \in O(2^{s(n)})$;

each node is represented using $\log m$ space.

M accepts *x* iff there is a path of length at most *m* from C_{start} to C_{accept} .

Consider the following algorithm reach(u,v,i) to determine whether there is a path from u to v of length at most 2^{i} .

- for each node z of M
 - b₁ = reach(u, z, i − 1)
 - b₂ = reach(z, v, i − 1)
 - return $b_1 \wedge b_2$

 \Rightarrow reach(C_{start}, C_{accept}, m) takes space $O((\log m)^2) = O(s(n)^2)$

Conclusion

Further Reading

- L. J. Stockmeyer and A. R. Meyer. Word problems requiring exponential time. STOC, pages 1-9, 1973
 - contains the original proof of PSPACE completeness of QBF
 - PSPACE-completeness of NFA equivalence
- regular expression equivalence with squaring is **EXPSPACE**-complete:

http://people.csail.mit.edu/meyer/rsq.pdf

- *Gilbert, Lengauer, Tarjan* The Pebbling Problem is Complete in Polynomial Space. SIAM Journal on Computing, Volume 9, Issue 3, 1980, pages 513-524.
- http://www.qbflib.org/
 - tools (solvers)
 - many QBF models from verification, games, planning
 - competitions
- PSPACE-completeness of Hex, Atomix, Gobang, Chess
- *W.J.Savitch* Relationship between nondeterministic and deterministic tape classes JCSS, 4, pp 177-192, 1970.

Conclusion

What have we learnt

- succinctness leads to more difficult problems
- **PSPACE**: computable in polynomial space (deterministically)
- PSPACE-completeness defined in terms of polynomial Karp reductions
- canonical **PSPACE**-complete problem: QBF generalizes SAT
- other complete problems: generalized geography, chess, Hex, Sokoban, Reversi, NFA equivalence, regular expressions equivalence
- PSPACE ~ winning strategies in games rather than short certificates
- PSPACE = NPSPACE
- Savitch: non-deterministic space can be simulated by deterministic space with quadratic overhead (by path enumeration in configuration graph)

Up next: NL