

# Complexity Theory

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## Lecture 10–Part II

**PH & co.**

# Agenda

- oracles
- oracles and **PH**
- relativization and **P** vs. **NP**
- alternation and **PH**

# Minimizing Boolean formulas

Let DNF be disjunctive normal form and  $\equiv$  denote logic equivalence.

$$\text{MinEqDNF} = \{\langle \varphi, k \rangle \mid \text{there is a DNF formula } \psi \\ \text{of size at most } k \text{ s.t. } \varphi \equiv \psi\}$$

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What if we can check equivalence of formulae for free?

# Oracle

## Definition

An **oracle** is a language  $A$ .

An **oracle Turing machine**  $M^A$  is a Turing machine that

1. has an extra *oracle* tape, and
2. can ask whether the string currently written on the oracle tape belongs to  $A$  and in a *single* computation step gets the answer.

$P^A$  is a class of languages decidable by a polynomial-time oracle Turing machine with an oracle  $A$ ; similarly  $NP^A$  etc.



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- We often write classes instead of the complete languages, e.g.,  
 $\text{pNP} = \text{P}^{\text{SAT}} = \text{pcoNP}$

# Oracles and PH

Recall that

$$\Sigma_1^P \text{SAT} = \{ \exists \vec{u}_1 \forall \vec{u}_2 \cdots Q \vec{u}_i. \varphi(\vec{u}_1, \dots, \vec{u}_i) \mid \text{formula is true} \}$$

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## Theorem

For every  $i$ ,  $\Sigma_i^P = \text{NP}^{\Sigma_{i-1} \text{SAT}} = \text{NP}^{\Sigma_{i-1}^P}$ .

e.g.  $\Sigma_3^P = \text{NP}^{\text{NP}^{\text{NP}}}$

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Proof

$\subseteq$ : easy

$\supseteq$  (here for  $i=2$ , i.e.  $\Sigma_2^P \supseteq \text{NP}^{\text{SAT}}$ ): Let  $\varphi_i$  denote the  $i$ th query  
 $x \in L \iff \exists c_1, \dots, c_m, a_1, \dots, a_k, u_1, \dots, u_k \forall v_1, \dots, v_k$  such that  
 TM accepts  $x$  using choices  $c_1, \dots, c_m$  and answers  $a_1, \dots, a_k$  AND  
 $\forall i \in [k]$  if  $a_i = 1$  then  $\varphi_i(u_i) = 1$  AND  
 $\forall i \in [k]$  if  $a_i = 0$  then  $\varphi_i(v_i) = 0$

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- But there exist oracles  $X$  and  $Y$ :
  - $P^X \neq NP^X$  (See Sipser p.378)
  - $P^Y = NP^Y$  (Proof:  $NP^{QBF} \subseteq NPSPACE \subseteq PSPACE \subseteq P^{QBF}$ )

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  - $P^Y = NP^Y$  (Proof:  $NP^{QBF} \subseteq NPSpace \subseteq PSpace \subseteq P^{QBF}$ )
- Diagonalization has its limits!  
It is not sufficient to **simulate** computation, we must **analyze** them  $\rightarrow$  e.g. circuit complexity.

# Agenda

- oracles ✓
- oracles and **PH** ✓
- relativization and **P** vs. **NP** ✓
- alternation and **PH**

# Alternation

Recall that

- $\Sigma_2\text{SAT} = \{\exists \vec{u}_1 \forall \vec{u}_2. \varphi(\vec{u}_1, \vec{u}_2) \mid \text{formula is true}\}$  is  $\text{NP}^{\text{coNP}}$ -complete
- $\text{SAT} = \{\exists \vec{u}_1. \varphi(\vec{u}_1) \mid \text{formula is true}\}$  is  $\text{NP}$ -complete
- $\text{VAL} = \{\forall \vec{u}_1. \varphi(\vec{u}_1) \mid \text{formula is true}\}$  is  $\text{coNP}$ -complete
- $\exists$  ~ existential certificate ~ there is an accepting computation
- $\forall$  ~ universal certificate ~ all computations are accepting

# Alternation

## Definition

An **alternating Turing machine** is a Turing machine where

- states are partitioned into **existential** (denoted  $\exists$  or  $\vee$ ) and **universal** (denoted  $\forall$  or  $\wedge$ ),
- configurations are labelled by the type of the current state,
- a configuration in the computation tree is **accepting** iff
  - it is  $\exists$  and **some** of its successors is accepting,
  - it is  $\forall$  and **all** its successors are accepting.

We define **ATIME**, **ASPACE**, **AP**, **APSPACE** etc. accordingly.

## Alternation and PH

Let  $\Sigma_i P$  denote the set of languages decidable by ATM

- running in polynomial time,
- with initial state being existential, and
- such that on every run there are at most  $i$  maximal blocks of existential and of universal configurations.

### Theorem

For all  $i$ ,  $\Sigma_i^P = \Sigma_i P$ .

# Power of alternation

## Theorem

For  $f(n) \geq n$ , we have

$$\text{ATIME}(f(n)) \subseteq \text{SPACE}(f(n)) \subseteq \text{ATIME}(f^2(n)).$$

For  $f(n) \geq \log n$ , we have

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Corollary:

$$\text{L} \subseteq \text{AL} = \text{P} \subseteq \text{AP} = \text{PSPACE} \subseteq \text{APSPACE} = \text{EXP} \subseteq \text{AEXP} \dots$$



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- **ASPACE**( $f(n)$ )  $\supseteq$  **TIME**( $2^{O(f(n))}$ )  
guess and check the tableaux of the computation  
(+ halting state on the left)

## Further Reading

### Alternation

- for a survey on **alternation** see *Chandra, Kozen, Stockmeyer Alternation* in Journal of the ACM 28(1), 1981.
- <http://portal.acm.org/citation.cfm?id=322243>

## What have we learnt?

- the **polynomial hierarchy** can be defined in terms of certificates, recursively by oracles, or by bounded alternation
- **diagonalization/simulation** proof techniques have their limits
- **alternation** seems to add power:  
it moves us to the “next higher” class

Up next: time/space tradeoffs, **TISP**( $f, g$ )