

Computational Complexity – Homework 5

Discussed on 14.05.2019.

Exercise 5.1

- (a) Show that for any $L \in \mathbf{PSPACE}$ there is single-tape TM M (which may also write on its input tape) which decides L also in polynomial space.
- (b) Show that it is \mathbf{PSPACE} -complete to decide if a given word w can be derived by a given context-sensitive grammar G , i.e.,

$$\text{CONSENS} := \{ \langle G, w \rangle \mid \text{if } G \text{ is a context-sensitive grammar and } w \in L(G) \}.$$

Exercise 5.2

Prove that $\mathbf{EXPTIME} = \mathbf{APSPACE}$.

[*Hint:* For the \subseteq direction consider breaking the work tape(s) into exponentially many segments which are then independently simulated in polynomial space. Use alternation to coordinate these simulations.]

Remark: We can also show that $\mathbf{P} = \mathbf{AL}$ (alternating logarithmic space).

Exercise 5.3

We will revisit two-player graph games, but this time we will not bound the number of moves in a play, and even allow the number of moves to be infinite.

A *game graph* is a structure $\langle V, E, V_0, V_1, v \rangle$ where $\langle V, E \rangle$ is a finite directed graph, and V_0, V_1 is a partition of the vertices V . Moreover $v \in V$ is the *initial node*.

Consider a sequence of nodes $(u)_{u \in I}$ where $I \subseteq \mathbb{N}$ is a downward closed index set (which may or may not be infinite) for the sequence. Such a sequence is called a *partial play* if (i) $u_0 = v$, and (ii) $(u_i, u_{i+1}) \in E$ for all $i + 1 \in I$. A partial play is called a *play* if either $I = \mathbb{N}$, or it is a finitely long play u_0, \dots, u_k such that there is no edge $(u_k, u) \in E$ for any $u \in V$.

Two players (player 0 and player 1) between them construct a partial play. The partial play begins with v . If a partial play v_0, \dots, v_i has been constructed, and $v_i \in V_j$, and there exists $u \in V$ such that $(v_i, u) \in E$, then player j *must* choose the next node v_{i+1} in the partial play such that $(v_i, v_{i+1}) \in E$. The partial play is extended no further if no such move exists.

Thus after either finitely many or infinitely many moves the two players will have constructed a partial play that is a play.

We consider three different types of game that are distinguished by their *winning conditions* W . Given a play σ , we write $Occ(\sigma)$ for the set of nodes occurring at least once in σ , and $Inf(\sigma)$ for the set of nodes occurring infinitely often in σ (which will in particular be empty if σ is only finitely long).

- In a *reachability game* $W \subseteq V$ and player 0 wins a play σ if $W \cap Occ(\sigma) \neq \emptyset$.

- In a *Rabin game*, W is a set of pairs of the form (F, I) where $F, I \subseteq V$. Player 0 wins the play σ if there exists $(F, I) \in W$ such that $F \cap \text{Inf}(\sigma) = \emptyset$ and $I \cap \text{Inf}(\sigma) \neq \emptyset$.
- In a *Müller game*, $W = \langle C, \mathcal{C}, \chi \rangle$ where C is a finite set of colours, $\mathcal{C} \subseteq 2^C$, and $\chi : V \rightarrow C$. Player 0 wins a play σ if $\chi(\text{Inf}(\sigma)) \in \mathcal{C}$.

The decision problem associated with a particular type of game is the set containing elements $\langle \mathcal{G}, W \rangle$ where \mathcal{G} is a game graph, W is an appropriate winning condition, and Player 0 can play in such a way that a play winning for Player 0 always results regardless of how Player 1 moves.

- (a) Prove that the decision problem for reachability games is **P**-hard. (Remember that logarithmic space reductions must be used for this). For this take it as given that **AL** = **P**.

[*Remark:* It is possible to see that the version of reachability games defined in the previous problem sheet are equivalent to those defined above. Thus in fact reachability games are **P**-complete.]

- (b) Prove that the decision problem for Rabin games is **NP**-complete.

[*Hint:* For hardness reduce from 3-SAT. Make Player 0 ‘prove’ that they know some satisfying assignment. Allow Player 1 to ‘interrogate’ player 0’s knowledge of such an assignment. Using the winning condition to ensure that for *some* literal player 0 is *eventually* consistent should suffice to allow Player 1 to successfully catch out Player 0 if no satisfying assignment exists.]

- (c) Prove that the decision problem for Müller games is **PSPACE**-complete.

[*Hint:* For hardness reduce from QBF. Observe that Rabin conditions can be (in polynomial time) translated into Müller conditions. Note further that the *complement* of a Rabin condition can also be so translated. You might also find it helpful to work with a slight generalisation of Müller games allowing one to have a Müller game equivalent of adding quantifiers to the front of a propositional formula.]

Exercise 5.4

You have seen that 2SAT is in **NL**. Show that 2SAT is also **NL**-hard.

Exercise 5.5

Show that deciding the inequivalence of context-free grammars over one-letter terminal alphabet is Σ_2^p -hard. You can make use of Σ_2^p -hardness of integer expression inequivalence.

What does it imply for the equivalence problem?

Exercise 5.6

Under the assumption that $3\text{SAT} \leq_p \overline{3\text{SAT}}$ show that **NP** = **PH**.

Exercise 5.7

Apart from the certificate definition and the alternative bounded alternating Turing machine characterization, there is one more standard characterization of the polynomial hierarchy via *oracles*.

For a language L , an oracle machine M^L is a Turing machine which can moreover do the following kind of computation steps. It can write down a word w on a special tape and ask whether $w \in L$ and it immediately receives the correct answer. One can also talk about this machine even when the oracle is not specified, then we write $M^?$.

Example: In Exercise 3.4 (a), you have constructed an example of M^{SAT} where $M^?$ is a polynomial time TM.

- Prove or disprove: for every $M^?$, if $A \subseteq B$ then $\mathcal{L}(M^A) \subseteq \mathcal{L}(M^B)$.

- Prove or disprove: if $A \subseteq B$ then $\mathbf{P}^A \subseteq \mathbf{P}^B$ (as classes).

The polynomial hierarchy can be defined inductively setting $\Sigma_0^p = \Pi_0^p = \mathbf{P}$ and

$$\Sigma_{i+1}^p = \mathbf{NP}^{\Sigma_i^p}$$

$$\Pi_{i+1}^p = \mathbf{co-NP}^{\Sigma_i^p}$$

where A^B is the set of decision problems solvable by a Turing machine in class A with an oracle for some complete problem in class B .

- Show this yields the same hierarchy as the original definition.

One can also define $\Delta_{i+1}^p = \mathbf{P}^{\Sigma_i^p}$ and show that $\Delta_{i+1}^p \subseteq \Sigma_{i+1}^p \cap \Pi_{i+1}^p$ and it contains all languages expressible as Boolean combinations (unions, intersections, complements) of languages of Σ_i^p and Π_i^p .

- What is the relationship of these classes to $\mathbf{DP} = \{L \mid \exists M, N \in \mathbf{NP} : L = M \setminus N\}$?