## Computational Complexity - Homework 4

Discussed on 9 May 2016.

## Exercise 4.1

Let us denote $\mathbf{D P}=\{L \mid \exists M, N \in \mathbf{N P}: L=M \backslash N\}$ the class of languages that are diferences of two NP languages.
(a) Show that $C=\left\{\left\langle G_{1}, k_{1}, G_{2}, k_{2}\right\rangle \mid G_{1}\right.$ has a $k_{1}$-clique and $G_{2}$ does not have any $k_{2}$-clique $\}$ is DPcomplete.
(b) Show that $M A X-C L I Q U E=\{\langle G, k\rangle \mid$ the largest clique of $G$ is of size exactly $k\}$ is DP-complete.
(c) It is unknown whether $M A X-C L I Q U E$ is in NP. Show that if $\mathbf{P}=\mathbf{N P}$ then $M A X-C L I Q U E$ is in NP and a largest clique can be found in polynomial time.

## Exercise 4.2

(a) Assume that $\mathbf{P}=\mathbf{N P}$. Show that then $\mathbf{E X P}=\mathbf{N E X P}$.

Remark: Assume that $L$ is decided by some TM running in time $T(n)$ with $T(n)$ time-constructible and $T(n) \in \mathcal{O}\left(2^{n^{c}}\right)$ for some $c \geq 1$. Show that then

$$
L_{\mathrm{pad}}:=\left\{x 10^{T(|x|)} 1 \mid x \in L\right\} \in \mathbf{N P} .
$$

*(b) Show that also $\mathbf{E X P}=\mathbf{N E X P}$ if only every unary $\mathbf{N P}$-language is also in $\mathbf{P}$.
Remark: For $x \in\{0,1\}^{*}$ let $\langle x\rangle$ be the natural number represented by $x$ assuming lsbf. Given a language $L$ which is decided in time $T(n)$ (with $T(n)$ time-constructable) show that

$$
L_{\mathrm{upad}}=\left\{1^{\left\langle x 10^{|T(n)|} 1\right\rangle} \mid x \in L\right\} \in \mathbf{N} \mathbf{P}
$$

with $|T(n)|(\approx\lceil\log T(n)\rceil)$ the length of the lsbf representation of $T(n)$.

## Exercise 4.3

Say that $A$ is linear-time reducible to $B$ if there is function $f$ computable in time $\mathcal{O}(n)$ such that $x \in A \Leftrightarrow$ $f(x) \in B$.

- Show that there is no P-complete problem w.r.t. linear-time reductions.

Hint: Use the time hierarchy theorem for DTIME.

## Exercise 4.4

A two-person game consists of a directed graph $G=\left(V_{0}, V_{1}, E\right)$ (called the game graph) whose nodes $V:=V_{0} \cup V_{1}$ are partitioned into two sets and a winning condition. We assume that every node $v \in V$ has a successor. The two players are called for simplicity player 0 and player 1. A play of the two is any finite or infinite path $v_{1} v_{2} \ldots$ in $G$ where $v_{1}$ is the starting node. If the play is currently in node $v_{i}$ and $v_{i} \in V_{0}$, then we assume that it is the turn of player 0 to choose $v_{i+1}$ from the successors of $v_{i}$; if $v_{i} \in V_{1}$, player 1 determines the next move. The winning condition defines when a play is won by player 0 . E.g.:

- In a reachability game the winning condition is simply defined by a subset $T \subseteq V_{0} \cup V_{1}$ (targets) of the nodes of $G$, and a play is won by player 0 if it visits $T$ within $n-1$ moves (where $n$ is the total number of nodes of $G$ ). Hence, player 1 wins a play if he can avoid visiting $T$ for at least $n-1$ moves.
- In a revisiting game player 0 wins a play $v_{1} v_{2} \ldots$ if the first node $v_{i}$ which is visited a second time belongs to player 0 , i.e., $v_{i} \in V_{0}$; otherwise player 1 wins the play.

We say that player $i$ wins node $s$ if he can choose his moves in such a way that he wins any play starting in $s$.

Example: Consider the following game graph where nodes of $V_{0}\left(V_{1}\right)$ are of circular (rectangular) shape:


In the reachability game with $T=\{5\}$ player 0 can win node 4 : if player 1 moves from 4 to 5 , player 0 immediately wins; if player 1 moves from 4 to 2 , then player 0 can win again by moving from 2 to 5 . On the other hand, player 1 can win node 0 by choosing to always play from 0 to 1 and from 3 to 1 .

In the revisiting game played on the same game graph, player 0 can win node 2 : he moves from 2 to 5 and then on to 4 ; no matter how player 1 then chooses to move, the play will end in an already visited node which belongs to player 0 . Player 1 can e.g. win node 3 by simply moving to node 1 .
(a) Consider a reachability game:

Show that one can decide in time polynomial in $\langle G, s, T\rangle$ if player 0 can win node $s$.
Hint: Starting in $T$ compute the set of nodes from which player 0 can always reach $T$ no matter how player 1 chooses his moves.
(b) Consider a revisiting game:

Show that it is PSPACE-complete to decide for a given game graph $G$ and node $s$ if player 0 can win $s$.

## Remarks:

- A game is called determined if every node if won by one of the two players.

Are reachability, resp. revisiting games determined?

- Assume that we change the definition of reachability game by dropping the restriction on the number of moves, i.e., player 0 wins a play if the play eventually reaches a state in $T$.

Does this change the nodes player 0 can win for a given game graph?

## Exercise 4.5

An alternating Turing machine (ATM) $M=\left(\Gamma, Q_{\forall}, Q_{\exists}, \delta_{0}, \delta_{1}\right)$ is an $\operatorname{NDTM}\left(\Gamma, Q_{\forall} \cup Q_{\exists}, \delta_{0}, \delta_{1}\right)$ except that (i) the control states are partitioned into sets $Q_{\forall}$ and $Q_{\exists}$ and (ii) the acceptance condition is defined as
follows:
Consider the configuration graph $G(M, x)$. We extend the partition of the control states to the configurations (nodes) of $G_{M ; x}$ : a configuration is in $V_{0}$ if its control state is in $Q_{\exists}$; otherwise it is in $V_{1}$. We then can consider the reachability game played on $G(M, x)$ by the players 0 and 1 where the target set is the set of accepting configurations. $M$ accepts $x$ iff player 0 wins the initial configuration in this reachability game. (For the sake of completeness, assume that every halting/accepting configuration is its unique successor.)

Example: Consider the following configuration graphs where accepting configurations have a second circle/rectangle drawn around them. In the left graph the corresponding ATM accepts the input while it rejects the input in the right example:


A language is decided by an ATM $M$ if $M$ accepts every $x \in L$ and rejects any $x \notin L$. The time and space required by an ATM is the time and space required by the underlying NDTM.

The class AP consists of all languages $L$ which are decided by an ATM $M$ running in time $T(n) \in \mathcal{O}\left(n^{k}\right)$ for some $k \geq 1$.
(a) An existential (universal) ATM is an ATM with $Q_{\forall}=\emptyset\left(Q_{\exists}=\emptyset\right)$.

Show that any language $L \in \mathbf{A P}$ which is decided by an existential (universal) ATM is in NP (coNP).
(b) Define coAP as usual: $L \in \operatorname{coAP}$ iff $\bar{L} \in \mathbf{A P}$.

Show or disprove that $\mathbf{A P}=\operatorname{coAP}$.
(c) Show that QBF is in AP.
(d) Show that any $L \in \mathbf{A P}$ is in PSPACE.

Remark: Adapt the recursive decision procedure for QBF $\in$ PSPACE you have seen in the lecture.
Remark: Similarly as AP=PSPACE, one can show APSPACE=EXPTIME.

