

Verification

Verification

- We use languages to describe the implementation and the specification of a system.
- We reduce the verification problem to language inclusion between implementation and specification

```

1  while  $x = 1$  do
2    if  $y = 1$  then
3       $x \leftarrow 0$ 
4     $y \leftarrow 1 - x$ 
5  end

```

- **Configuration**: triple $[l, n_x, n_y]$ where
 - l is the current value of the program counter, and
 - n_x, n_y are the current values of x, y

Examples: $[1, 1, 1], [5, 0, 1]$

- **Initial configuration**: configuration with $l = 1$
- **Potential execution**: finite or infinite sequence of configurations

Examples: $[1, 1, 1][4, 1, 0]$
 $[2, 1, 0][5, 1, 0]$
 $[1, 1, 0][2, 1, 0][4, 1, 0][1, 1, 0]$

```
1  while  $x = 1$  do  
2    if  $y = 1$  then  
3       $x \leftarrow 0$   
4     $y \leftarrow 1 - x$   
5  end
```

- **Execution**: potential execution starting at an initial configuration, and where configurations are followed by their „legal successors“ according to the program semantics.

Examples: $[1,1,1][2,1,1][3,1,1][4,0,1][1,0,1][5,0,1]$
 $[1,1,0][2,1,0][4,1,0][1,1,0]$

- **Full execution**: execution that cannot be extended (either infinite or ending at a configuration without successors)

Verification as a language problem

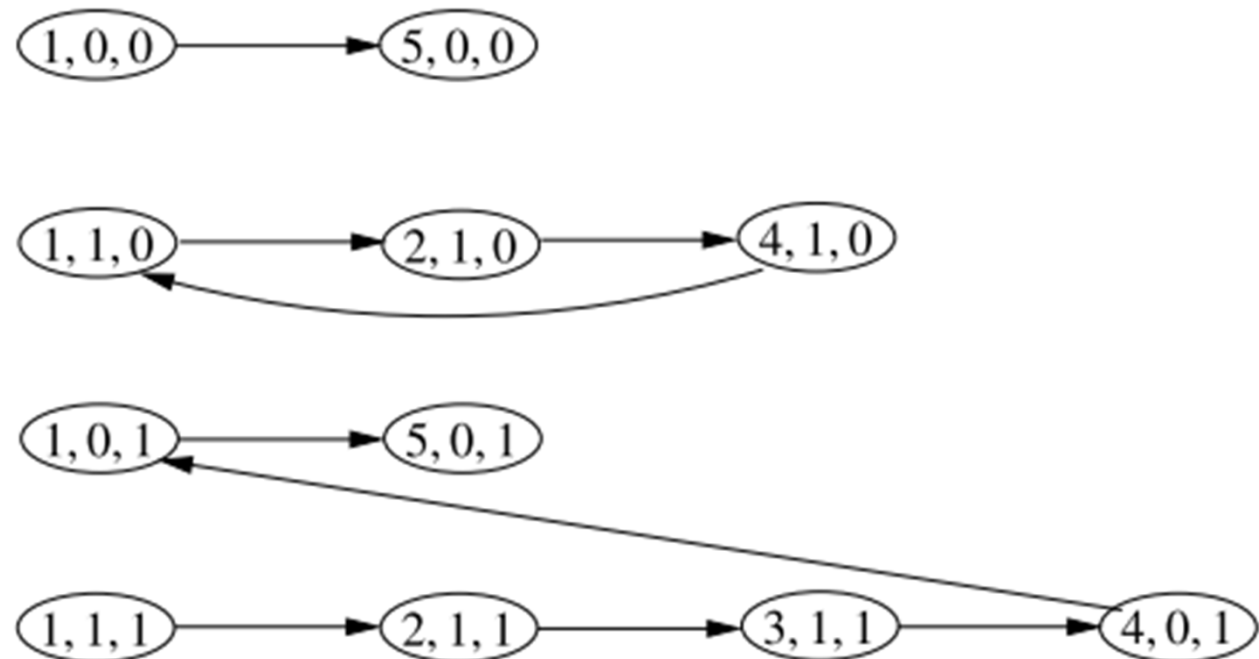
- Implementation: set E of executions
- Specification:
 - subset P of the potential executions that satisfy a property , or
 - subset V of the potential executions that violate a property
- Implementation satisfies specification if :
 - $E \subseteq P$, or
 - $E \cap V = \emptyset$.
- If E and P regular: inclusion checkable with automata
- If E and V regular: disjointness checkable with automata

Verification as a language problem

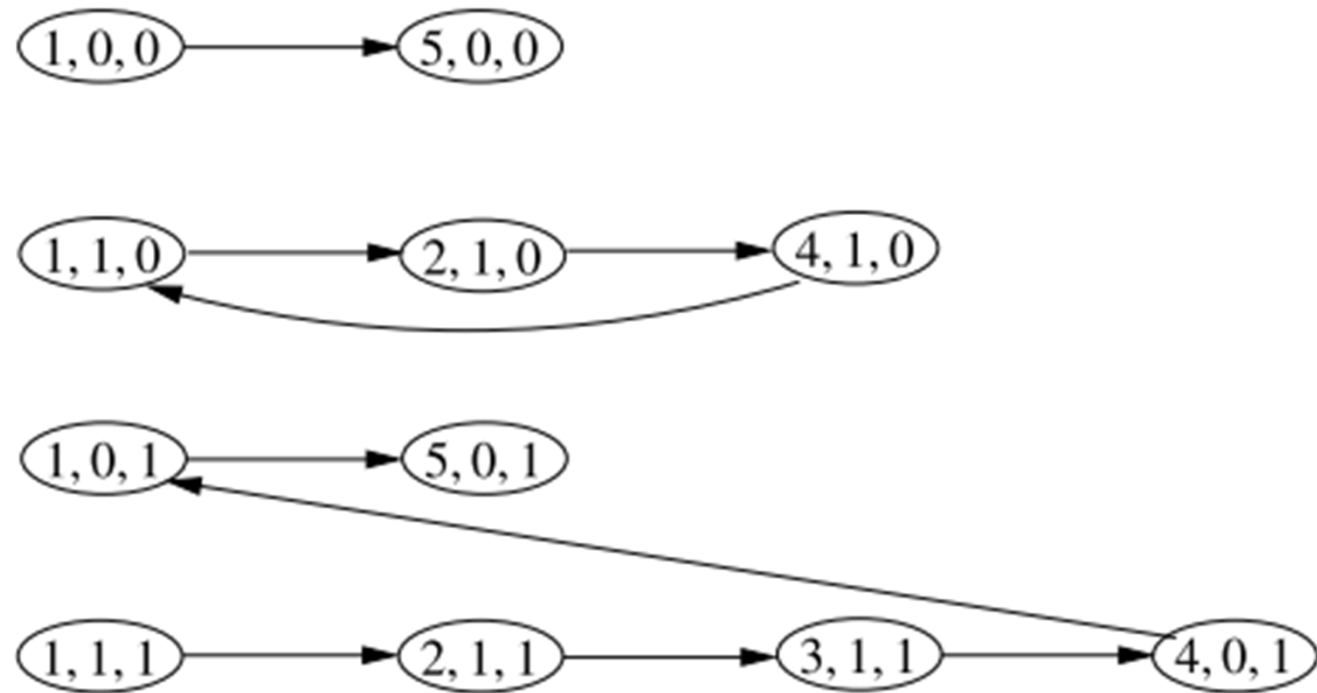
- Implementation: set E of executions
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- Implementation satisfies specification if :
 - $E \subseteq P$, or
 - $E \cap V = \emptyset$.
- If E and P regular: inclusion checkable with automata
- If E and V regular: disjointness checkable with automata
- How often is the case that E, P, V are regular?

System NFA

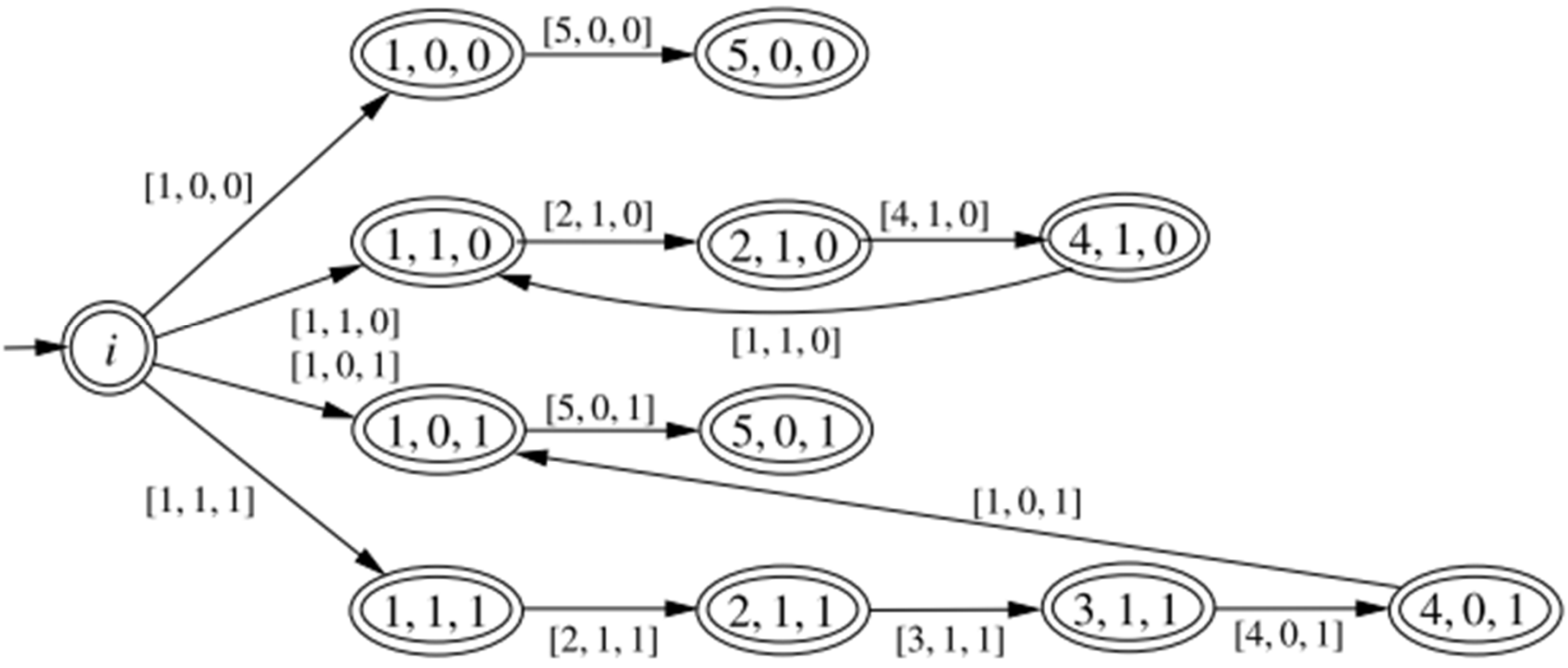
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5  end
```



System NFA

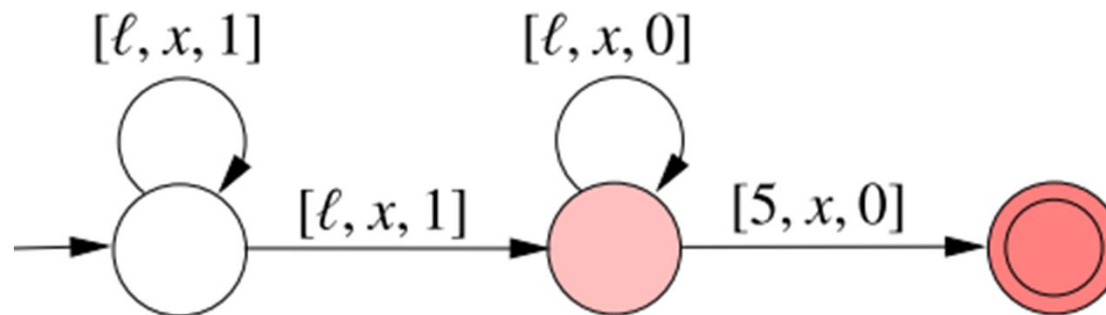


System NFA

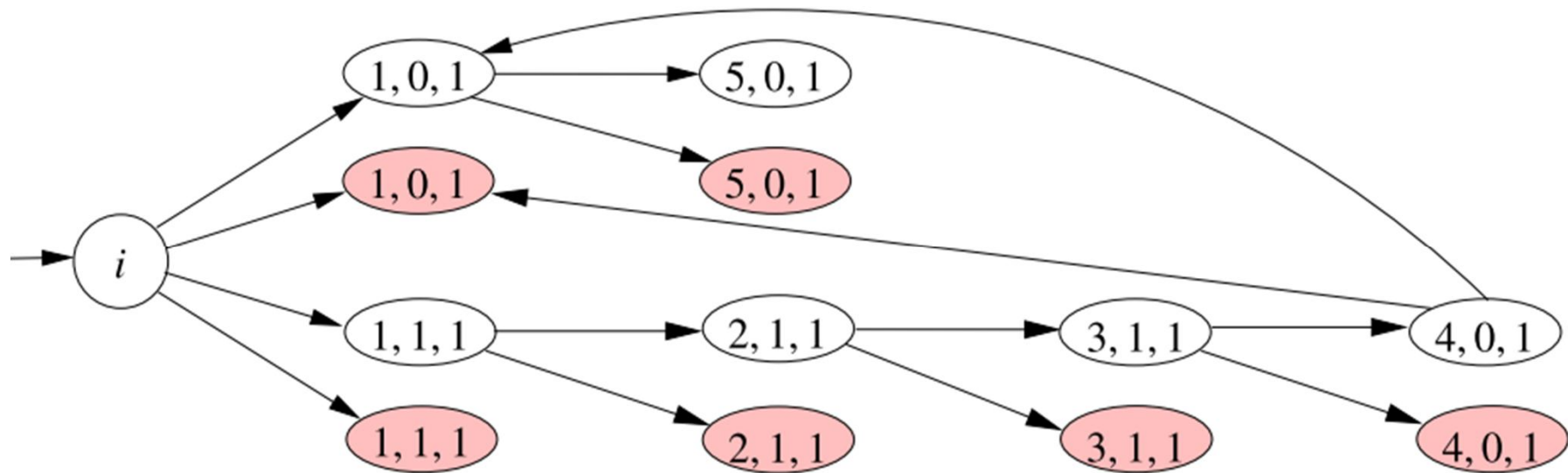


Property NFA

- Is there a full execution such that
 - initially $y = 1$,
 - finally $y = 0$, and
 - y never increases?
- Set of potential executions for this property:
 $[l, x, 1][l, x, 1]^* [l, x, 0]^* [5, x, 0]$
- Automaton for this set:



Intersection of the system and property NFAs

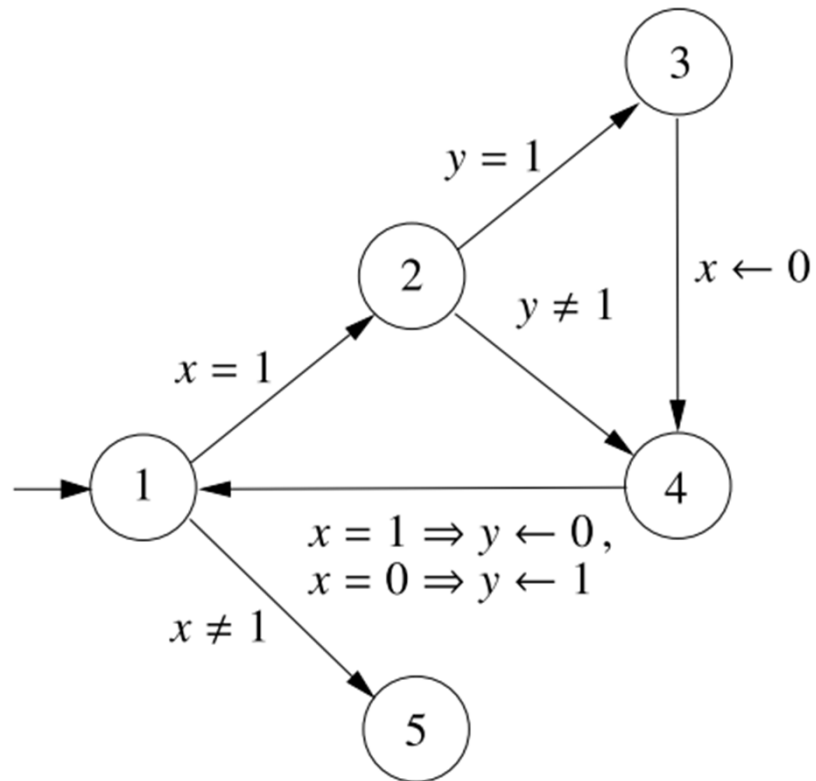


- Automaton is empty, and so no execution satisfies the property

Another property

- Is the assignment $y \leftarrow x - 1$ redundant?
- Potential executions that use the assignment:
 $[l, x, y]^* ([4, x, 0][1, x, 1] + [4, x, 1][1, x, 0]) [l, x, y]^*$
- Therefore: assignment redundant iff none of these potential executions is a real execution of the program.

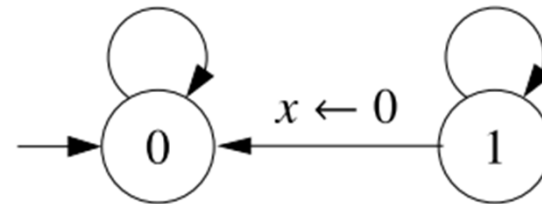
Networks of automata



$$x = 0 \Rightarrow y \leftarrow 1,$$

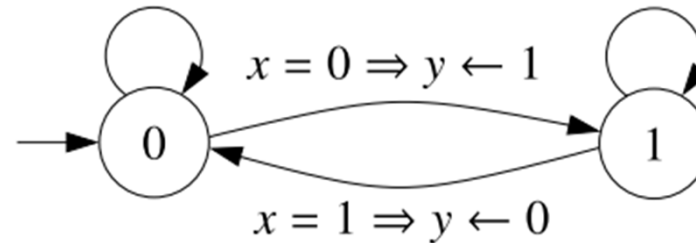
$$x \leftarrow 0, \quad x = 1 \Rightarrow y \leftarrow 0,$$

$$x \neq 1 \quad \quad \quad x = 1$$

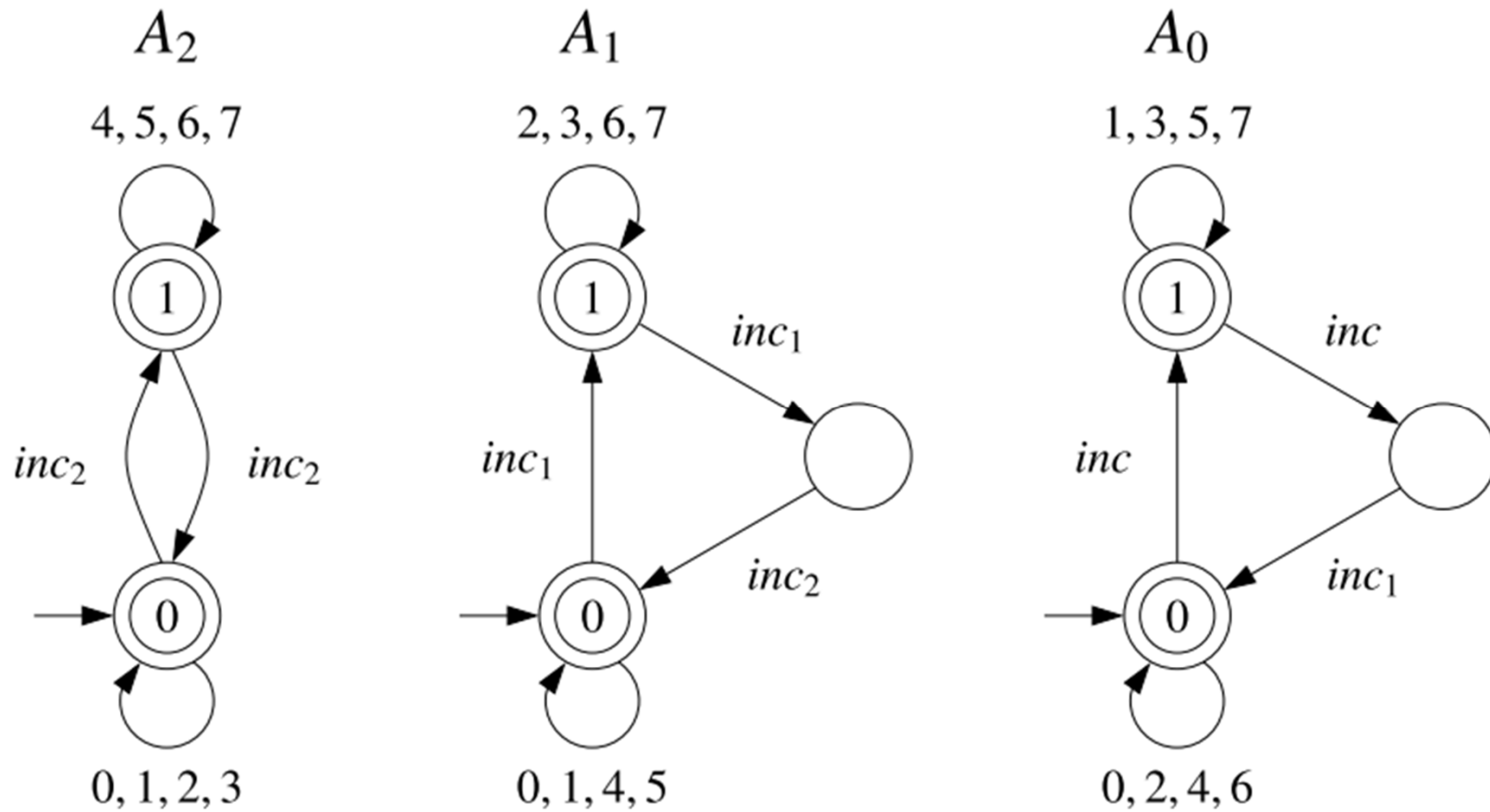


$$x = 1 \Rightarrow y \leftarrow 0, \quad x = 0 \Rightarrow y \leftarrow 1,$$

$$y \neq 1 \quad \quad \quad y = 1$$

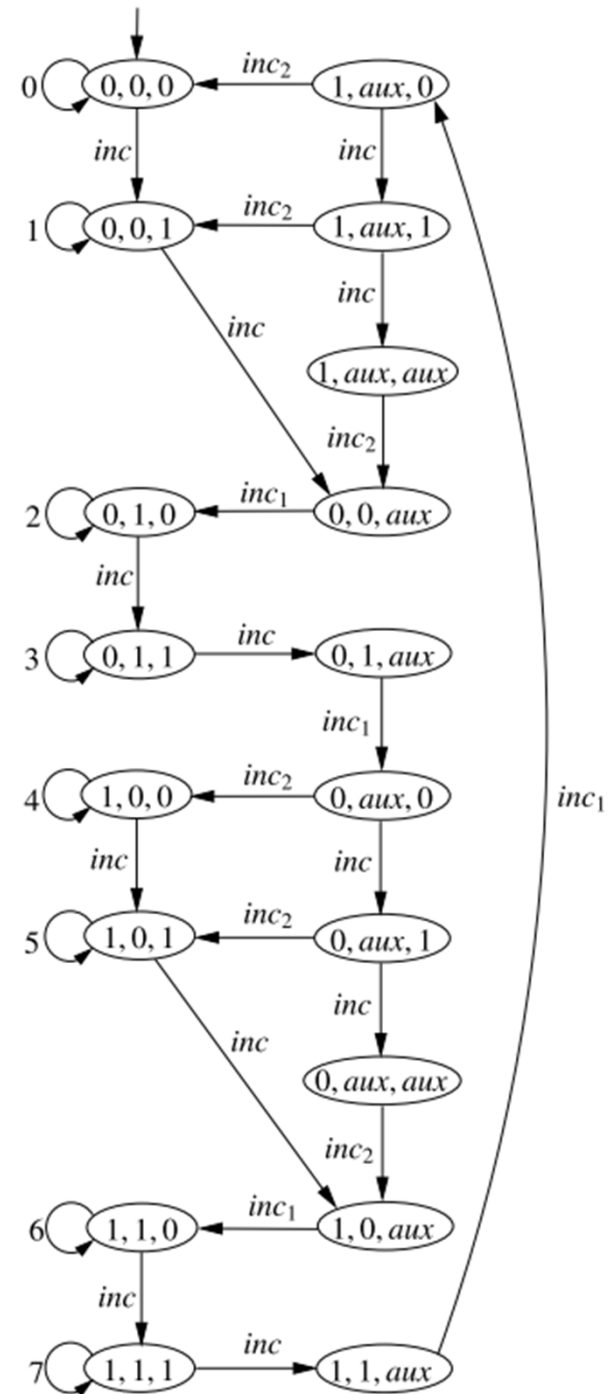


Networks of automata



- Tuple $\mathcal{A} = \langle A_1, \dots, A_n \rangle$ of NFAs .
- Each NFA has its own alphabet Σ_i of actions
- Alphabets usually not disjoint!
- A_i participates in action a if $a \in \Sigma_i$.
- A configuration is a tuple $\langle q_1, \dots, q_n \rangle$ of states, one for each automaton of the network.
- $\langle q_1, \dots, q_n \rangle$ enables a if every participant in a is in a state from which an a -transition is possible.
- Enabled actions can occur, and their occurrence simultaneously changes the states of their participants. Non-participants stay idle and don't change their states.

Configuration graph of the network



Asynchronous product

AsyncProduct(A_1, \dots, A_n)

Input: a network of automata $\mathcal{A} = \langle A_1, \dots, A_n \rangle$, where

$A_i = (Q_i, \Sigma_i, \delta_i, Q_{0i}, F_i)$ for every $i = 1, \dots, n$.

Output: NFA $A_1 \otimes \dots \otimes A_n = (Q, \Sigma, \delta, Q_0, F)$ recognizing $L(\mathcal{A})$.

```
1   $Q, \delta, F \leftarrow \emptyset$ 
2   $Q_0 \leftarrow Q_{01} \times \dots \times Q_{0n}$ 
3   $W \leftarrow Q_0$ 
4  while  $W \neq \emptyset$  do
5    pick  $[q_1, \dots, q_n]$  from  $W$ 
6    add  $[q_1, \dots, q_n]$  to  $Q$ 
7    if  $\bigwedge_{i=1}^n q_i \in F_i$  then add  $[q_1, \dots, q_n]$  to  $F$ 
8    for all  $a \in \Sigma_1 \cup \dots \cup \Sigma_n$  do
9      for all  $i \in [1..n]$  do
10         if  $a \in \Sigma_i$  then  $Q'_i \leftarrow \delta_i(q_i, a)$  else  $Q'_i = \{q_i\}$ 
11         for all  $[q'_1, \dots, q'_n] \in Q'_1 \times \dots \times Q'_n$  do
12           if  $[q'_1, \dots, q'_n] \notin Q$  then add  $[q'_1, \dots, q'_n]$  to  $W$ 
13           add  $([q_1, \dots, q_n], a, [q'_1, \dots, q'_n])$  to  $\delta$ 
14  return  $(Q, \Sigma, \delta, Q_0, F)$ 
```

Concurrent programs as networks of automata: Lamport's 1-bit algorithm (JACM86)

Shared variables: $b[0], \dots, b[n-1] \in \{0, 1\}$, initially 0

Process $i \in \{0, \dots, n-1\}$

repeat forever

noncritical section

T: $b[i]:=1$

for $j \in \{0, \dots, i-1\}$

if $b[j]=1$ **then** $b[i]:=0$

await $\neg b[j]$

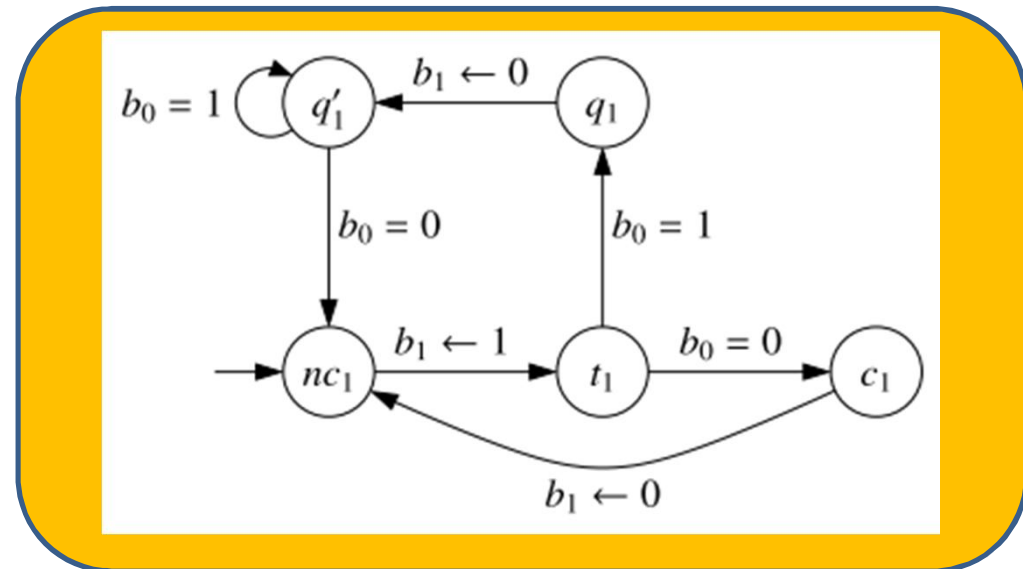
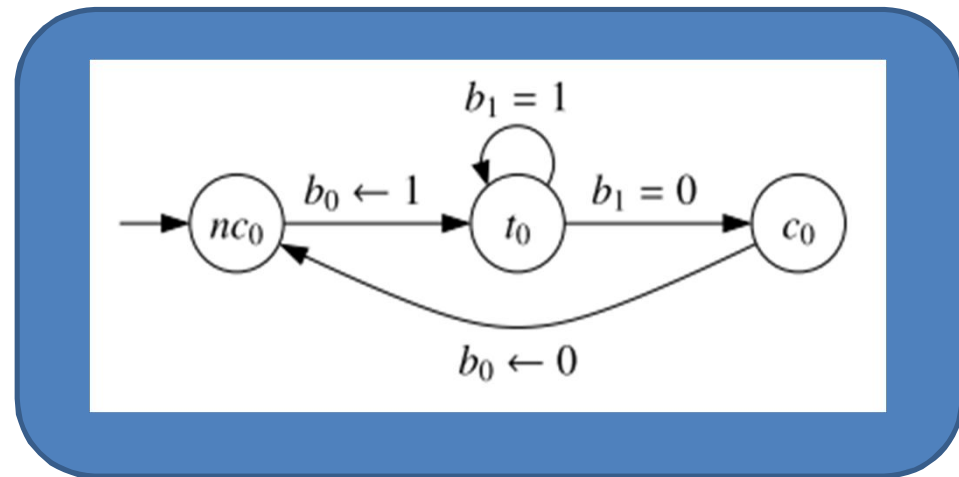
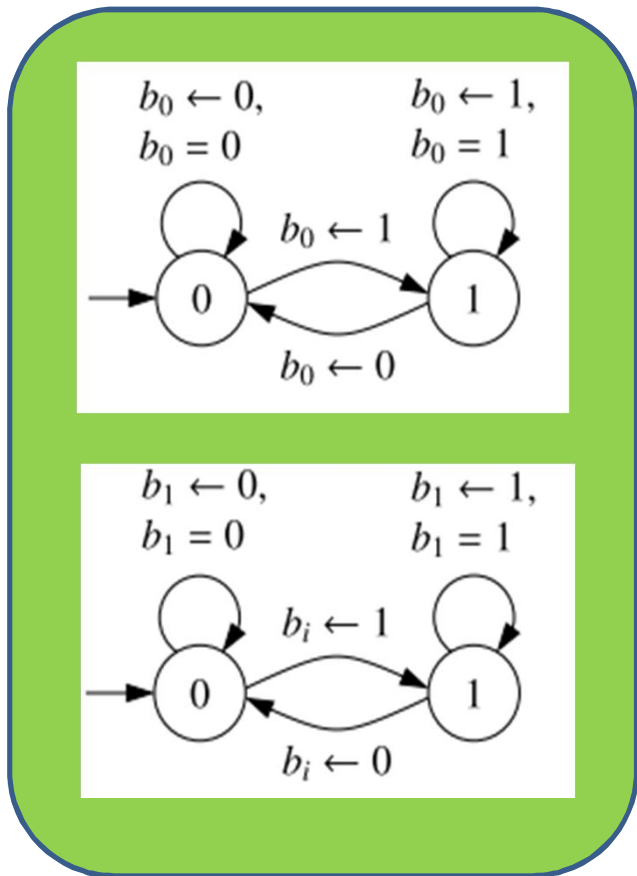
goto T

for $j \in \{i+1, \dots, n-1\}$ **await** $\neg b[j]$

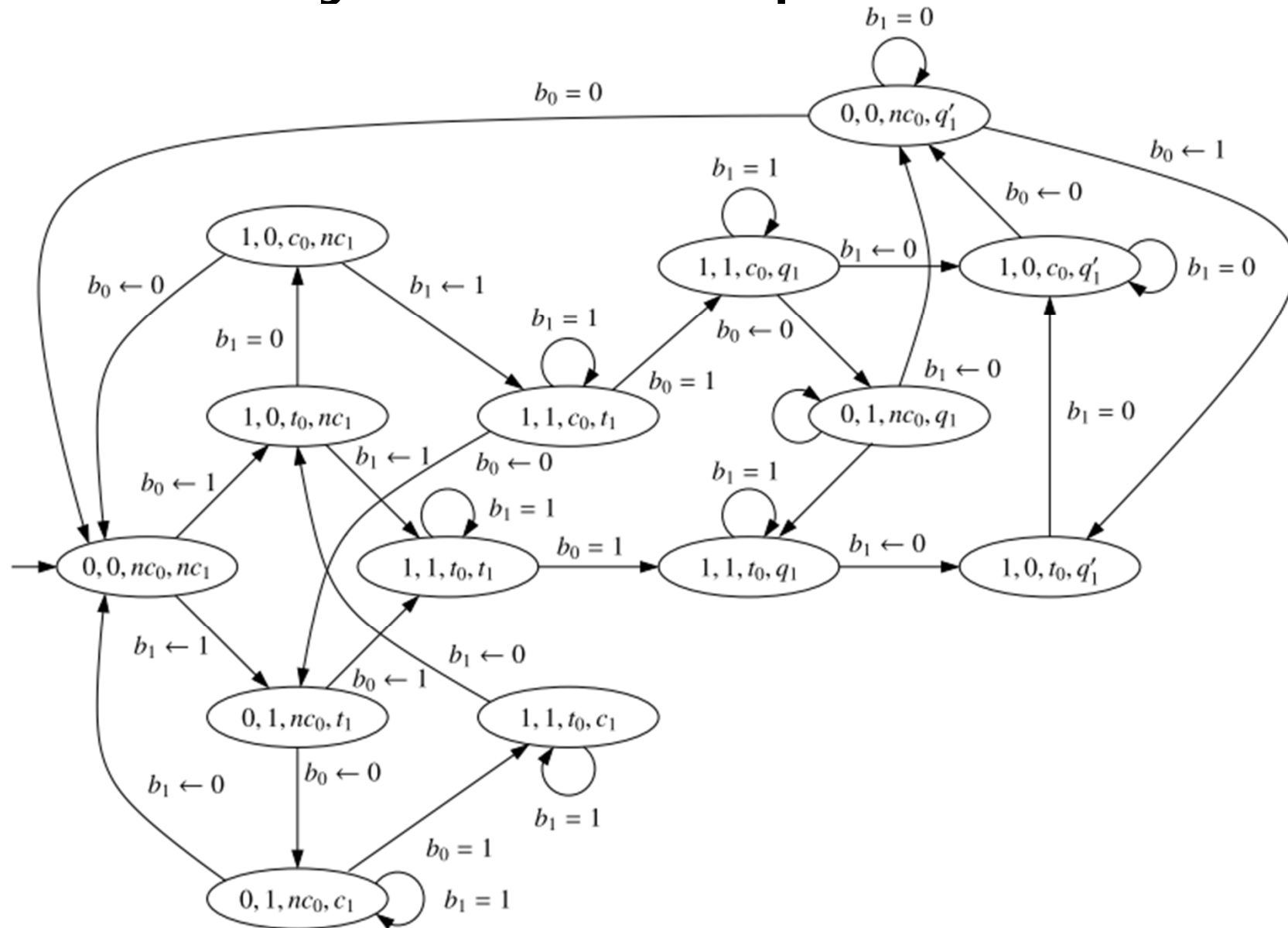
critical section

$b[i]:=0$

Network for the two-process case



Asynchronous product



Checking properties of the algorithm

- **Deadlock freedom:** every configuration has at least one successor.
- **Mutual exclusion:** no configuration of the form $[b_0, b_1, c_0, c_1]$ is reachable
- **Bounded overtaking (for process 0):** after process 0 signals interest in accessing the critical section, process 1 can enter the critical section at most one before process 0 enters.
 - Let NC_i, T_i, C_i be the configurations in which process i is non-critical, trying, or critical
 - Set of potential executions violating the property:

$$\Sigma^* T_0 (\Sigma \setminus C_0)^* C_1 (\Sigma \setminus C_0)^* NC_1 (\Sigma \setminus C_0)^* C_1 \Sigma^*$$

The state-explosion problem

- In sequential programs, the number of reachable configurations grows exponentially in the number of variables.
- **Proposition:** The following problem is **PSPACE-complete**.
 - **Given:** a boolean program π (program with only boolean variables), and a NFA A_V recognizing a set of potential executions
 - **Decide:** Is $E_\pi \cap L(A_V)$ empty?

The state-explosion problem

- In concurrent programs, the number of reachable configurations also grows exponentially in the number of components.
- **Proposition:** The following problem is **PSPACE-complete**.
 - **Given:** a network of automata $\mathcal{A} = \langle A_1, \dots, A_n \rangle$ and a NFA A_V recognizing a set of potential executions of \mathcal{A}
 - **Decide:** Is $L(A_1 \otimes \dots \otimes A_n \otimes A_V) = \emptyset$?

On-the-fly Verification

CheckViol(A_1, \dots, A_n, V)

Input: a network $\mathcal{A} = \langle A_1, \dots, A_n \rangle$, where $A_i = (Q_i, \Sigma_i, \delta_i, Q_{0i}, F_i)$ for $1 \leq i \leq n$;
an NFA $V = (Q_V, \Sigma_V, \delta_V, Q_{0v}, F_v)$.

Output: true if $L(A_1 \otimes \dots \otimes A_n \otimes V)$ is nonempty, false otherwise.

```
1   $Q \leftarrow \emptyset; Q_0 \leftarrow Q_{01} \times \dots \times Q_{0n} \times Q_{0v}$ 
2   $W \leftarrow Q_0$ 
3  while  $W \neq \emptyset$  do
4    pick  $[q_1, \dots, q_n, q]$  from  $W$ 
5    add  $[q_1, \dots, q_n, q]$  to  $Q$ 
6    for all  $a \in \Sigma_1 \cup \dots \cup \Sigma_n$  do
7      for all  $i \in [1..n]$  do
8        if  $a \in \Sigma_i$  then  $Q'_i \leftarrow \delta_i(q_i, a)$  else  $Q'_i = \{q_i\}$ 
9         $Q' \leftarrow \delta_V(q, a)$ 
10     for all  $[q'_1, \dots, q'_n, q'] \in Q'_1 \times \dots \times Q'_n \times Q'$  do
11       if  $\bigwedge_{i=1}^n q'_i \in F_i$  and  $q' \in F_v$  then return true
12       if  $[q'_1, \dots, q'_n, q'] \notin Q$  then add  $[q'_1, \dots, q'_n, q']$  to  $W$ 
13 return false
```

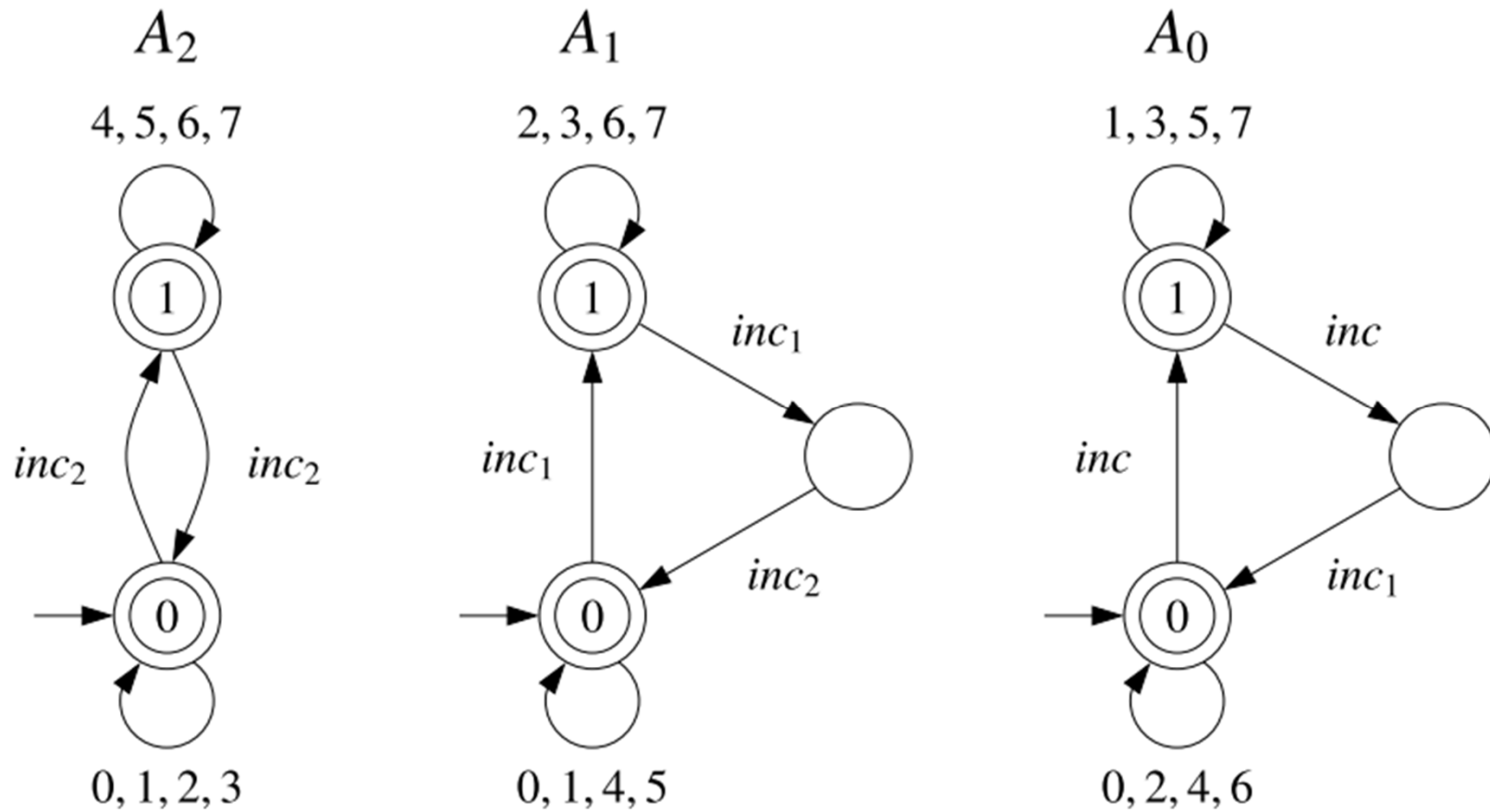

Compositional verification

To check emptiness of an asynchronous product $A_1 \otimes \cdots \otimes A_n$ we can

- Replace A_1 by an automaton A'_1 recognizing $proj_{\Sigma \setminus \Sigma_1}(L(A_1))$ and compute $A_{12} = A'_1 \otimes A_2$;
- Replace A_{12} by an automaton A'_{12} recognizing $proj_{\Sigma \setminus (\Sigma_1 \cup \Sigma_2)}(L(A_{12}))$ and compute $A_{13} = A'_{12} \otimes A_3$;
- ...
- Replace $A_{1(n-1)}$ by an automaton $A'_{1(n-1)}$ recognizing $proj_{\Sigma \setminus (\Sigma_1 \cup \cdots \cup \Sigma_{n-1})}(L(A_{1(n-1)}))$ and compute $A_{1n} = A'_{1(n-1)} \otimes A_n$

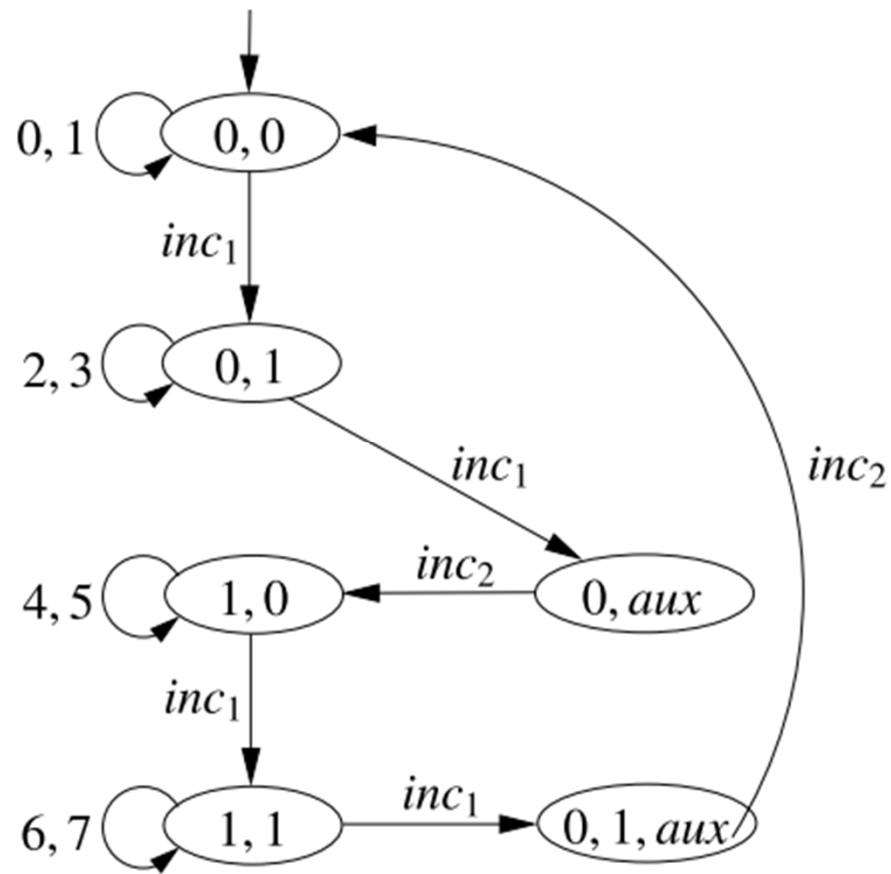
This can save space w.r.t. the direct computation .

Compositional verification

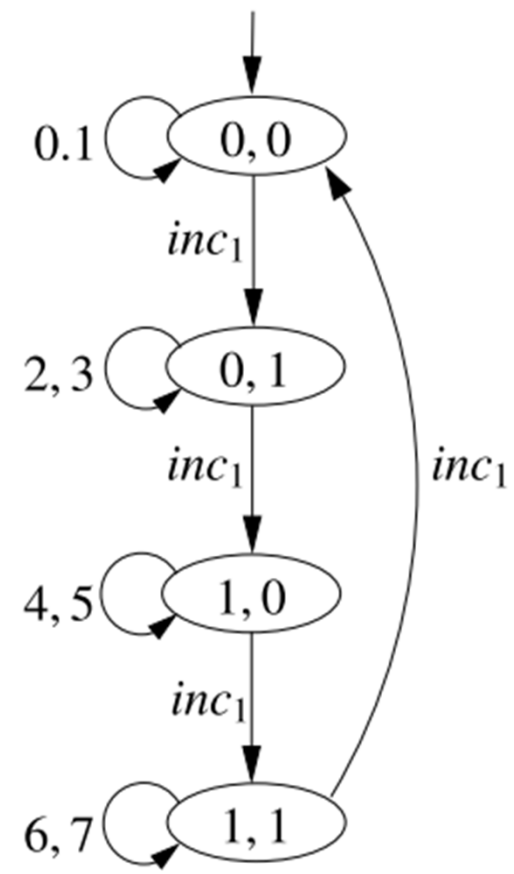


Compositional verification

A_{21}



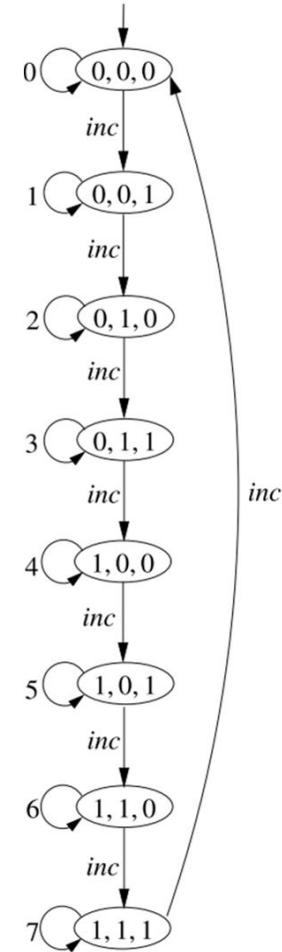
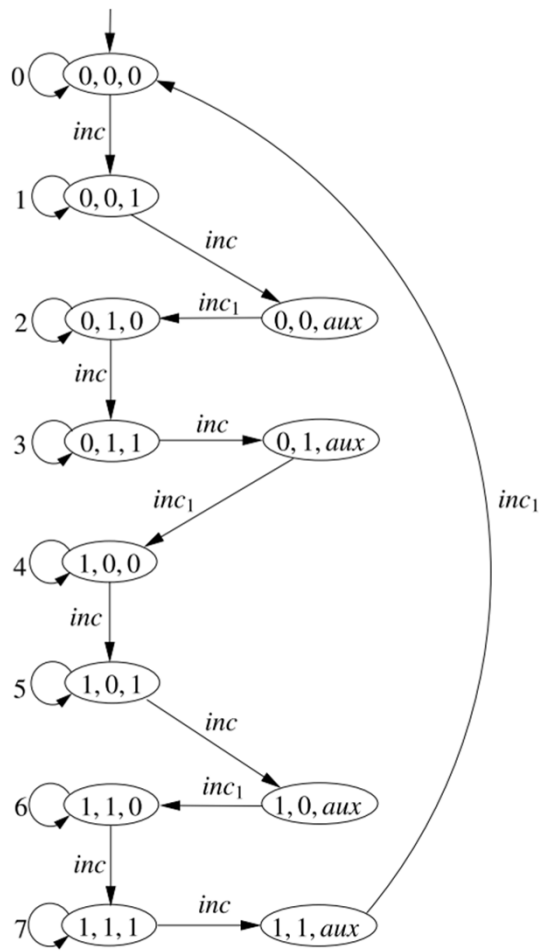
A'_{21}



Compositional verification

A_{20}

A'_{20} (proj. on visible actions)

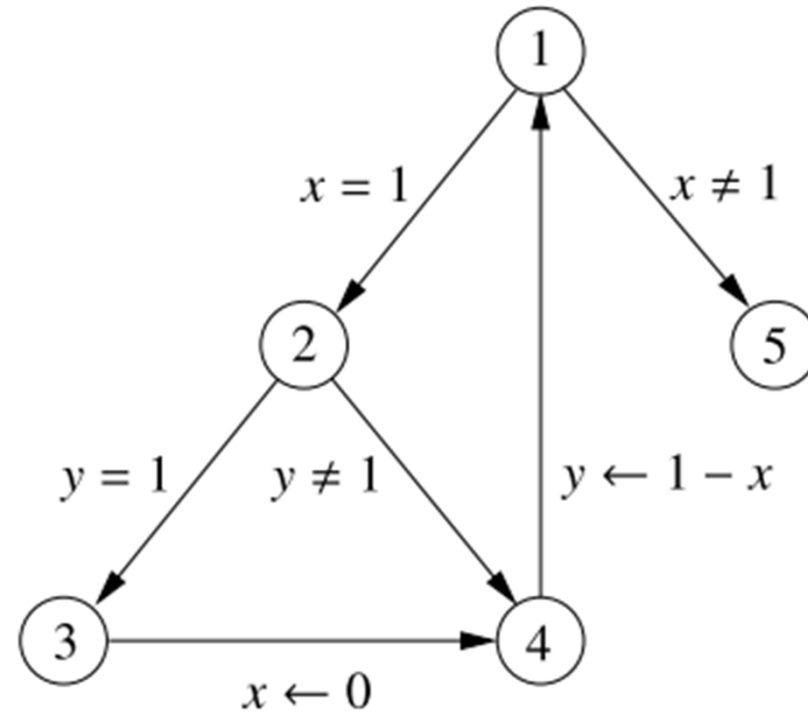


Symbolic exploration

- A technique to palliate the state-explosion problem
- Configurations can be encoded as words.
- The set of reachable configurations of a program can be encoded as a language.
- We use automata to compactly store the set of reachable configurations.

Flowgraphs

```
1  while  $x = 1$  do  
2    if  $y = 1$  then  
3       $x \leftarrow 0$   
4     $y \leftarrow 1 - x$   
5  end
```



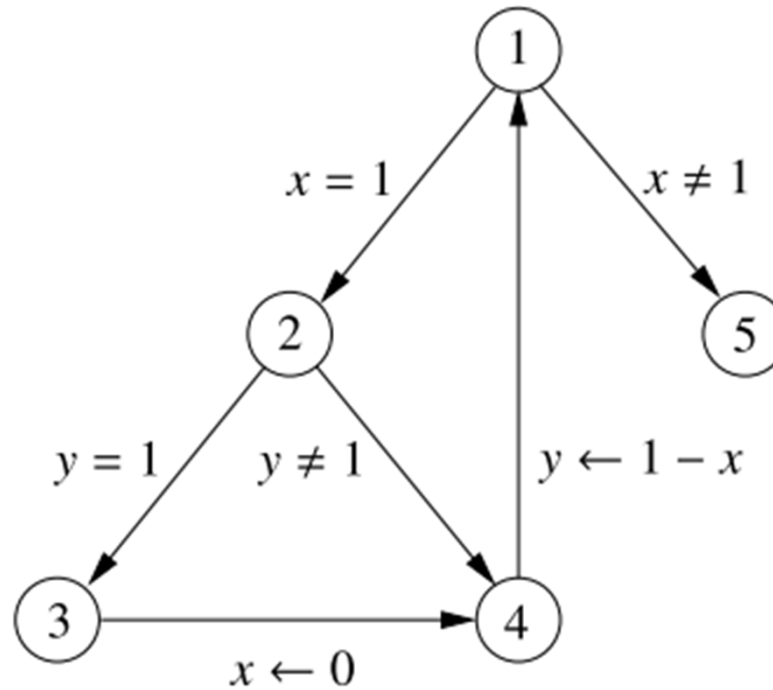
Step relations

- Let l, l' be two control points of a flowgraph.
- The **step relation** $S_{l,l'}$ contains all pairs

$$([l, x_0, y_0], [l', x'_0, y'_0])$$

of configurations such that :

if at point l the current values of x, y are x_0, y_0 ,
then the program can take a step,
after which the new control point is l' , and the new
values of x, y are x'_0, y'_0 .



$$S_{4,1} = \{ ([4, x_0, y_0], [1, x_0, 1 - x_0]) \mid x_0, y_0 \in \{0,1\} \}$$

- The **global step relation** S is the union of the step relations $S_{l,l'}$ for all pairs l, l' of control points.

Computing reachable configurations

- Start with the set of initial configurations.
- Iteratively: add the set of successors of the current set of configurations until a fixed point is reached.

$$P_0 = I$$



The diagram consists of two nested ellipses. The outer ellipse is a light orange color and contains the equation $P_1 = P_0 \cup Post(P_0, S)$. The inner ellipse is a darker brown color and contains the equation $P_0 = I$. The inner ellipse is centered within the outer ellipse, illustrating that P_0 is a subset of P_1 .

$$P_1 = P_0 \cup Post(P_0, S)$$

$$P_0 = I$$


$$P_1 = P_0 \cup Post(P_0, S)$$

$$P_0 = I$$

$$P_2 = P_1 \cup Post(P_1, S)$$



The diagram consists of three concentric, horizontally-oriented ellipses. The innermost ellipse is dark brown and contains the equation $P_0 = I$. The middle ellipse is a medium brown color and contains the equation $P_1 = P_0 \cup Post(P_0, S)$. The outermost ellipse is a light brown color and contains the equation $P_2 = P_1 \cup Post(P_1, S)$. The ellipses are nested, with each outer ellipse completely containing the inner ones.

$$P_1 = P_0 \cup Post(P_0, S)$$

$$P_0 = I$$

$$P_2 = P_1 \cup Post(P_1, S)$$

The diagram consists of three concentric, horizontally-oriented ovals. The innermost oval is dark brown and contains the text $P_0 = I$. The middle oval is a medium brown color and contains the text $P_1 = P_0 \cup Post(P_0, S)$. The outermost oval is a light tan color and contains the text $P_2 = P_1 \cup Post(P_1, S)$. The ovals are nested, with each outer oval completely containing the inner ones, illustrating the iterative expansion of a set P through a post-closure operation.

$$P_1 = P_0 \cup Post(P_0, S)$$

$$P_0 = I$$

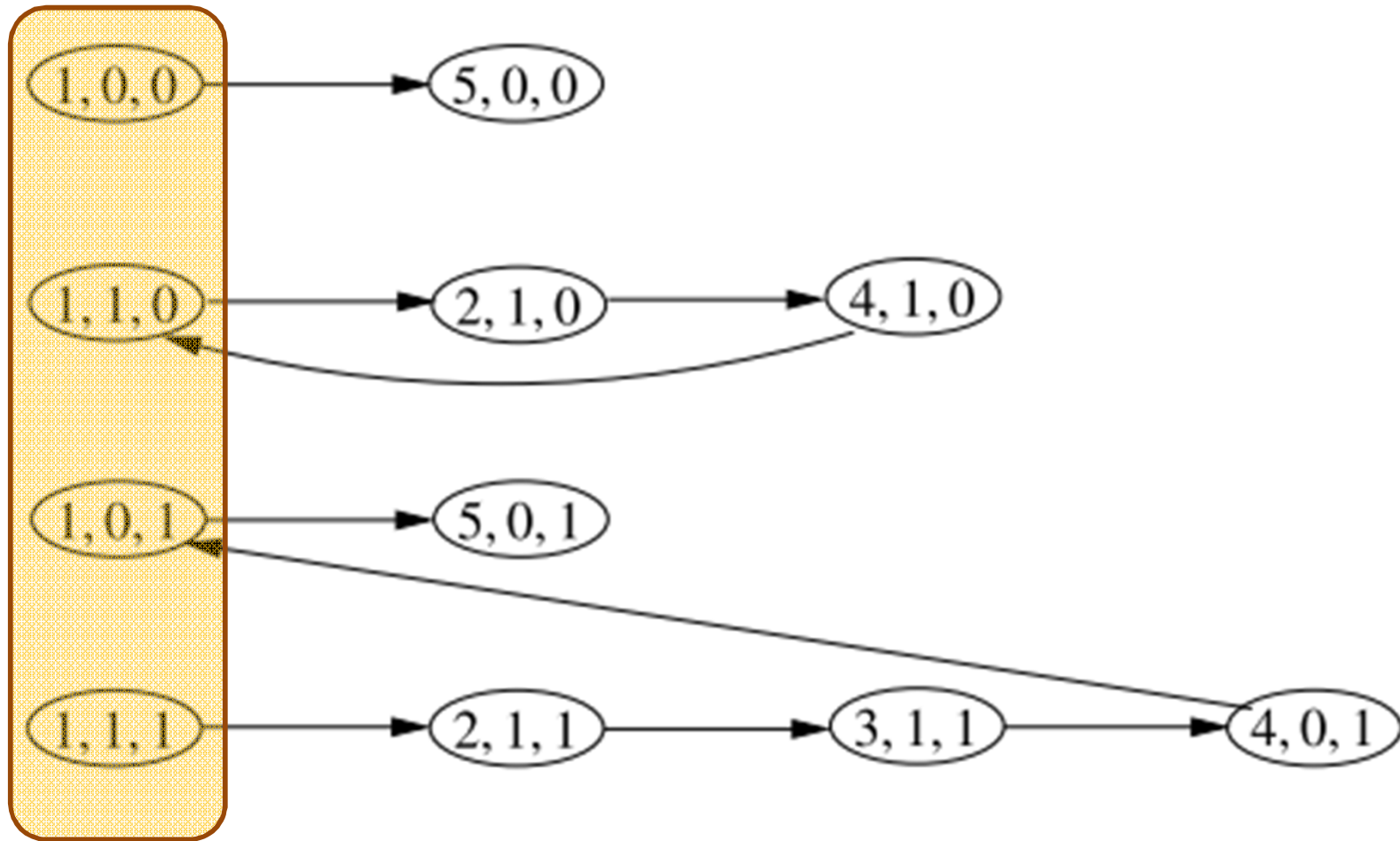
$$P_2 = P_1 \cup Post(P_1, S)$$

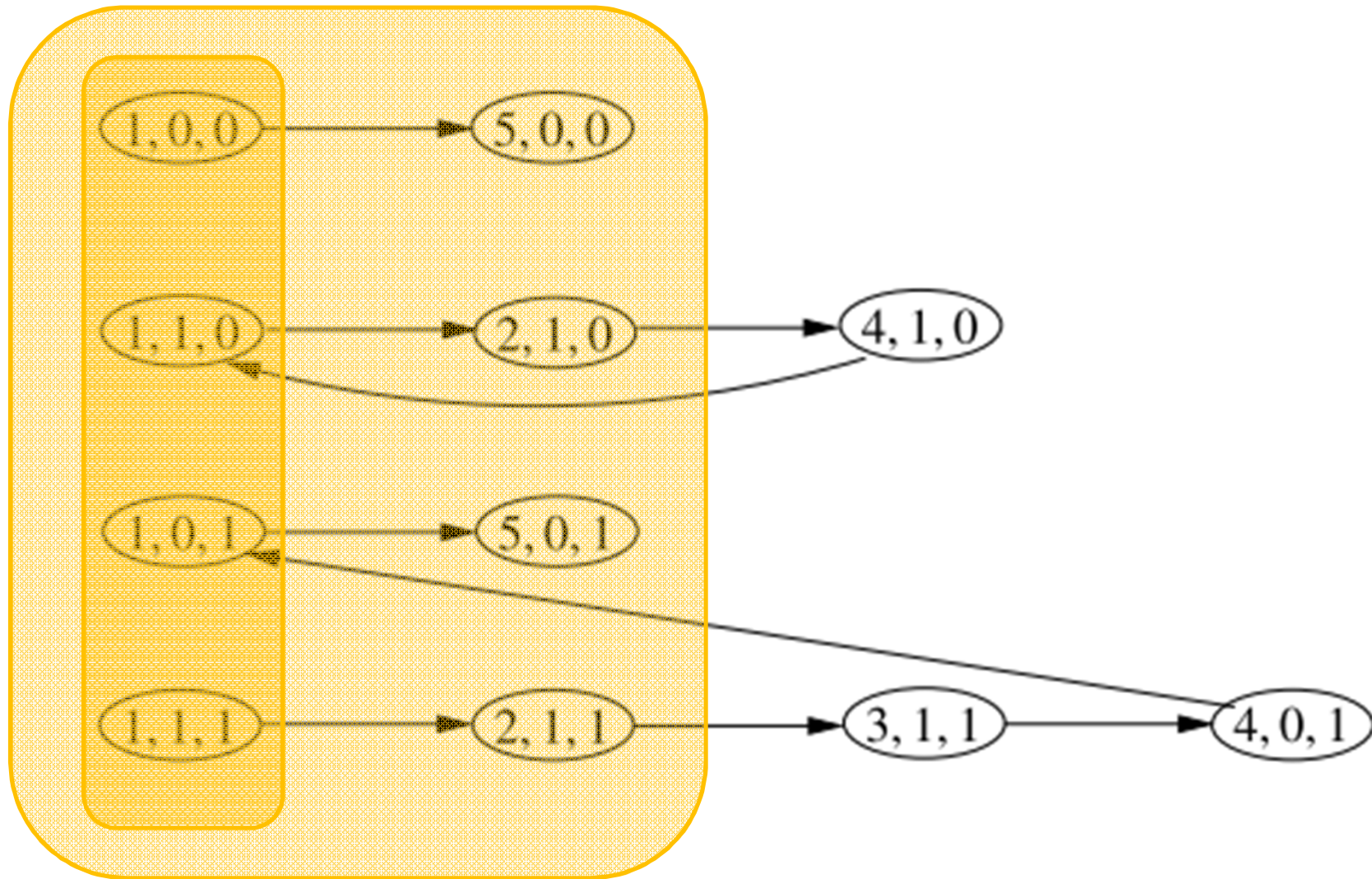
Reach(I, R)

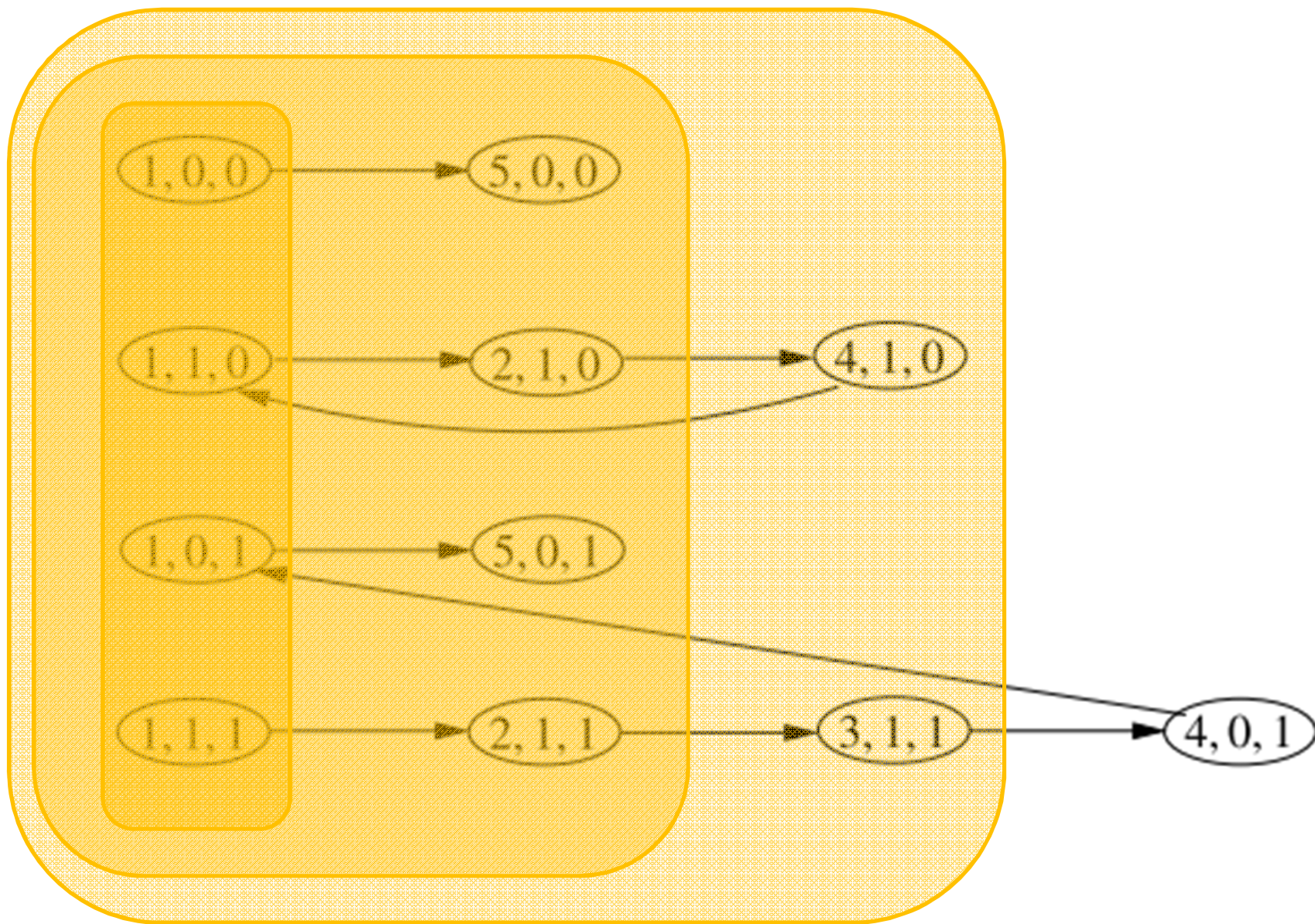
Input: set I of initial configurations; relation R

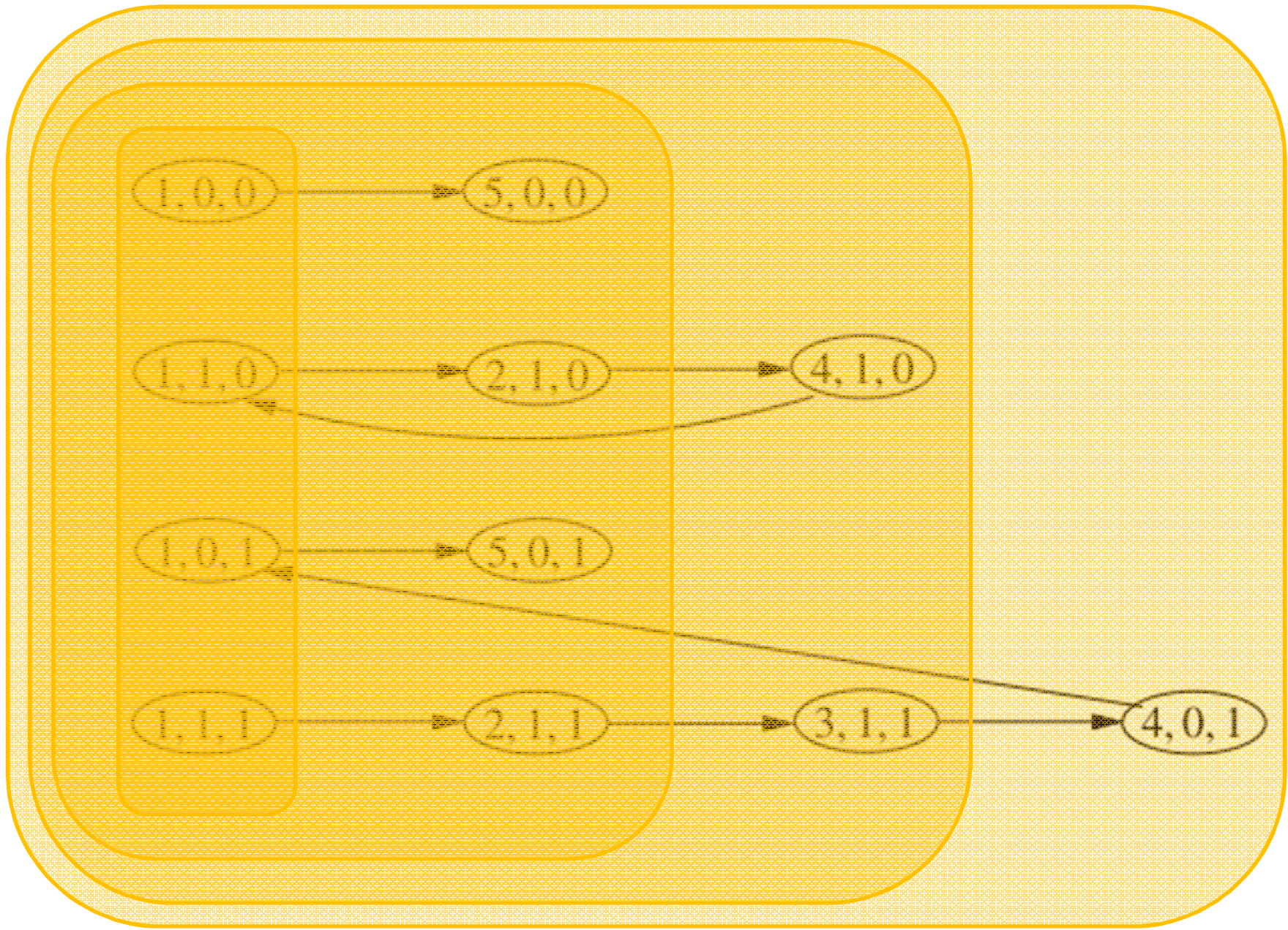
Output: set of configurations reachable from I

- 1 $OldP \leftarrow \emptyset; P \leftarrow I$
- 2 **while** $P \neq OldP$ **do**
- 3 $OldP \leftarrow P$
- 4 $P \leftarrow \mathbf{Union}(P, \mathbf{Post}(P, S))$
- 5 **return** P







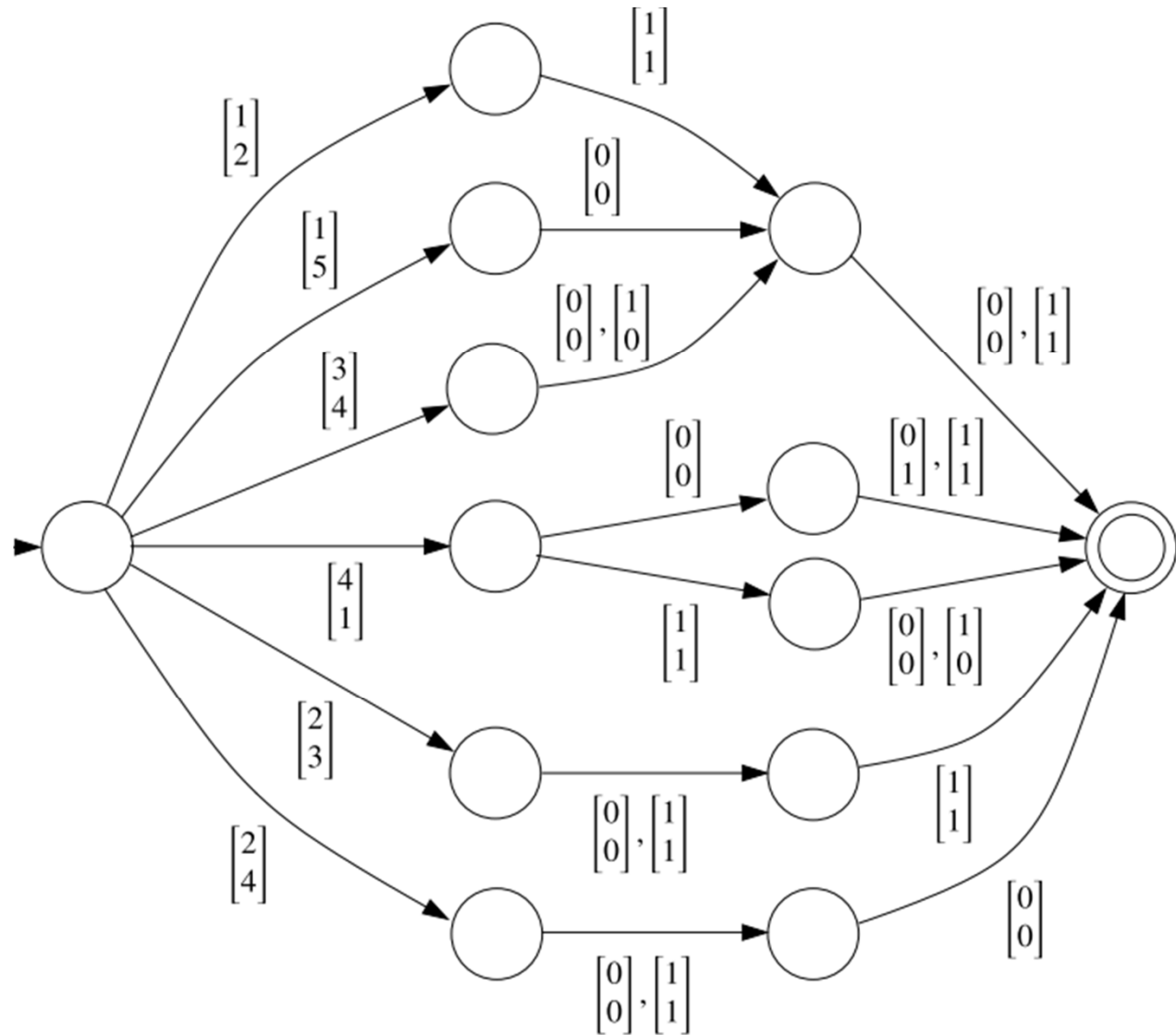


Example: Transducer for the global step relation

```

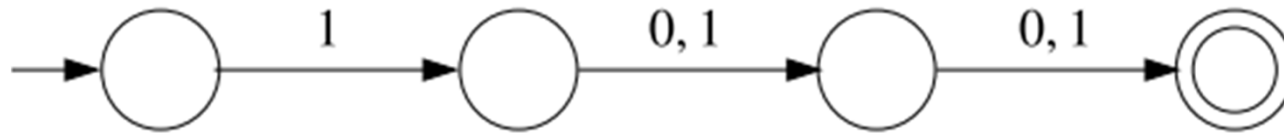
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```

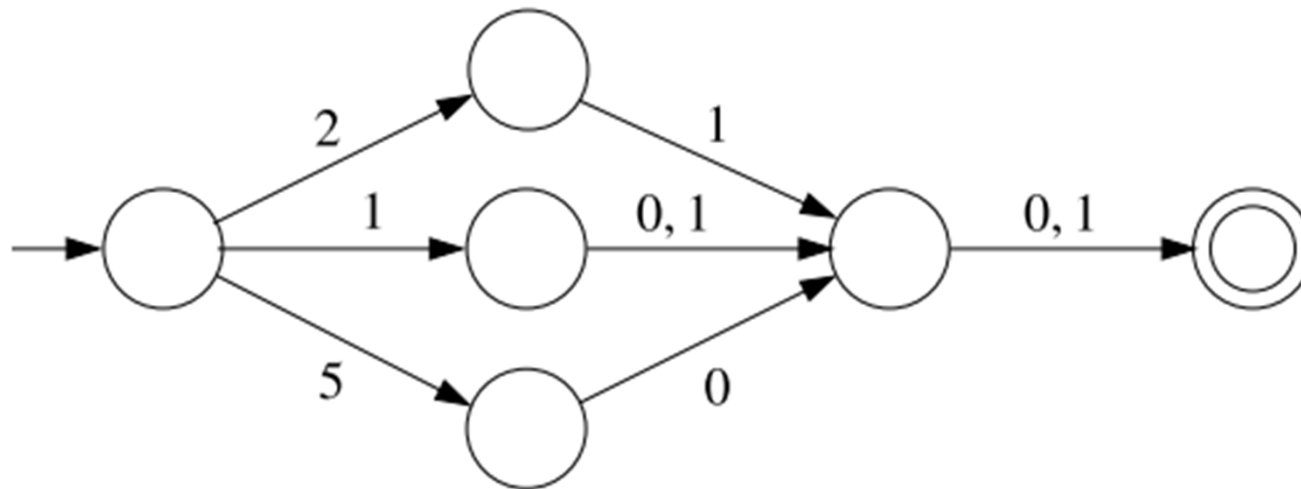


Example: DFAs generated by Reach

- Initial configurations

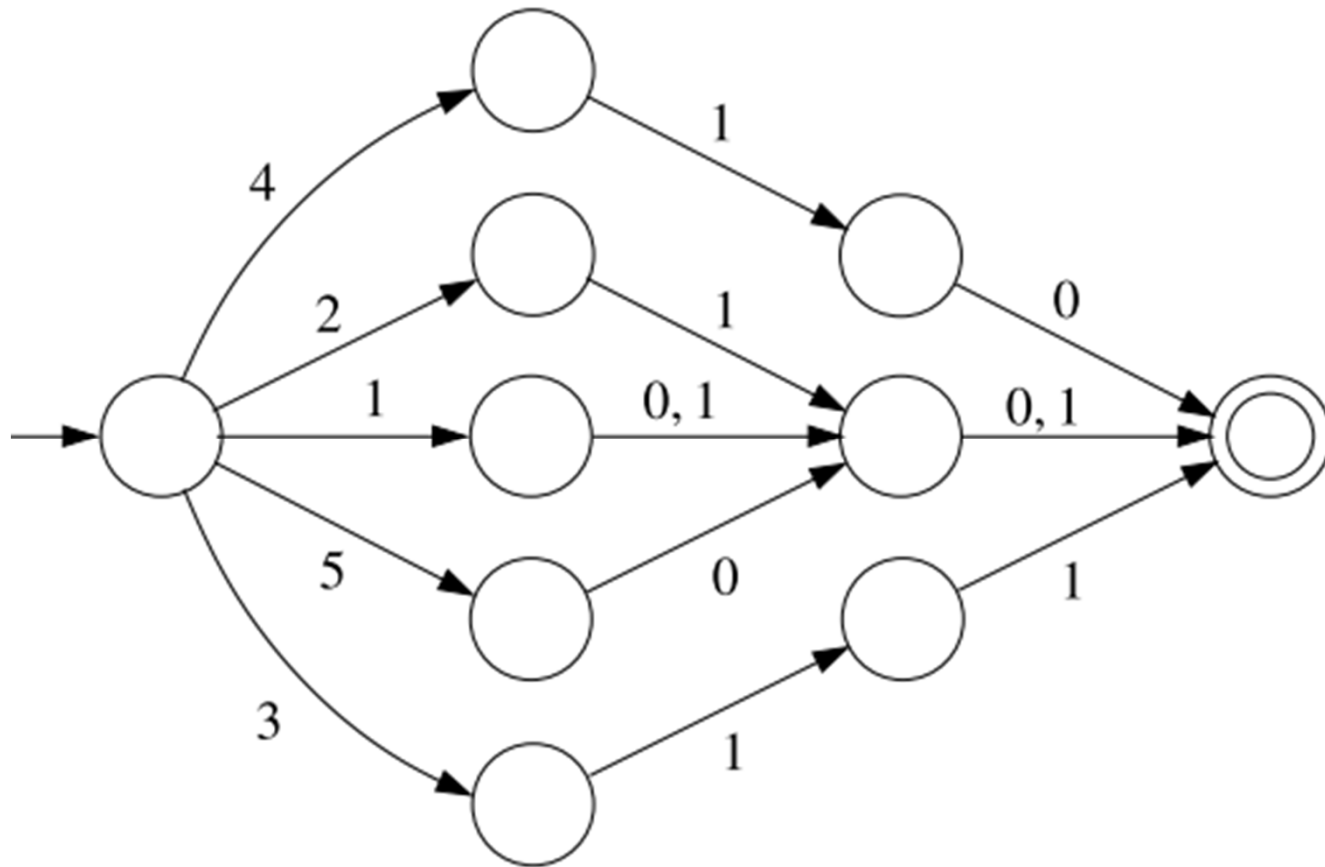


- Configurations reachable in at most 1 step



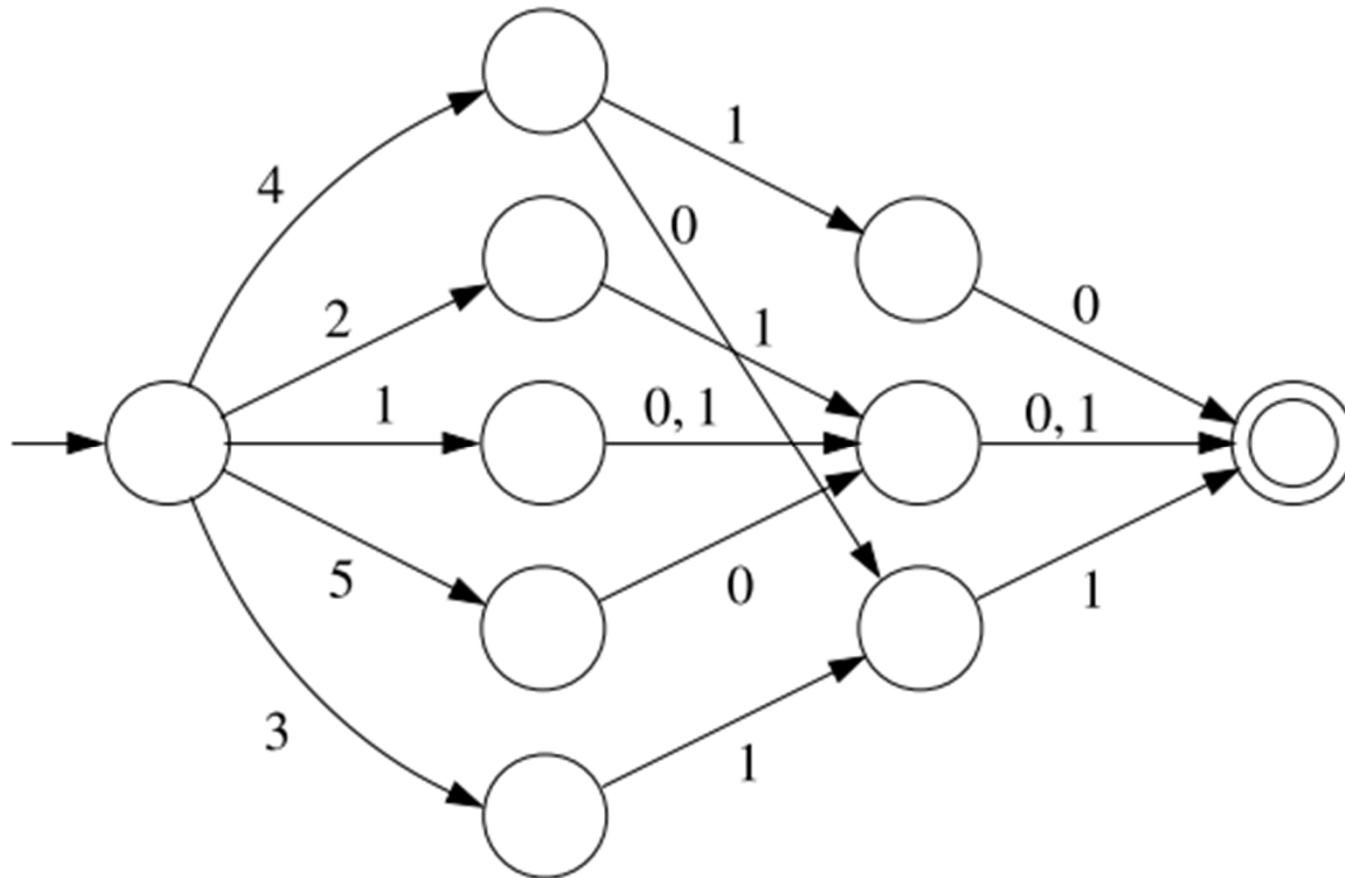
Example: DFAs generated by Reach

- Configurations reachable in at most 2 steps



Example: DFAs generated by Reach

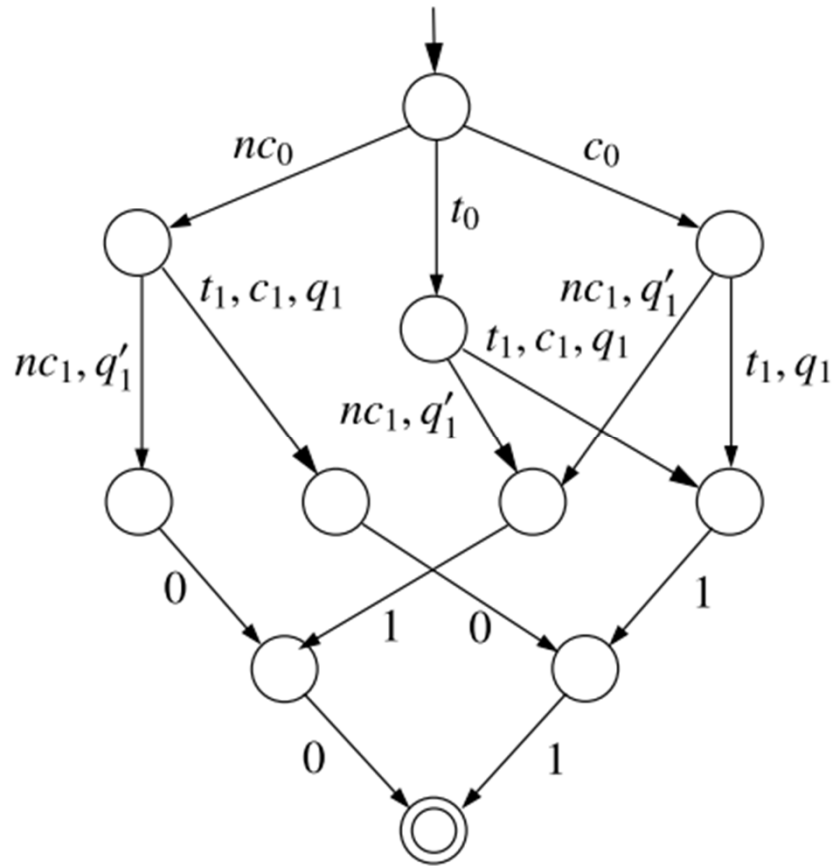
- Configurations reachable in at most 3 steps



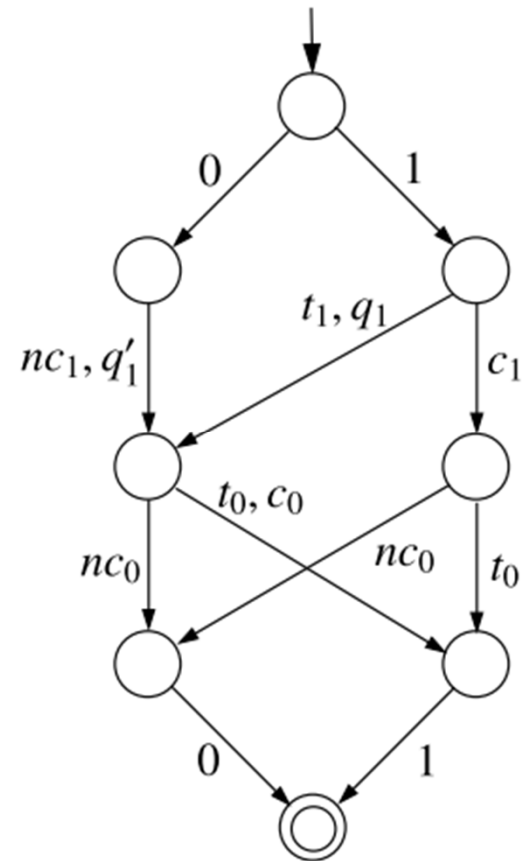
Variable orders

- Consider the set Y of tuples $[x_1, \dots, x_{2k}]$ of booleans such that $x_1 = x_{k+1}, x_2 = x_{k+2}, \dots, x_k = x_{2k}$
- A tuple $[x_1, \dots, x_{2k}]$ can be encoded by the word $x_1 x_2 \dots x_{2k-1} x_{2k}$ but also by the word $x_1 x_{k+1} \dots x_k x_{2k}$.
- For $k = 3$, the encodings of Y are then, respectively
 $\{000000, 001001, 010010, 011011, 100100, 101101, 110110, 111111\}$
 $\{000000, 000011, 001100, 001111, 110000, 110011, 111100, 111111\}$
- The minimal DFAs for these languages have very different sizes!

Another example: Lamport's algorithm

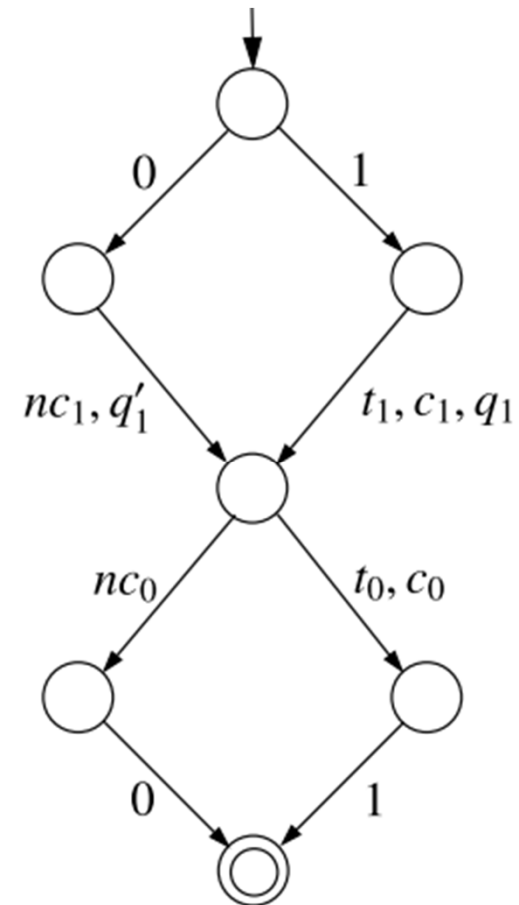
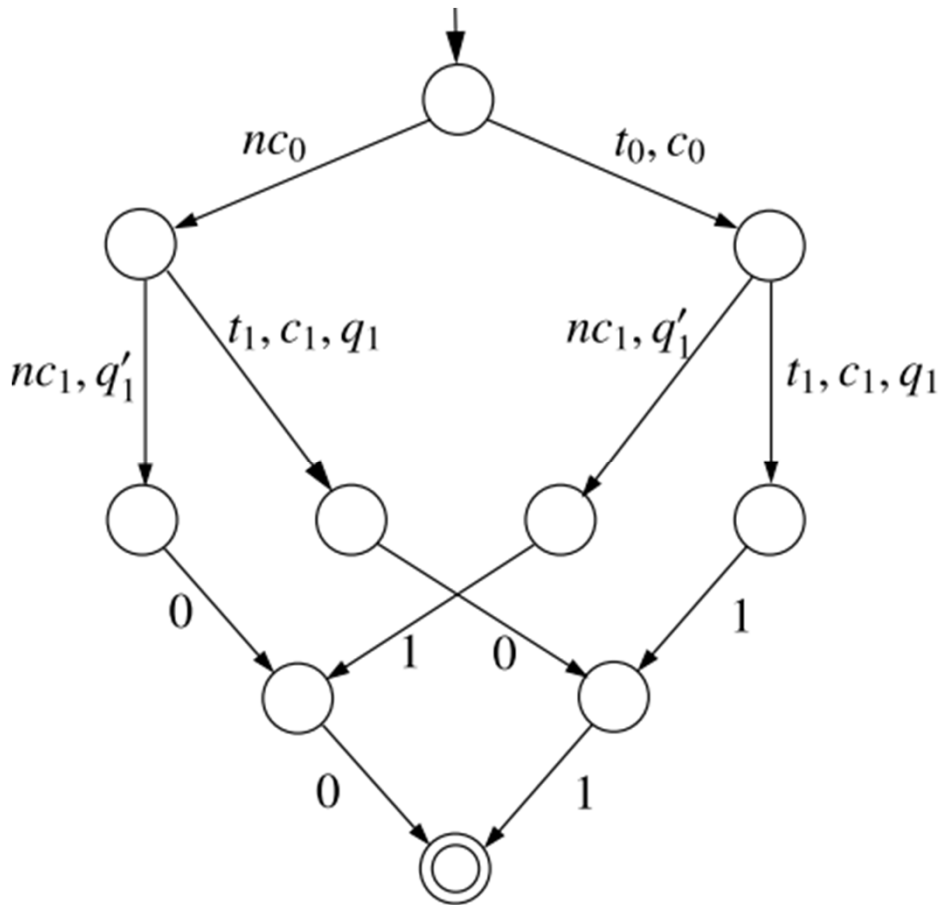


$\langle v_0, v_1, s_0, s_1 \rangle$
 encoded by
 $s_0 s_1 v_0 v_1$



$\langle v_0, v_1, s_0, s_1 \rangle$
 encoded by
 $v_1 s_1 s_0 v_0$

Larger sets can yield smaller DFAs!



- DFAs after adding the configuration $\langle c_0, c_1, 1, 1 \rangle$ to the set

- When encoding configurations, good variable orders can lead to much smaller automata.
- Unfortunately, the problem of finding an optimal encoding for a language represented by a DFA is NP-complete.