

Solution

Automata and Formal Languages – Homework 3

Due 12.11.2009.

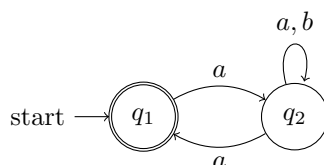
Exercise 3.1

Let $\mathcal{A} = (Q, \Sigma, \delta, q_{\text{initial}}, F)$ be some NFA. We assume that $Q = \{q_1, q_2, \dots, q_n\}$. With every word $w \in \Sigma^*$ we then associate the boolean matrix $M_w \in \{0, 1\}^{n \times n}$ with

$$(M_w)_{i,j} = 1 \text{ iff } \mathcal{A} \text{ can end up in state } q_j \text{ when reading the word } w \text{ starting from state } q_i.$$

The set $\mathcal{T}_{\mathcal{A}} := \{M_w \mid w \in \Sigma^*\}$ is then called the *transition monoid* of \mathcal{A} .

Example: Consider the following FA:



For this automaton, the matrices M_a , M_b , M_{aa} and M_{ab} are:

$$M_a = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}, \quad M_b = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \quad M_{aa} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \text{ and } M_{ab} = \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}.$$

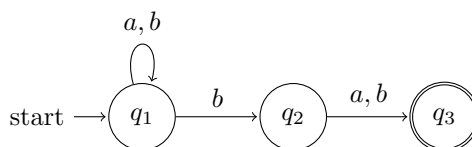
(a) Assuming standard multiplication of boolean matrices, we have in our example that $M_{aa} = M_a \cdot M_a$ and $M_{ab} = M_a \cdot M_b$.

- Show that $M_u \cdot M_v = M_{uv}$ holds for all $u, v \in \Sigma^*$ for any given NFA \mathcal{A} .
- Check that $\mathcal{T}_{\mathcal{A}}$ w.r.t. this multiplication is indeed a monoid.

Reminder:

$\langle S, \cdot \rangle$ is a monoid if (i) $\forall a, b \in S : a \cdot b \in S$, (ii) $\forall a, b, c \in S : a \cdot (b \cdot c) = (a \cdot b) \cdot c$, and (iii) $\exists 1 \in S \forall a \in S : a \cdot 1 = a = 1 \cdot a$.

(b) Consider the following FA \mathcal{A} :



- Draw the labeled graph with states the elements of $\mathcal{T}_{\mathcal{A}}$ and edges $M_u \xrightarrow{a} M_{ua}$ for $a \in \Sigma, u \in \Sigma^*$.

Note that $\mathcal{T}_{\mathcal{A}}$ has at most 2^9 elements; construct the graph on the fly starting from M_ε . You should end up with 7 elements/states.

- How can you obtain from this graph a deterministic finite automaton accepting the same language as the original nondeterministic automaton? How does this construction relate to the determinization procedure you have seen in the lecture?

Solution:

- (a) By definition of \mathcal{T}_A , for any $M \in \mathcal{T}_A$ we find a u such that $M_u = M$. It therefore suffices to consider matrices M_u, M_v, M_w with $u, v, w \in \Sigma^*$.

Notation: We also write δ for its extension to words (sometimes also explicitly denoted by $\hat{\delta}$). We then may write the definition of M_w also as follows:

$$(M_w)_{i,j} = \begin{cases} 1 & \text{if } q_j \in \delta(q_i, w) \\ 0 & \text{else} \end{cases}$$

One then easily checks then that for any two words $u, v \in \Sigma^*$ we have $M_u \cdot M_v = M_{uv}$ (*):

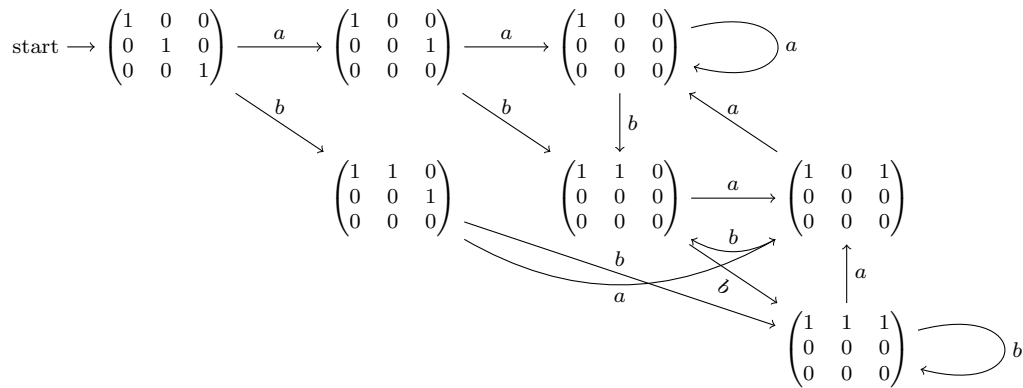
$$\begin{aligned} (M_u \cdot M_v)_{i,j} = 1 & \quad \text{iff} \quad \exists k \in [n] : (M_u)_{i,k} = 1 \wedge (M_v)_{k,j} = 1 \\ & \quad \text{iff} \quad \exists k \in [n] : \delta(q_i, u) \ni q_k \wedge \delta(q_k, v) \ni q_j \\ & \quad \text{iff} \quad \delta(q_i, uv) \ni q_j \\ & \quad \text{iff} \quad (M_{uv})_{i,j} = 1. \end{aligned}$$

By (*) we therefore have immediately that

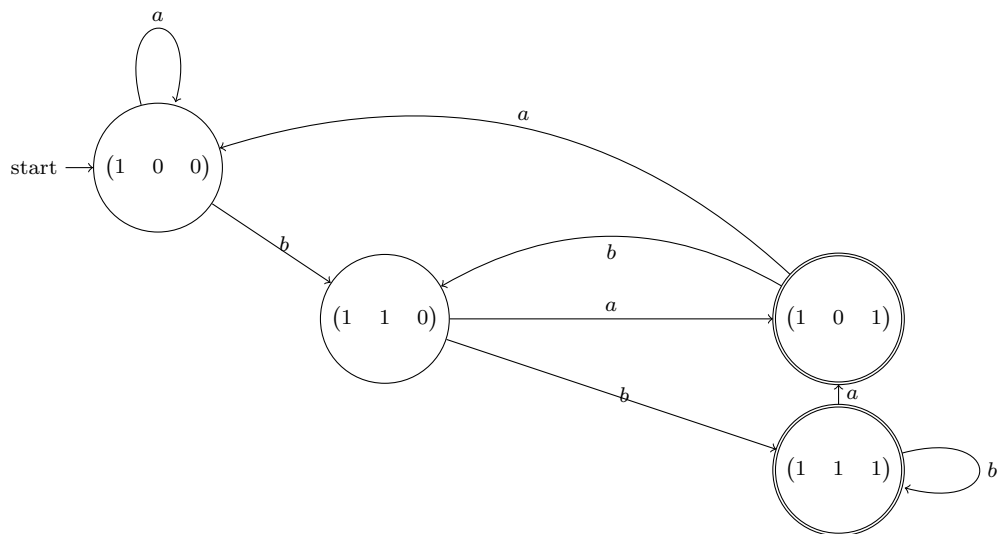
$$M_u \cdot M_v = M_{uv} \in \mathcal{T}_A \text{ and, in particular, } M_\varepsilon \cdot M_u = M_u = M_u \cdot M_\varepsilon.$$

That is, \mathcal{T}_A is closed w.r.t. the multiplication of boolean matrices and M_ε is a neutral element. Associativity also follows easily, as matrix multiplication is associativ.

- (b) •



- In the determinization procedure we only remember which states have been reached starting from the initial state. We therefore simply have to multiply (from the left) the states of above graph by the (row) vector encoding the initial state(s) (this also generalizes to FAs with multiple initial states). In our example, this vector is $(1, 0, 0)$, yielding (after unifying states):



In order to determine the final states, we similarly have to multiply (from the right) with the (column) vector encoding the final states (here: $(0, 0, 1)^T$).

Exercise 3.2

In the preceding exercise, the transition monoid $\mathcal{T}_{\mathcal{A}}$ of a finite automaton \mathcal{A} has been introduced. Recall also the syntactic monoid $\mathcal{S}_L := \Sigma^* / \equiv_L$ of a language $L \subseteq \Sigma^*$ which was the set of equivalence classes w.r.t. the binary relation \equiv_L on Σ^* defined by

$$x \equiv_L y \text{ iff } \forall u, v \in \Sigma^* : uxv \in L \Leftrightarrow uyv \in L.$$

- (a) Let $\mathcal{A} = (Q, \Sigma, \delta, q_i, F)$ be an NFA. Show that for $x, y \in \Sigma^*$ we have

$$M_x = M_y \Rightarrow x \equiv_L y.$$

- (b) Let L be a regular language over Σ . Let \mathcal{A}_L be a minimal DFA with $L = \mathcal{L}(\mathcal{A}_L)$. Show that for $x, y \in \Sigma^*$ it holds that

$$x \equiv_L y \Rightarrow M_x = M_y.$$

Is it necessary for \mathcal{A} to be deterministic or minimal?

- (c) Calculate the size of the syntactic monoid of the following languages:

- $\mathcal{L}((aa)^*)$ for $\Sigma = \{a\}$.
- $\mathcal{L}((ab + ba)^*)$ for $\Sigma = \{a, b\}$.

You can find some incomplete C++-code on the webpage for an easier calculation of the transition monoid.

- (d) A famous result by Schützenberger says that a regular language L is representable by a star-free expression if and only if its syntactic monoid \mathcal{S}_L is aperiodic. (A monoid $\langle M, \cdot, 1 \rangle$ is aperiodic if for any $a \in M$ there is a natural number n such that $a^n = a^{n+1}$.)

- Show that syntactic monoid of a regular language L is isomorphic to the transition monoid of a minimal DFA for L , i.e., show:

$$\forall x, y, z \in \Sigma^* : [x]_L \cdot [y]_L = [z]_L \text{ iff } M_x \cdot M_y = M_z.$$

- Decide for the two languages considered in (c) whether they are representable by star-free expressions. Use a computer.

Solution:

- (a) Assume $M_x = M_y$. Let $u, v \in \Sigma^*$ be arbitrary words. Further, let v_I be the row vector which encodes the initial states of \mathcal{A} . Similarly, let v_F be the column vector encoding the final states. It then holds:

$$\begin{aligned} uxv \in L & \text{ iff } v_I M_{uxv} v_F = 1 \\ & \text{ iff } v_I M_u M_x M_v v_F = 1 \\ & \text{ iff } v_I M_u M_y M_v v_F = 1 & \text{ (as } M_x = M_y) \\ & \text{ iff } v_I M_{uyv} v_F = 1 \\ & \text{ iff } uyv \in L. \end{aligned}$$

So, $M_x = M_y \Rightarrow x \equiv_L y$ indeed holds.

- (b) Assume $x \equiv_L y$ and $M_x \neq M_y$. We then find i, j such that $(M_x)_{i,j} \neq (M_y)_{i,j}$. W.l.o.g. we may assume that $(M_x)_{i,j} = 1$ (otherwise swap x and y), i.e., $\delta(q_i, x) = q_j \neq \delta(q_i, y)$. As \mathcal{A} is deterministic, $\delta(q_i, y)$ is defined, hence, set $q_k := \delta(q_i, y)$.

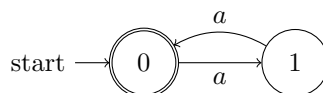
By minimality of \mathcal{A} , any state is reachable from the initial state, so there is a word $u \in \Sigma^*$ s.t. $\delta(q_{\text{initial}}, u) = q_i$. We now have $ux \in P(q_i)$ and $uy \in P(q_k)$, and, again by minimality of \mathcal{A} , we conclude $ux \not\equiv_L uy$ (see ex.2.3), and subsequently $ux \not\equiv_L uy$ which contradicts our assumption.

- (c) From (a) and (b) it follows:

Let \mathcal{A} be a minimal DFA for $L \subseteq \Sigma^*$. Then $x \equiv_L y$ iff $M_x = M_y$.

This means that the transition monoid of a minimal DFA for L has the same number of elements as Σ^* / \equiv_L . It therefore suffices to determine the size of $\mathcal{T}_{\mathcal{A}}$ in order to determine $|\Sigma^* / \equiv_L|$:

- The minimal DFA for $(aa)^*$ is drawn below:

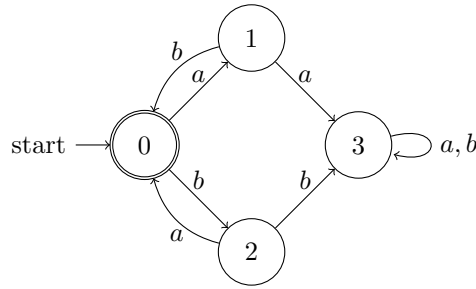


This yields the transition matrix

$$M_a = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

One easily checks that $M_a^2 = \text{Id} = M_\varepsilon$. So, the syntactic monoid consists of the equivalence classes $[\varepsilon] = \mathcal{L}((aa)^*)$ and $[a] = \mathcal{L}(a(aa)^*)$.

- The minimal DFA for $(ab + ba)^*$:



This yields the matrices:

$$M_a = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \text{ and } M_b = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Using the supplied code, one can check that the transition monoid consists of 15 elements. By (a) and (b) the transition monoid of the minimal DFA has the same size as the syntactic monoid.

- (d) • The multiplication on \mathcal{S}_L was defined by

$$[x]_L \cdot [y]_L := [xy]_L.$$

In exercise 2.3 it was shown that this multiplication is well-defined. So

$$\begin{aligned} [x]_L \cdot [y]_L = [z]_L & \text{ iff } xy \equiv_L z \\ & \text{ iff } M_{xy} = M_z & \text{(cf. (a) and (b))} \\ & \text{ iff } M_x \cdot M_y = M_z \end{aligned}$$

Therefore we have

$$\begin{aligned} [x]_L^n = [x]_L^{n+1} & \text{ iff } [x^n]_L = [x^{n+1}]_L \\ & \text{ iff } M_{x^n} = M_{x^{n+1}} \\ & \text{ iff } (M_x)^n = (M_x)^{n+1}. \end{aligned}$$

It therefore suffices to check that the transition monoid of a minimal DFA for L is aperiodic.

- For $(aa)^*$ we have already seen that the transition monoid of the minimal DFA is periodic as $M_a^{2k} = M_\varepsilon, M_a^{2k+1} = M_a$ for all $k \in \mathbb{N}_0$. As the syntactic monoid is isomorphic to this transition monoid, $(aa)^*$ is not representable by a star-free expression.

For $(ab + ba)^*$ one easily extends the supplied code to also check that the transition, and therefore syntactic monoid are aperiodic. Thus a star-free expression exists for $\mathcal{L}((ab + ba)^*)$.

Exercise 3.3

Let $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ be an NFA and \sim its bisimilarity relation.

- (a) Prove or disprove that $\mathcal{L}(q) = \mathcal{L}(q') \Rightarrow q \sim q'$ for $q, q' \in Q$.
- (b) A binary relation $R \subseteq Q \times Q$ is called a *simulation* if for any pair $(q, q') \in R$ we have

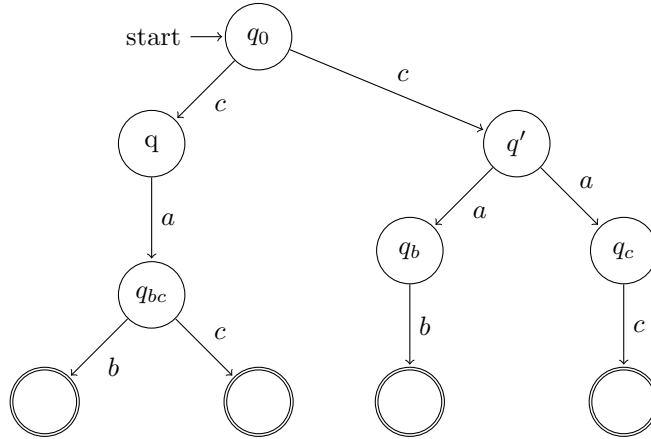
$$(q \in F \Leftrightarrow q' \in F) \wedge \forall a \in \Sigma \forall q_a \in \delta(q, a) \exists q'_a \in \delta(q', a) : (q_a, q'_a) \in R.$$

Let \preceq denote $\bigcup \{R \mid R \text{ is a simulation w.r.t. } \mathcal{A}\}$.

- Show that $q \preceq q' \Rightarrow \mathcal{L}(q) \subseteq \mathcal{L}(q')$.
- Prove or disprove: $(q \preceq q' \wedge q' \preceq q) \Rightarrow q \sim q'$.

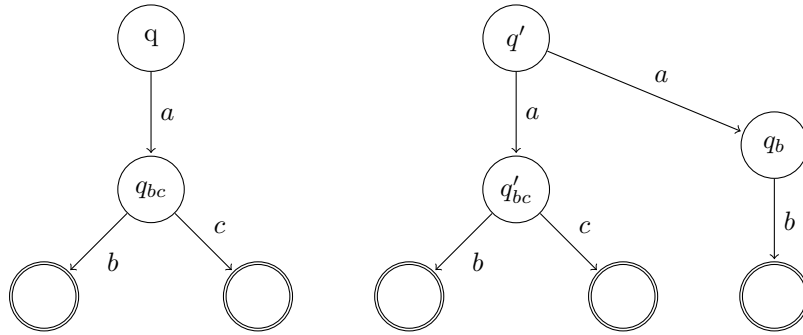
Solution:

- (a) Obviously, $\mathcal{L}(q) = \mathcal{L}(q') = \{ab, ac\}$. We claim $q \not\sim q'$. If $q \sim q'$, then $q_{bc} \sim q_b$ or $q_{bc} \sim q_c$. This is not possible since q_{bc} has transitions under both b and c , while q_b and q_c do not.



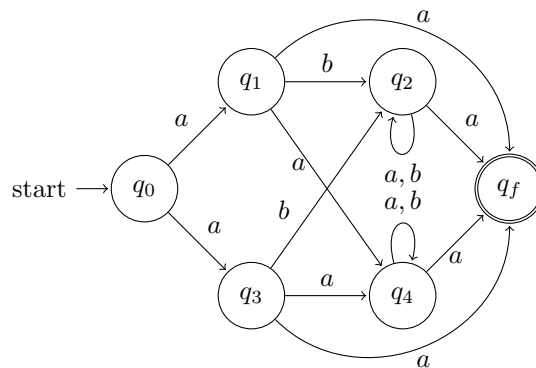
- (b) Let $w \in \Sigma^*$, we prove that for $q \preceq q'$ if $w \in \mathcal{L}(q)$ then also $w \in \mathcal{L}(q')$. We proceed by induction on the length of word w . Let $|w| = 0$ then $w \in \mathcal{L}(q) \Rightarrow q \in F \Rightarrow q' \in F \Rightarrow w \in \mathcal{L}(q')$. Now suppose the claim holds for n and $|w| = n + 1$. Let us denote $w = xy$ for the appropriate $x \in \Sigma$. Assuming $w \in \mathcal{L}(q)$ there exists $p \in \delta(q, x)$ with $y \in \mathcal{L}(p)$ and thus also $p' \in \delta(q', x)$ with $p \preceq p'$ (by the definition of simulation, since \preceq is clearly also a simulation). By induction hypothesis $y \in \mathcal{L}(p')$ and thus $w = xy \in \mathcal{L}(q')$.

- (c) Clearly, $q \preceq q'$ and since $q_b \preceq q_{bc}$ also $q' \preceq q$. However, since $q_b \not\preceq q_{bc}$ we get $q \not\sim q'$.



Exercise 3.4

Consider the following NFA \mathcal{A} :



- (a) Determine $L := \mathcal{L}(\mathcal{A})$.
 (b) Determine the bisimilarity relation \sim of \mathcal{A} . Use the partitioning algorithm presented in the lecture.

Solution:

- (a) $L = a\Sigma^*a$

(b) We begin with partitioning $\{\{q_0, q_1, q_2, q_3, q_4\}, \{q_f\}\}$. Since $(a, \{q_f\})$ splits $\{q_0, q_1, q_2, q_3, q_4\}$ we get a new partitioning $\{\{q_0\}, \{q_1, q_2, q_3, q_4\}, \{q_f\}\}$ which is stable.