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IMPLEMENTING LTL MODEL CHECKING WITH NET UNFOLDINGS

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Picaset Oy Helsinki 2001 ABSTRACT: We report on an implementation of the unfolding approach to model-checking LTL-X recently presented by the authors. Contrary to that work, we consider an state-based version of LTL-X, which is more used in practice. We improve on the checking algorithm; the new version allows to reuse code much more efficiently. We present results on a set of case studies.

KEYWORDS: Net unfoldings, model checking, tableau systems, Petri nets, LTL

Contents

1	Introduction	1
2	Petri nets	1
3	Automata Theoretic Approach to Model Checking LTL	3
4	Basic definitions on unfoldings	7
5	Tableau System	10
6	Generating the Tableau	11
7	Experimental Results	16
8	Conclusions	18
9	Appendix A - Proofs of Theorems	22

1 INTRODUCTION

Unfoldings [14, 6, 5] are a partial-order approach to the automatic verification of concurrent and distributed systems, in which partial-order semantics is used to generate a compact representation of the state space. For systems exhibiting a high degree of concurrency, this representation can be exponentially more succinct than the explicit enumeration of all states or the symbolic representation in terms of a BDD, thus providing a very good solution to the state-explosion problem.

Unfolding-based model-checking techniques for LTL without the next operator (called LTL-X in the sequel) were first proposed in [22]. A new algorithm with better complexity bounds was introduced in [3], in the shape of a tableau system. The approach is based on the automata-theoretic approach to model-checking (see for instance [20]), consisting of the following well-known three steps: (1) translate the negation of the formula to be checked into a Büchi automaton; (2) synchronize the system and the Büchi automaton in an adequate way to yield a composed system, and (3) check emptiness of the language of the composed system, where language is again defined in a suitable way.

In [3] we used an action-based version of LTL-X having an operator $\phi_1 \mathcal{U}^a \phi_2$ for each action a; $\phi_1 \mathcal{U}^a \phi_2$ holds if ϕ_1 holds until action a occurs, and immediately after ϕ_2 holds. Step (2) is very simple for this logic, which allowed us to concentrate on step (3), the most novel contribution of [3]. However, the state-based version of LTL-X is more used in practice. The first contribution of this paper is a solution to step (2) for this case, which turns out to be quite delicate.

The second contribution of this paper concerns step (3). In [3] we presented a two-phase solution; the first phase requires to construct one tableau, while the second phase requires to construct a possibly large set of tableaux. We propose here a more elegant solution which, loosely speaking, allows to merge all the tableaux of [3] into one while keeping the rules for the tableau construction simple and easy to implement.

The third contribution is an implementation using the *smodels* NP-solver [18], and a report on a set of case studies.

The paper is structured as follows. Section 2 contains basic definitions on Petri nets, which we use as system model. Section 3 describes step (2) above for the state-based version of LTL-X. Readers wishing to skip this section need only read (and believe the proof of) Theorem 1. Section 4 presents some basic definitions about the unfolding method. Section 5 describes the new tableau system for (3), and shows its correctness. Section 6 discusses the tableau generation together with some optimizations. Section 7 reports on the implementation and case studies, and Section 8 contains conclusions.

2 PETRI NETS

A net is a triple (P, T, F), where P and T are disjoint sets of places and transitions, respectively, and F is a function $(P \times T) \cup (T \times P) \rightarrow \{0, 1\}$. Places and transitions are generically called nodes. If F(x, y) = 1 then we

2 PETRINETS 1

say that there is an arc from x to y. The preset of a node x, denoted by ${}^{\bullet}x$, is the set $\{y \in P \cup T \mid F(y,x) = 1\}$. The postset of x, denoted by x^{\bullet} , is the set $\{y \in P \cup T \mid F(x,y) = 1\}$. In this paper we consider only nets in which every transition has a nonempty preset and a nonempty postset.

A marking of a net (P, T, F) is a mapping $P \to \mathbb{N}$ (where \mathbb{N} denotes the natural numbers including 0). We identify a marking M with the multiset containing M(p) copies of p for every $p \in P$. For instance, if $P = \{p_1, p_2\}$ and $M(p_1) = 1$, $M(p_2) = 2$, we write $M = \{p_1, p_2, p_2\}$.

A marking M enables a transition t if it marks each place $p \in {}^{\bullet}t$ with a token, i.e. if M(p) > 0 for each $p \in {}^{\bullet}t$. If t is enabled at M, then it can fire or occur, and its occurrence leads to a new marking M', obtained by removing a token from each place in the preset of t, and adding a token to each place in its postset; formally, M'(p) = M(p) - F(p,t) + F(t,p) for every place p. For each transition t the relation t is defined as follows: t is enabled at t and its occurrence leads to t.

A 4-tuple $\Sigma = (P, T, F, M_0)$ is a net system if (P, T, F) is a net and M_0 is a marking of (P, T, F) (called the *initial marking* of Σ). A sequence of transitions $\sigma = t_1 t_2 \dots t_n$ is an occurrence sequence if there exist markings M_1, M_2, \dots, M_n such that

$$M_0 \xrightarrow{t_1} M_1 \xrightarrow{t_2} \dots M_{n-1} \xrightarrow{t_n} M_n$$

 M_n is the marking reached by the occurrence of σ , which is also denoted by $M_0 \stackrel{\sigma}{\longrightarrow} M_n$. A marking M is a reachable marking if there exists an occurrence sequence σ such that $M_0 \stackrel{\sigma}{\longrightarrow} M$. An execution is an infinite occurrence sequence starting from the initial marking. The reachability graph of a net system Σ is the labelled graph having the reachable markings of Σ as nodes, and the $\stackrel{t}{\longrightarrow}$ relations (more precisely, their restriction to the set of reachable markings) as edges. In this work we only consider net systems with finite reachability graphs.

A marking M of a net is n-safe if $M(p) \le n$ for every place p. A net system Σ is n-safe if all its reachable markings are n-safe. Fig. 1 shows a 1-safe net system.

Labelled nets. Let \mathcal{L} be an alphabet. A *labelled net* is a pair (N, l) (also represented as a 4-tuple (P, T, F, l)), where N is a net and $l: P \cup T \to \mathcal{L}$ is a labelling function. Notice that different nodes of the net can carry the same label. We extend l to multisets of $P \cup T$ in the obvious way.

For each label $a \in \mathcal{L}$ we define the relation $\stackrel{a}{\longrightarrow}$ between markings as follows: $M \stackrel{a}{\longrightarrow} M'$ if $M \stackrel{t}{\longrightarrow} M'$ for some transition t such that l(t) = a. For a finite sequence $w = a_1 a_2 \dots a_n \in \mathcal{L}^*$, $M \stackrel{w}{\longrightarrow} M'$ denotes that for some reachable markings M_1, M_2, \dots, M_{n-1} of the net system the relation $M \stackrel{a_1}{\longrightarrow} M_1 \stackrel{a_2}{\longrightarrow} M_2 \dots M_{n-1} \stackrel{a_n}{\longrightarrow} M'$ holds. For an infinite sequence $w = a_1 a_2 \dots \in \mathcal{L}^{\omega}$, $M \stackrel{w}{\longrightarrow}$ denotes that $M \stackrel{a_1}{\longrightarrow} M_1 \stackrel{a_2}{\longrightarrow} M_2 \dots$ holds for some reachable markings M_1, M_2, \dots

The reachability graph of a labelled net system (N, l, M_0) is obtained by applying l to the reachability graph of (N, M_0) . In other words, its nodes are the set

 $\{l(M) \mid M \text{ is a reachable marking}\}$

2 PETRINETS 2

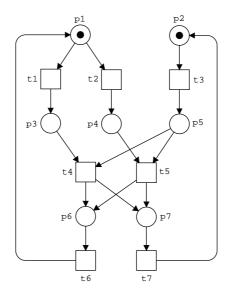


Figure 1: The net system Σ

and its edges are the set

$$\{l(M_1) \xrightarrow{l(t)} l(M_2) \mid M_1 \text{ is reachable and } M_1 \xrightarrow{t} M_2\}$$
.

3 AUTOMATA THEORETIC APPROACH TO MODEL CHECKING LTL

We show how to modify the automata theoretic approach to model checking LTL [20] to best suit the net unfolding method.

We restrict the logic LTL by removing the next time operator X. We call this stuttering invariant fragment LTL-X. Given a finite set Π of atomic propositions, the abstract syntax of LTL-X is given by:

$$\varphi ::= \pi \in \Pi \mid \neg \varphi_1 \mid \varphi_1 \land \varphi_2 \mid \varphi_1 \mathcal{U} \varphi_2$$

The semantics is a set of ω -words over the alphabet 2^{Π} , defined as usual.

Given a 1-safe net system Σ with initial marking M_0 , we identify the atomic propositions Π with a subset $Obs \subseteq P$ of observable places of the net system, while the rest of the places are called hidden. Each marking M determines a valuation of $\Pi = Obs$ in the following way: $p \in Obs$ is true at M if M puts a token in p. Now, an execution $M_0 \xrightarrow{t_1} M_1 \xrightarrow{t_2} \ldots$ of Σ satisfies φ iff the ω -word $M_0M_1\ldots$ satisfies φ . The net system Σ satisfies φ , denoted $\Sigma \models \varphi$, if every execution of Σ satisfies φ .

The approach. Let φ be a formula of LTL-X. Using well-known algorithms (see e.g. [8]) we construct a Büchi automaton $\mathcal{A}_{\neg \varphi}$ over the alphabet $2^{\Pi} = 2^{Obs}$ which accepts a word w iff $w \not\models \varphi$.

We define a 1-safe product net system $\Sigma_{\neg\varphi}$ from Σ and $\mathcal{A}_{\neg\varphi}$. $\Sigma_{\neg\varphi}$ can be seen as the result of placing Σ in a suitable environment, i.e., $\Sigma_{\neg\varphi}$ is constructed by connecting Σ to an environment net system through new arcs.

It is easy to construct a product net system with a distinguished set of transitions I such that Σ violates φ iff some execution of the product fires some transition of I infinitely often. We call such an execution an illegal ω -trace. However, this product synchronizes $\mathcal{A}_{\neg\varphi}$ with Σ on all transitions, which effectively disables all concurrency present in Σ . Since the unfolding approach exploits the concurrency of Σ in order to generate a compact representation of the state space, this product is not suitable, and so we propose a new one.

We define the set V of visible transitions of Σ as the set of transitions which change the marking of some observable place of Σ . Only these transitions will synchronize with the automaton. So, for instance, in order to check a property of the form $\Box(p \to \Diamond q)$, where p and q are places, we will only synchronize with the transitions removing or adding tokens to p and q. This approach is similar but not identical to Valmari's tester approach described in [19]. (In fact, a subtle point in Valmari's construction makes its direct implementation unsuitable for checking state based LTL-X.)

The price to pay for this nicer synchronization is the need to check not only for illegal ω -traces, but also for so-called illegal livelocks. The new product contains a new distinguished set of transitions L (for livelock). An *illegal livelock* is an execution of the form $\sigma_1 t \sigma_2$ such that $t \in L$ and σ_2 does not contain any visible transition. For convenience we use the notation $M_0 \xrightarrow{\sigma} M \xrightarrow{\tau}$ to denote this, and implicitly require that $\sigma = \sigma_1 t$ with $t \in L$ and that τ is an infinite sequence which only contains invisible transitions.

In the rest of the section we define $\Sigma_{\neg \varphi}$. Readers only interested in the definition of the tableau system for LTL model-checking can safely skip it. Only the following theorem, which is proved hand in hand with the definition, is necessary for it. Property (b) is what we win by our new approach: The environment only interferes with the visible transitions of Σ .

Theorem 1 Let Σ be a 1-safe net system whose reachable markings are pairwise incomparable with respect to set inclusion. Let φ be an LTL-X formula over the observable places of Σ . It is possible to construct a net system $\Sigma_{\neg \varphi}$ satisfying the following properties:

- (a) $\Sigma \models \varphi$ iff $\Sigma_{\neg \varphi}$ has neither illegal ω -traces nor illegal livelocks.
- (b) The input and output places of the invisible transitions are the same in Σ and $\Sigma_{\neg \omega}$.

Construction of $\Sigma_{\neg\varphi}$ We describe the synchronization $\Sigma_{\neg\varphi}$ of Σ and $\mathcal{A}_{\neg\varphi}$ in a semiformal but hopefully precise way. Let us start with two preliminaries. First, we identify the Büchi automaton $\mathcal{A}_{\neg\varphi}$ with a net system having a place for each state q, with only the initial state q^0 having a token, and a net transition for each transition (q, x, q'); the input and output places of the transition are q and q', respectively; we keep $\mathcal{A}_{\neg\varphi}$, q and (q, x, q') as names for the net representation, the place and the transition. Second, we split the executions of Σ that violate φ into two classes: executions of type I, which

¹This condition is purely technical. Any 1-safe net system can be easily transformed into an equivalent one satisfying it by adding some extra places and arcs; moreover, the condition can be removed at the price of a less nice theory.

contain infinitely many occurrences of visible transitions, and *executions of type II*, which only contain finitely many. We will deal with these two types separately.

 $\Sigma_{\neg\varphi}$ is constructed in several steps:

- (1) Put Σ and (the net representation of) $\mathcal{A}_{\neg\varphi}$ side by side.
- (2) For each observable place p add a complementary place (see [17]) \overline{p} to Σ

 \overline{p} is marked iff p is not, and so checking that proposition p does not hold is equivalent to checking that the place \overline{p} has a token. A set $x \subseteq \Pi$ can now be seen as a conjunction of literals, where $\overline{p} \in x$ is used to denote $p \in (\Pi \setminus x)$.

- (3) Add new arcs to each transition (q, x, q') of $\mathcal{A}_{\neg \varphi}$ so that it "observes" the places in x.
 - This means that for each literal $p(\overline{p})$ in x we add an arc from $p(\overline{p})$ to (q, x, q') and an arc from (q, x, q') to $p(\overline{p})$. The transition (q, x, q') can only be enabled by markings of Σ satisfying all literals in x.
- (4) Add a scheduler guaranteeing that:
 - Initially $\mathcal{A}_{\neg\varphi}$ can make a move, and all *visible* moves (i.e., the firings of visible transitions) of Σ are disabled.
 - After a move of $\mathcal{A}_{\neg \varphi}$, only Σ can make a move.
 - After Σ makes a visible move, $\mathcal{A}_{\neg\varphi}$ can make a move and until that happens all visible moves of Σ are disabled.

This is achieved by introducing two scheduler places s_f and s_s [22]. The intuition behind these places is that when s_f (s_s) has a token it is the turn of the Büchi automaton (the system Σ) to make a move. In particular, visible transitions transfer a token from s_s to s_f , and Büchi transitions from s_f to s_s . Because the Büchi automaton needs to observe the initial marking of Σ , we initially put one token in s_f and no tokens on s_s .

(5) Let I be a subset of transitions defined as follows. A transition belongs to I iff its postset contains a final state of $\mathcal{A}_{\neg\varphi}$.

Observe that since only moves of $\mathcal{A}_{\neg\varphi}$ and visible moves of Σ are scheduled, invisible moves can still be concurrently executed.

Let $\Sigma'_{\neg\varphi}$ be the net system we have constructed so far. The following is an immediate consequence of the definitions:

 Σ has an execution of type I if and only if $\Sigma'_{\neg\varphi}$ has an illegal $\omega\text{-trace}.$

We now extend the construction in order to deal with executions of type II. Let σ be a type II execution of Σ . Take the sequence of markings reached along the execution of σ , and project it onto the observable places. Since σ only contains finitely many occurrences of visible transitions, the result is a

sequence of the form $O_0^0 O_0^1 \dots O_0^j O_1^0 O_1^1 \dots O_1^k O_2^0 \dots O_n^0 (O_n)^{\omega}$. (The moves from O_i to O_{i+1} are caused by the firing of visible transitions.)

We can split σ into two parts: a finite prefix σ_1 ending with the last occurrence of a visible transition (σ_1 is empty if there are no visible transitions), and an infinite suffix σ_2 containing only invisible transitions. Clearly, the projection onto the observable places of the marking reached by the execution of σ_1 is O_n

Since LTL-X is closed under stuttering, $A_{\neg \varphi}$ has an accepting run

$$r = q_0 \xrightarrow{O_0} q_1 \xrightarrow{O_1} \dots \xrightarrow{O_{n-1}} q_n \xrightarrow{O_n} q_{n+1} \xrightarrow{O_n} q_{n+2} \dots$$

where the notation $q \xrightarrow{O} q'$ means that a transition (q, x, q') is taken such that the literals of x are true at the valuation given by Q. We split this run into two parts: a finite prefix $r_1 = q_0 \xrightarrow{O_0} q_1 \dots q_{n-1} \xrightarrow{O_{n-1}} q_n$ and an infinite suffix $r_2 = q_n \xrightarrow{O_n} q_{n+1} \xrightarrow{O_n} q_{n+2} \dots$

In the net system representation of $\mathcal{A}_{\neg\varphi}$, r_1 and r_2 correspond to occurrence sequences. By construction, the "interleaving" of r_1 and σ_1 yields an occurrence sequence τ_1 of $\Sigma'_{\neg\varphi}$.

Observe that reachable markings of $\Sigma'_{\neg\varphi}$ are of the form (q, s, O, H), meaning that they consist of a token on a state q of $\mathcal{A}_{\neg\varphi}$, a token on one of the places of the scheduler (i.e., $s \in \{s_s, s_f\}$), a marking O of the observable places, and a marking H of the hidden places. Let (q_n, s_f, O_n, H) be the marking of $\Sigma'_{\neg\varphi}$ reached after executing τ_1 . (We have $s = s_f$ because the last transition of σ_1 is visible.) The following property holds: With q_n as initial state, the Büchi automaton $\mathcal{A}_{\neg\varphi}$ accepts the sequence O_n^{ω} . We call any pair (q, O) satisfying this property a checkpoint and define $\Sigma_{\neg\varphi}$ as follows:

(6) For each checkpoint (q, O) and for each reachable marking (q, s_f, O, H) of $\Sigma'_{\neg \varphi}$, add a new transition having all the places marked at (q, s_f, O, H) as preset, and all the places marked at O and H as postset. Let L (for *livelocks*) be this set of transitions.

The reader has possibly observed that the set L can be very large, because there can be many hidden markings H for a given marking O (exponentially many in the size of Σ). Apparently, this makes $\Sigma_{\neg \varphi}$ unsuitable for model-checking. In Sect. 6 we show that this is not the case, because $\Sigma_{\neg \varphi}$ need not be explicitly constructed.

Observe that after firing a L-transition no visible transition can occur anymore, because all visible transitions need a token on s_s for firing. We prove:

 Σ has an execution of type II if and only if $\Sigma_{\neg \varphi}$ has an illegal livelock.

For the only if direction, assume first that σ is a type II execution of Σ . Let τ_1 be the occurrence sequence of $\Sigma_{\neg \varphi}$ defined above (as the "interleaving" of the prefix σ_1 of σ and the prefix r_1 of r). Further, let (q_n, s_f, O_n, H) be the marking reached after the execution of τ_1 , and let t be the transition added in (6) for this marking. Define $\rho_1 = \tau_1$ and $\rho_2 = \sigma_2$. It is easy to show that $\rho_1 t \rho_2$ is an execution of $\Sigma_{\neg \varphi}$ and so an illegal livelock. For the if direction, let $\rho_1 t \rho_2$ be an illegal livelock of $\Sigma_{\neg \varphi}$, where t is an L-transition. After the

firing of t there are no tokens in the places of the scheduler, and so no visible transition can occur again; hence, no visible transition of Σ occurs in ρ_2 . Let σ_1 and σ_2 be the projections of ρ_1 and ρ_2 onto the transitions of Σ . It is easy to see that $\sigma = \sigma_1 \sigma_2$ is an execution of Σ . Since σ_2 does not contain any visible transition, σ is an execution of type II.

4 BASIC DEFINITIONS ON UNFOLDINGS

In this section we briefly introduce the definitions we needed to describe the unfolding approach. More details can be found in [6].

Occurrence nets. Given two nodes x and y of a net, we say that x is causally related to y, denoted by $x \leq y$, if there is a (possibly empty) path of arrows from x to y. We say that x and y are in conflict, denoted by x # y, if there is a place z, different from x and y, from which one can reach x and y, exiting z by different arrows. Finally, we say that x and y are concurrent, denoted by x co y, if neither x < y nor y < x nor x # y hold. A co-set is a set of nodes X such that x co y for every $x, y \in X$. Occurrence nets are those satisfying the following three properties: the net, seen as a directed graph, has no cycles; every place has at most one input transition; and, no node is in self-conflict, i.e., x # x holds for no x. A place of an occurrence net is minimal if it has no input transitions. The net of Fig. 2 is an infinite occurrence net with minimal places a, b. The default initial marking of an occurrence net puts one token on each minimal place an none in the rest.

Branching processes. We associate to Σ a set of *labelled* occurrence nets, called the *branching processes* of Σ . To avoid confusions, we call the places and transitions of branching processes *conditions* and *events*, respectively. The conditions and events of branching processes are labelled with places and transitions of Σ , respectively. The conditions and events of the branching processes are subsets from two sets \mathcal{B} and \mathcal{E} , inductively defined as the smallest sets satisfying the following conditions:

- $\bot \in \mathcal{E}$, where \bot is an special symbol;
- if $e \in \mathcal{E}$, then $(p, e) \in \mathcal{B}$ for every $p \in P$;
- if $\emptyset \subset X \subset \mathcal{B}$, then $(t, X) \in \mathcal{E}$ for every $t \in T$.

In our definitions of branching process (see below) we make consistent use of these names: The label of a condition (p,e) is p, and its unique input event is e. Conditions (p, \perp) have no input event, i.e., the special symbol \perp is used for the minimal places of the occurrence net. Similarly, the label of an event (t, X) is t, and its set of input conditions is X. The advantage of this scheme is that a branching process is completely determined by its sets of conditions and events. We make use of this and represent a branching process as a pair (B, E).

Definition 1 The set of finite branching processes of a net system Σ with the initial marking $M_0 = \{p_1, \dots, p_n\}$ is inductively defined as follows:

- $(\{(p_1, \bot), \ldots, (p_n, \bot)\}, \emptyset)$ is a branching process of Σ .
- If (B, E) is a branching process of Σ , $t \in T$, and $X \subseteq B$ is a coset labelled by •t, then $(B \cup \{(p, e) \mid p \in t^{\bullet}\}, E \cup \{e\})$ is also a branching process of Σ , where e = (t, X). If $e \notin E$, then e is called a possible extension of (B, E).

The set of branching processes of Σ is obtained by declaring that the union of any finite or infinite set of branching processes is also a branching process, where union of branching processes is defined componentwise on conditions and events. Since branching processes are closed under union, there is a unique maximal branching process, called the *unfolding* of Σ . The unfolding of our running example is an infinite occurrence net. Figure 2 shows an initial part. Events and conditions have been assigned identificators that will be used in the examples. For instance, the event $(t_1, \{(p_1, \bot)\})$ is assigned the identificator 1.

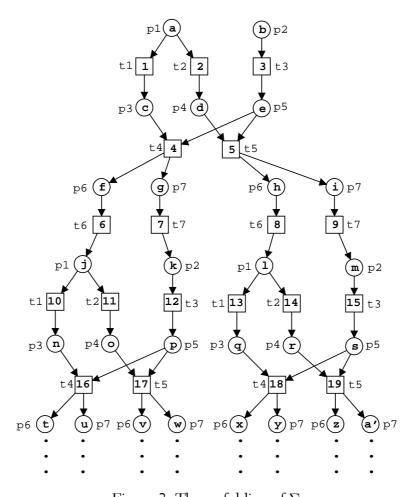


Figure 2: The unfolding of Σ

We take as partial order semantics of Σ its unfolding. This is justified, because it can be easily shown the reachability graphs of Σ and of its unfolding coincide. (Notice that the unfolding of Σ is a *labelled* net system, and so its reachability graph is defined as the *image* under the labelling function of the reachability graph of the *unlabelled* system.)

Configurations. A configuration of an occurrence net is a set of events C satisfying the two following properties: C is causally closed, i.e., if $e \in C$ and e' < e then $e' \in C$, and C is conflict-free, i.e., no two events of C are in conflict. Given an event e, we call $[e] = \{e' \in E \mid e' \leq e\}$ the local configuration of e. Let Min denote the set of minimal places of the branching process. A configuration C of the branching process is associated with a marking of Σ denoted by $Mark(C) = l((Min \cup C^{\bullet}) \setminus {}^{\bullet}C)$. The corresponding set of conditions associated with a configuration is called a cut, and it is defined as $Cut(C) = ((Min \cup C^{\bullet}) \setminus {}^{\bullet}C)$.

In Fig. 2, $\{1,3,4,6\}$ is a configuration, and $\{1,4\}$ (not causally closed) or $\{1,2\}$ (not conflict-free) are not. A set of events is a configuration if and only if there is one or more firing sequences of the occurrence net (from the default initial marking) containing each event from the set exactly once, and no further events. These firing sequences are called *linearisations*. The configuration $\{1,3,4,6\}$ has two linearisations, namely 1346 and 3146. All linearisations lead to the same reachable marking. For example, the two sequences above lead to the marking $\{p_1,p_7\}$. By applying the labelling function to a linearisation we obtain a firing sequence of Σ . Abusing of language, we also call this firing sequence a linearisation. In our example we obtain $t_1t_3t_4t_6$ and $t_3t_1t_4t_6$ as linearisations.

Given a configuration C, we denote by $\uparrow C$ the set of events of the unfolding $\{e \mid e \not\in C \land \forall e' \in C : \neg(e\#e')\}$. Intuitively, $\uparrow C$ corresponds to the behavior of Σ from the marking reached after executing any of the linearisations of C. We call $\uparrow C$ the continuation after C of the unfolding of Σ . If C_1 and C_2 are two finite configurations leading to the same marking, i.e. $Mark(C_1) = M = Mark(C_2)$, then $\uparrow C_1$ and $\uparrow C_2$ are isomorphic, i.e., there is a bijection between them which preserves the labelling of events and the causal, conflict, and concurrency relations (see [6]).

Adequate orders. To implement a net unfolding algorithm we need the notion of adequate order on configurations [6]. Given a configuration C of the unfolding of Σ , we denote by $C \oplus E$ the set $C \cup E$, under the condition that $C \cup E$ is a configuration satisfying $C \cap E = \emptyset$. We say that $C \oplus E$ is an extension of C. Now, let C_1 and C_2 be two finite configurations leading to the same marking. Then $\uparrow C_1$ and $\uparrow C_2$ are isomorphic. This isomorphism, say f, induces a mapping from the extensions of C_1 onto the extensions of C_2 ; the image of $C_1 \oplus E$ under this mapping is $C_2 \oplus f(E)$.

Definition 2 A partial order \prec on the finite configurations of the unfolding of a net system is an adequate order if:

- \prec is well-founded,
- $C_1 \subset C_2$ implies $C_1 \prec C_2$, and
- \prec is preserved by finite extensions; if $C_1 \prec C_2$ and $Mark(C_1) = Mark(C_2)$, then the isomorphism f from above satisfies $C_1 \oplus E \prec C_2 \oplus f(E)$ for all finite extensions $C_1 \oplus E$ of C_1 .

Total adequate orders for 1-safe Petri nets and for synchronous products of transition systems have been presented in [6, 5].

5 TABLEAU SYSTEM

We showed in Section 3 that the model checking problem for LTL-X can be solved by checking the existence of illegal ω -traces and illegal livelocks in $\Sigma_{\neg \varphi}$. In [3] these problems are solved using tableau techniques. A branching process can be seen as a "distributed" tableau, in which conditions are "facts" and events represent "inferences". For two conditions b and b', b co b' models that the facts represented by b and b' can be simultaneously true. A tableau is constructed by adding new events (inferences) one by one following an adequate order; some events are declared as "terminals", and the construction of the tableau terminates when no new event can be added having no terminals among its predecessors.

The tableau systems of [3] require to construct a possibly large set of branching processes. Here we present a new tableau system consisting of one single branching process.²

An Adequate Order for LTL. We simplify the implementation of the tableau system by selecting a special adequate order. We use \prec to denote the total adequate order defined for 1-safe Petri nets in [6]. We call an event corresponding to an L-transition an L-event. We define for a set of events C the function before L-event as $BL(C) = \{e \in C \mid [e] \setminus \{e\} \text{ contains no } L\text{-events}\}$. The function after L-event is defined correspondingly as $AL(C) = (C \setminus BL(C))$. We can now define our new adequate order.

Definition 3 Let C_1 and C_2 be two finite configurations of the unfolding of the product net system $\Sigma_{\neg \varphi}$. $C_1 \prec_{LTL} C_2$ holds if

- $BL(C_1) \prec BL(C_2)$, or
- $BL(C_1) = BL(C_2)$ and $C_1 \prec C_2$.

The adequate order \prec_{LTL} is application specific in the sense that it is not an adequate order for an arbitrary net system Σ , but needs some special properties of the net system $\Sigma_{\neg \varphi}$. We have the following result.

Theorem 2 The order \prec_{LTL} is a total adequate order for finite configurations of the unfolding of $\Sigma_{\neg \varphi}$.

Proof:

See Appendix A for the proof.

New Tableau System. We first divide the unfolding of $\Sigma_{\neg \varphi}$ into two disjoint sets of events. Intuitively, the first set is used for the ω -trace detection part, and the second for the illegal livelock detection part. We define *part-II* to be the set of events e such that [e] does not contain an L-event and part-II as the set of events which are not in part-II.

5 TABLEAU SYSTEM 10

²For the reader familiar with [3]: the *L*-transitions in the net system $\Sigma_{\neg\varphi}$ act as glue to connect a set of branching processes (the tableau components of [3]) together into one larger tableau.

Definition 4 An event e of the unfolding $\Sigma_{\neg \varphi}$ is a terminal, if there exists another event e' such that Mark([e']) = Mark([e]), $[e'] \prec_{LTL} [e]$, and one of the following two mutually exclusive cases holds:

- (I) $e \in \text{part-I}$, and either
 - (a) e' < e, or
 - (b) $\neg (e' < e)$ and $\#_I[e'] \ge \#_I[e]$, where $\#_I C$ denotes the number of *I*-events in *C*.
- (II) $e \in \text{part-II}$, and either
 - (a) $BL([e']) \prec_{LTL} BL([e])$, or
 - (b) BL([e']) = BL([e]) and $\neg (e' \# e)$, or
 - (c) $BL([e']) = BL([e]), e' \# e, \text{ and } |[e']| \ge |[e]|.$

A tableau \mathcal{T} is a branching process (B, E) of $\Sigma_{\neg \varphi}$ such that for every possible extension e of (B, E) at least one of the immediate predecessors of e is a terminal. A terminal is successful if it is type (I)(a) and $[e] \setminus [e']$ contains an I-event, or it is of type (II)(b). All other terminals are unsuccessful. A tableau \mathcal{T} is successful if it contains a successful terminal, otherwise it is unsuccessful.

Loosely speaking, a tableau is a branching process which cannot be extended without adding a causal successor to a terminal.

We have the following result:

Theorem 3 Let \mathcal{T} be a tableau for $\Sigma_{\neg \varphi}$.

- $\Sigma_{\neg \varphi}$ has an illegal ω -trace iff \mathcal{T} has a successful terminal of type I.
- $\Sigma_{\neg \varphi}$ has an illegal livelock iff \mathcal{T} has a successful terminal of type II.
- \mathcal{T} contains at most K^2 non-terminal events, where K is the number of reachable markings of $\Sigma_{\neg \varphi}$.

Proof:

See Appendix A for the proof.

6 GENERATING THE TABLEAU

We describe an implementation of the tableau system of Sect. 5. The main goal is to keep the tableau generation as similar as possible to a conventional prefix generation algorithm [6]. In this way any prefix generation algorithm can be easily adapted to also perform LTL model checking.

The tableau generation algorithm (Algorithm 1) is almost identical to the main routine of a prefix generation algorithm. The changes are: an additional block of code devoted to generating the *L*-events dynamically; a different but easy to implement adequate order; a new cut-off detection subroutine. The main feature of the implementation is the efficient handling of *L*-transitions, which we discuss next.

Generating the L-transitions Dynamically. Recall that in the synchronization $\Sigma_{\neg \varphi}$ we can for each Büchi state q have as many L-transitions as there are reachable markings of the form (q, s_f, O, H) in the net system $\Sigma_{\neg \varphi}$. Clearly we can not explicitly generate them all due to efficiency reasons. Instead we generate a net system $\Sigma_{\neg \varphi}^s$ (s stands for static) in which this set of L-transitions (added by step (6) of the synchronization procedure in Section 3) is replaced by:

(6') Add for each Büchi transition t = (q, x, q') in the net system $\Sigma'_{\neg \varphi}$ (i.e., the synchronization after steps (1)-(5) as defined in Sect. 3) a new transition t'. The preset of t' is equivalent to the preset of t and the postset of t' is empty. Let L (for *livelocks*) be this set of transitions.

We can now dynamically generate any of the (enabled) L-transitions of $\Sigma_{\neg\varphi}$. Namely, for a transition t corresponding to a reachable marking $M=(q,s_f,O,H)$ to be enabled in $\Sigma_{\neg\varphi}$, a transition t' (for some (q,x,q')) must be enabled in $\Sigma_{\neg\varphi}^s$ and the Büchi automaton must accept O^ω when q is given as the initial state. Loosely speaking we test the first label of the sequence using the transition t', and if this test succeeds we check whether O can be infinitely stuttered. (Using this construction it is easy to implement "no-care values" for selected atomic propositions by leaving them out of the preset of t'.) Now generating the postset of t from t' is trivial.

Optimizations in Dynamic Creation. We can thus dynamically generate L-transitions for each reachable marking M as required. However, we can do better by using the net unfolding method. The main idea is to generate the unfolding of $\Sigma_{\neg \varphi}$ by using $\Sigma_{\neg \varphi}^s$ to find "candidate" L-events. Assume we have found an event e^s corresponding to a transition t' in the unfolding of $\Sigma_{\neg \omega}^s$ and the stuttering check described above passes for the marking $M = Mark([e^s])$. Then we add an event e into the unfolding of $\Sigma_{\neg \varphi}$ corresponding to the effect of the transition t in the marking M. If we would directly use the construction above we would also add an event e' to the unfolding of $\Sigma_{\neg \varphi}$ for each marking $M' = (q, s_f, O, H')$ which is reachable from M using only invisible transitions. We now show that adding only the event e suffices: Let E be an extension of [e]. If there is an illegal livelock starting from $M' = Mark([e] \oplus E)$ then there is also an illegal livelock starting from M. This can be easily seen to be the case because all extensions E contain only invisible events and thus the set of observable places in both M and M'is O. Algorithm 1 uses the property described above to add the required Levents dynamically. Another optimization used is the fact that only the places in the presets of invisible transitions (denoted *InvisPre*) need to be added to the postset of an L-transition.

Algorithm 2 is the cut-off detection subroutine. It handles events in *part-II* and *part-II* differently. This is one example implementation, and it closely follows the definition of the tableau. It sets the global boolean variable *success* to *true* and calls the counterexample generation subroutine (Algorithm 3) if it finds a counterexample.

The implementation of the check whether $\mathcal{A}_{\neg\varphi}^q$ accepts O^{ω} in Algorithm 1 can be done in linear time in the size of the automaton $\mathcal{A}_{\neg\varphi}$ as follows. First restrict $\mathcal{A}_{\neg\varphi}$ to transitions satisfying O, and then use a linear time emptiness

checking algorithm (see e.g. [2]) to check whether an accepting loop can be reached starting from q in this restricted automaton. Because $\mathcal{A}_{\neg\varphi}$ is usually quite small compared to the size of the model checked system this should not be a limiting factor. Caching of these check results can also be used if necessary.

The adequate order \prec_{LTL} can also be quite efficiently implemented. We can prove that if a configuration C contains an L-event e, then BL(C) = [e]. Now it is also the case that each configuration only includes at most one L-event. By using these two facts a simple and efficient implementation can be devised.

Each time our algorithm adds a non-terminal L-event, it first finds out whether a livelock counterexample can be generated from its future. Only if no counterexample is found, it continues to look for illegal ω -traces and further L-events. Thus we use the adequate order \prec_{LTL} to force a search order similar to that used by Valmari in [19] which detects divergence counterexamples in interleaved state spaces. However, our algorithm is "breadth-first style" and it also does illegal ω -trace detection, a part which is not included in [19].

Algorithm 1 The tableau generation algorithm

```
input: The product net system \Sigma_{\neg \varphi}^s = (P, T, F, M_0), where M_0 = \{p_1, \dots, p_n\}.
output: true if there is a counterexample, false otherwise.
global variables: success
begin
Fin := \{(p_1, \bot), \ldots, (p_n, \bot)\};
cut-off := \emptyset;
pe := PE(Fin); /* Compute the set of possible extensions */
success := false;
while pe \neq \emptyset and success = false do
  choose an event e = (t, X) in pe such that [e] is minimal
  with respect to \prec_{LTL};
  Y := t^{\bullet}; /* Remember the postset of t^*/
  /* Create the required L-events dynamically */
  if t is a L-transition then
    M := Mark([e] \setminus \{e\}); /* The marking M = (q, s_f, O, H) */
    q := M \cap Q; /* Extract the Büchi state q */
    /* (Büchi emptiness checking algorithm can be used here) */
    if \mathcal{A}^q_{\neg \varphi} = (\Gamma, Q, q, \rho, F) does not accept O^\omega then
      continue; /* Discard e because (q, O) is not a checkpoint */
    endif
    X := Cut([e] \setminus \{e\}); /* Extend the preset to also remove tokens from H */
    e := (t, X); /* Rename e (i.e., add arcs from all preset conditions to e) */
    Y := (M \cap InvisPre); /* Project M on invisible transition presets */
  endif
  if [e] \cap cut-off = \emptyset then
    append to Fin the event e and a condition (p, e)
      for every place p \in Y;
    pe := PE(Fin); /* Compute the set of possible extensions */
    if is \ cutoff(e) then
      cut-off := cut-off \cup \{e\};
    endif
  else
    pe := pe \setminus \{e\};
  endif
enddo
return success;
end
```

Algorithm 2 The is_cutoff subroutine

```
input: An event e.
output: true if e is a terminal of the tableau, false otherwise.
begin
foreach e' such that Mark([e']) = Mark([e]) do /^* [e'] \prec_{LTL} [e] holds */
  if e \in part-I then /* case (I) */
    if e' < e then
      if [e] \setminus [e'] contains an I-event then
        success := true; /* Counterexample found! */
        counterexample(e, e');
      endif
      return true;
    else if \#_I[e'] \ge \#_I[e] then
      return true;
    endif
  else /* case (II) */
    if BL([e']) \prec_{LTL} BL([e]) then
      return true;
    else if \neg (e' \# e) then /^* BL([e']) = BL([e]) holds */
      success := true; /* Counterexample found! */
      counterexample(e, e');
      return true;
    else if |[e']| \ge |[e]| then /* BL([e']) = BL([e]) holds */
      return true;
    endif
  endif
enddo
return false;
end
```

Algorithm 3 The counterexample subroutine

```
input: A successful event e with the corresponding event e'. begin C_1 := [e] \cap [e']; C_2 := [e] \setminus C_1; /* C_1 contains the prefix and C_2 the accepting loop */ print\_linearisation(C_1); print\_linearisation(C_2); end
```

7 EXPERIMENTAL RESULTS

We have implemented a prototype of the LTL model checking procedure called *unfsmodels*. We use the SPIN tool [12] version 3.4.3 to generate the Büchi automaton $\mathcal{A}_{\neg\varphi}$ and a tool by F. Wallner [22] to generate the synchronization $\Sigma'_{\neg\varphi}$ which is given to the prototype tool as input.

The *smodels* tool [18] is used to calculate the set of possible extensions of a branching process. It is a NP-solver which uses logic programs with stable model semantics as the input language. Calculating the possible extensions is a quite demanding combinatorial problem. Actually a decision version of the problem can be show to be NP-complete in the general case [10]. However if the maximum preset size of the transitions $| ^{\bullet}t |$ is bounded the problem becomes polynomial [7]. (The problem is closely related to the *clique* problem which has a similar characteristic, for a longer discussion see [7].)

We chose to use *smodels* to solve this combinatorial problem instead of implementing a dedicated algorithm. That choice allowed us to concentrate on other parts of the implementation. The translation employs constructs similar to those presented for the submarking reachability problem in [11], however it differs in several technical details. The translation is linear in the sizes of both the net and the prefix, however we will not present it here due to space restrictions.

For benchmarks we used a set of LTL model checking examples collected by C. Schröter. The experimental results are collected in Fig. 3. The 1-safe net systems used in the experiments are as follows:

- BRUIJN(2), DIJKST(2), and KNUTH(2): Mutex algorithms modeled by S. Melzer.
- BYZA4_0B and BYZA4_0B: Byzantine agreement algorithm versions modeled by S. Merkel [16].
- RW1W1R, RW1W3R and RW2W1R: Readers and writers synchronization modeled by S. Melzer and S. Römer [15].
- PLATE(5): A production cell example from [13], modeled by M. Heiner and P. Deussen [9].
- EBAHN: A train model by K. Schmidt.
- ELEV(3) and ELEV(4): Elevator models by J. C. Corbett [1], converted to nets by S. Melzer and S. Römer [15].
- RRR(xx): Dining philosophers with xx philosophers, modeled by C. Schröter.

The reported running times only include *unfsmodels* 0.9 running times, as the Büchi automata generation and the synchronization with the original net system took insignificant amount of time. All the running times are reported as the sum of system and user times as reported by the /usr/bin/time command when run on a PC with an AMD Athlon 1GHz processor, 512MB

7 EXPERIMENTAL RESULTS 16

RAM, using *gcc* 2.95.2 and Linux 2.2.17. The times are all averaged over 5 runs.

The unfsmodels tool in an on-the-fly tool in the sense that it stops the prefix (tableau) generation if it finds a counterexample during the unfolding. The reported prefix sizes in this case are the partial prefix at the time the counterexample was found. The tool can also be instructed to generate a conventional prefix using the prefix generation algorithm described in [6] for comparison.

Problem	B_{LTL}	E_{LTL}	c_{LTL}	С	B_{Fin}	E_{Fin}	\mathfrak{c}_{Fin}	States	S_{LTL}	S_{Fin}
BRUIJN(2)	2874	1336	327	N	2676	1269	318	5183	13.1	11.0
DIJKST(2)	1856	968	230	N	1700	921	228	2724	4.8	3.8
KNUTH(2)	2234	1044	251	N	2117	1009	251	4483	7.1	6.1
BYZA4_0B	1642	590	82	N	1630	587	82	>2000000	7.0	6.9
BYZA4_2A	401	125	4	N	396	124	4	>2500000	0.3	0.3
RW1W1R	568	296	32	N	563	295	32	2118	0.5	0.5
RW1W3R	28143	15402	5210	N	28138	15401	5210	165272	1863.4	1862.2
RW2W1R	18280	9242	1334	N	18275	9241	1334	127132	1109.6	1108.2
PLATE(5)	1803	810	12	N	1619	768	12	16572 4 2	14.0	11.8
EBAHN	151	62	21	Y	1419	673	383	7776	0.0	0.7
ELEV(3)	124	64	10	Y	7398	3895	1629	7276	0.1	91.7
ELEV(4)	154	80	13	Y	32354	16935	7337	48217	0.1	1706.2
RRR(10)	88	42	5	Y	85	45	19	14985	0.0	0.0
RRR(20)	167	81	8	Y	161	81	32	>10000000	0.1	0.0
RRR(30)	240	114	9	Y	230	110	41	>10000000	0.2	0.1
RRR(50)	407	201	18	Y	388	188	70	>10000000	0.7	0.5

Figure 3: Experimental results.

In Fig. 3 the columns of the table have the following meanings:

- Problem: The name of the problem with the size of the instance.
- B_{LTL} , E_{LTL} , and c_{LTL} : The number of conditions, events, and the number of events which are terminals in the LTL prefix, respectively.
- C: N There was no counterexample, the formula holds. Y There was a counterexample, the formula does not hold.
- B_{Fin} , E_{Fin} , and c_{Fin} : The size of different parts of the finite complete prefix as above but for the original net system Σ using the conventional prefix generation algorithm described in [6].
- States: The number of states n in the reachability graph of the original net system Σ obtained using the PROD tool [21], or a lower bound > n.
- S_{LTL} : The time used by *unfsmodels* in seconds needed to find a counterexample or to show that there is none.
- S_{Fin} : The time used by *unfsmodels* in seconds needed to generate a finite complete prefix of the original net system Σ .

At this point there are a couple of observations to be made. First of all, on this set of example nets and formulas, the speed of computing a LTL prefix is almost identical to the speed of computing a conventional prefix (of comparable size). The main reason for this is that the time needed to compute the

7 EXPERIMENTAL RESULTS 17

possible extensions dominates the computation time in our prototype. Thus the (slightly) more complicated algorithm needed for the cut-off detection do not contribute in a major way to the running time of the tool. Secondly, on all of the experiments, the size of the LTL prefix is of the same order of magnitude as the conventional prefix. Thus in this set of examples the quadratic worst-case blow-up (possible according to Theorem 3) does not materialize. We expect this to be the case also in other examples when the used LTL formulas are short and the properties to be checked are local, in the sense that the product net system preserves most of the concurrency present in the original net system.

Problem	B_I	E_I	c_I	B_{II}	E_{II}	c_{II}	Cpt	Formula type
BRUIJN(2)	2874	1336	327	0	0	0	0	$\Box \neg (p_1 \land p_2)$
DIJKST(2)	1856	968	230	0	0	0	0	$\Box \neg (p_1 \wedge p_2)$
KNUTH(2)	2234	1044	251	0	0	0	0	$\Box \neg (p_1 \wedge p_2)$
BYZA4_0B	1642	590	82	0	0	0	0	$\Box(p_1 \to \Diamond p_2)$
BYZA4_2A	401	125	4	0	0	0	0	$\Box(p_1 \to \Diamond p_2)$
RW1W1R	568	296	32	0	0	0	0	$\Box(p_1 \to \Diamond p_2)$
RW1W3R	28143	15402	5210	0	0	0	0	$\Box(p_1 \to \Diamond p_2)$
RW2W1R	18280	9242	1334	0	0	0	0	$\Box(p_1 \to \Diamond p_2)$
PLATE(5)	1803	810	12	0	0	0	0	$\Box((p_1 \land \neg p_2 \land \neg p_3) \lor$
								$(\neg p_1 \wedge p_2 \wedge \neg p_3) \vee$
								$(\neg p_1 \wedge \neg p_2 \wedge p_3))$
EBAHN	113	48	20	38	14	1	l	$\Box \neg (p_1 \land p_2)$
ELEV(3)	22	10	0	102	54	10	1	$\Box(p_1 \to \Diamond p_2)$
ELEV(4)	25	12	0	129	68	13	l	$\Box(p_1 \to \Diamond p_2)$
RRR(10)	40	14	0	48	28	5	1	$\Box(p_1 \to \Diamond p_2)$
RRR(20)	73	27	0	94	54	8	1	$\Box(p_1 \to \Diamond p_2)$
RRR(30)	104	38	0	136	76	9	l	$\Box(p_1 \to \Diamond p_2)$
RRR(50)	173	67	0	234	134	18	1	$\Box(p_1\to\Diamond p_2)$

Figure 4: Detailed LTL tableau statistics.

In Fig. 4 a detailed breakdown of the different components of the LTL prefix is given. The subscripts I and II denote the part of the prefix used for ω -trace and livelock checking, respectively (i.e., events in part-I and part-II). Column Cpt contains the number of checkpoints, i.e. how many of the L-events are checkpoints. Finally Formula type gives the type of the formula being checked.

In Fig. 4 we can also see that in the cases a counterexample was found it was found after only a small amount of the prefix was generated. Actually in all the experiments the counterexample was a livelock counterexample, and the livelock was found from the first checkpoint found during the prefix generation. This allowed the LTL model checking procedure to terminate quite early with a counterexample in many case, see e.g. the ELEV(4) example.

The net systems used in experiments and unfsmodels 0.9 are available at http://www.tcs.hut.fi/kepa/experiments/spin2001/>.

8 CONCLUSIONS

We have presented an implementation of the tableau system of [3]. We have been able to merge the possibly large set of tableaux of [3] into a single one. In this way, the algorithm for model checking LTL with unfoldings remains conceptually similar to the algorithms used to generate prefixes of the unfold-

8 CONCLUSIONS 18

ing containing all reachable states [6, 5]: We just need more sophisticated adequate orders and cut-off events.

The division of the tableau into *part-II* and *part-II* events is the price to pay for a partial-order approach to model checking. Other partial-order techniques, like the one introduced by Valmari [19], also require a special treatment of divergences or livelocks. ³ We have shown that the conditions for checking if *part-II* or *part-II* events are terminals remain very simple.

In our tableau system the size of a tableau may grow quadratically in the number of reachable states of the system. We have not been able to construct an example showing that this bound can be reached, although it probably exists. In all experiments conducted so far the number of events of the tableau is always smaller than the number of reachable states. In examples with a high degree of concurrency we obtain exponential compression factors.

The prototype implementation was created mainly for investigating the sizes of the generated tableau. Implementing this procedure in a high performance prefix generator such as the one described in [5] is left for further work.

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REFERENCES 21

9 APPENDIX A - PROOFS OF THEOREMS

We start with a lemma proving some additional properties of $\Sigma_{\neg \varphi}$.

Lemma 1 Let $\Sigma_{\neg\varphi}$ be the net system defined through steps (1)-(6) in Section 3. On top of (a) and (b) in Theorem 1 $\Sigma_{\neg\varphi}$ also satisfies the following properties:

- (c) No reachable marking of $\Sigma_{\neg \varphi}$ concurrently enables two different *I*-transitions.
- (d) If a reachable marking of $\Sigma_{\neg \varphi}$ concurrently enables two different transitions, then none of them is an L-transition.
- (e) After firing an L-transition all transitions in the sets L, V, and I stay disabled.
- (f) If M is a marking reached without firing any L-transitions, and M' is a marking reached after firing some L-transitions, then $M \neq M'$.

Proof:

- (c) No reachable marking of $\Sigma_{\neg \varphi}$ concurrently enables two different *I*-transitions. Just observe that all *I*-transitions have the place s_f in their preset.
- (d) If a reachable marking of $\Sigma_{\neg \varphi}$ concurrently enables two different transitions, then none of them is a L-transition. Let (q, s, O, H) be a reachable marking that concurrently enables an L-transition t and another transition u. Since the preset of t is also a reachable marking (q, s_f, O, H) , we have $q = q, s = s_f, O \subseteq O$, and $H \subseteq H$. Since all reachable markings of Σ are pairwise incomparable and (O, H), (O, H) are reachable markings of Σ , we have O = O and O = H. Since O = H is enabled at O = H and O = H is enabled at O = H and O = H is enabled at O = H and O = H are not concurrently enabled.
- (e) After firing an L-transition all transitions in the sets L, V, and I stay disabled forever.Is immediate from the fact that L-transitions do not put tokens on any scheduling places, and a scheduling place is in the preset of all L, V, and I-transitions.
- (f) Let M be a marking reached without firing any L-transitions, and M' be a marking reached after firing some L-transitions. Then it holds that $M \neq M'$.
 - After an *L*-transition has fired both scheduling places will stay empty, and before firing it exactly one of them contains a token.

Proof of Theorem 2

We use the Lemma 1(d),(f) above in this proof.

The totality follows directly from the fact that \prec is a total order. It is easy to see that \prec_{LTL} is well founded. Also it it easy to see from the definition that $C_1 \subset C_2$ implies $C_1 \prec_{LTL} C_2$ because this property holds for the \prec order. We now want to prove that \prec_{LTL} is preserved by finite extensions. We proceed by showing the claim for extension by a single event $E = \{e\}$, the full claim will follow by induction. We have now two cases:

- (1) C_1 does not contain an L-event: Now $Mark(C_1) = Mark(C_2)$ implies that C_2 does not contain an L-event either (Lemma 1 (f)). Thus $BL(C_1) = C_1$, $BL(C_2) = C_2$, $BL(C_1 \oplus E) = C_1 \oplus E$, and $BL(C_2 \oplus f(E)) = C_2 \oplus f(E)$, and we obtain the result from the fact that \prec is preserved by finite extensions.
- (2) C_1 contains an L-event: Now $Mark(C_1) = Mark(C_2)$ implies that C_2 also contains an L-event. Thus $BL(C_1 \oplus E) = BL(C_1)$ because L-events are not concurrent with any other events (Lemma 1 (d)). By the same reasoning $BL(C_2 \oplus f(E)) = BL(C_2)$. We us this result in a simple case analysis of the \prec_{LTL} definition:
 - (a) $BL(C_1) \prec BL(C_2)$: We get $BL(C_1 \oplus E) \prec BL(C_2 \oplus f(E))$, and thus $C_1 \oplus E \prec_{LTL} C_2 \oplus f(E)$.
 - (b) $BL(C_1) = BL(C_2)$ and $C_1 \prec C_2$: Now it holds that $BL(C_1 \oplus E) = BL(C_2 \oplus f(E))$ and $C_1 \oplus E \prec C_2 \oplus f(E)$. Therefore $C_1 \oplus E \prec_{LTL} C_2 \oplus f(E)$.

Proof of Theorem 3

The proofs strategies here are similar to those in [3, 4]. However, technical details differ enough that those proofs cannot be directly used here. Thus a self-contained proof is given.

We split Theorem 3 into five results contained in Theorem 4-Theorem 8.

Soundness and completeness for illegal ω -traces

Theorem 4 If \mathcal{T} contains a successful terminal of type I, then $\Sigma_{\neg \varphi}$ has an illegal ω -trace.

Proof:

Let e be a successful terminal of \mathcal{T} of type I with companion e'. In particular, e' < e, and so $[e'] \subset [e]$. Let $M_0 \stackrel{\sigma}{\longrightarrow} M_1 \stackrel{\sigma_1}{\longrightarrow} M_2$ be a firing sequence of $\Sigma_{\neg \varphi}$ such that σ and $\sigma \sigma_1$ are linearisations of [e'] and [e], respectively. Since Mark([e']) = Mark([e]), we have $M_1 = M_2$. Since $[e] \setminus [e']$ contains some I-event, $M_0 \stackrel{\sigma}{\longrightarrow} M_1 \stackrel{\sigma_1^{\omega}}{\longrightarrow}$ is an infinite firing sequence of $\Sigma_{\neg \varphi}$ containing infinitely many occurrences of transitions of I.

The proof of completeness is a bit more involved. We need a preliminary definition and a lemma.

Definition 5 A configuration C of the unfolding of $\Sigma_{\neg \varphi}$ is bad if it contains at least K+1 I-events, where K is the number of reachable markings of $\Sigma_{\neg \varphi}$.

- **Lemma 2** (1) $\Sigma_{\neg \varphi}$ has an illegal ω -trace if and only if its unfolding contains a bad configuration.
 - (2) A bad configuration contains at least one successful terminal of type I. (More precisely, if a branching process of $\Sigma_{\neg \varphi}$ contains a bad configuration, then some event of this configuration is a terminal.)

Proof:

- (1) (\Rightarrow): Let $M_0 \xrightarrow{\sigma} M$ be a prefix of an illegal ω -trace such that σ contains K+1 occurrences of I-transitions. There exists a configuration of the unfolding of $\Sigma_{\neg \varphi}$ such that σ is a linearisation of C. This configuration is bad.
- (1) (\Leftarrow): Let C be a bad configuration. C contains at least K+1 I-events. By Lemma 1(c), these events are causally ordered, and so by the pigeonhole principle two of them e' < e satisfy Mark([e']) = Mark([e]). Let $M_0 \xrightarrow{\sigma_1} M_1 \xrightarrow{\sigma_2} M_2$ be a linearisation of [e] such that σ_1 is a linearisation of [e']. Then $M_1 = M_2$, and so $\sigma_1 \sigma_2^{\omega}$ is an illegal ω -trace.
 - (2) Event e in the proof of (1) (\Leftarrow) is a successful terminal of type I. \Box

Theorem 5 If $\Sigma_{\neg \varphi}$ has an illegal ω -trace then \mathcal{T} has a successful terminal of type I.

Proof:

By Lemma 2(1), it suffices to show that if the unfolding of $\Sigma_{\neg \varphi}$ contains a bad configuration, then \mathcal{T} has a successful terminal of type I.

We prove that, given a bad configuration C of the unfolding of $\Sigma_{\neg \varphi}$, either C contains a type I successful terminal of \mathcal{T} (and so \mathcal{T} itself contains a type I successful terminal), or there exists another bad configuration C' such that $C' \prec_{LTL} C$. Since \prec_{LTL} is well founded (see Definition 2), \mathcal{T} contains a type I successful terminal.

By Lemma 2(2), C contains a successful terminal e of type I. If e belongs to \mathcal{T} , then we are done. Otherwise, C must contain an unsuccessful terminal d < e. Since e is of type I so is d. We have $C = [d] \oplus (C \setminus [d])$. Let d' be the companion of d, and let f be an isomorphism between $\uparrow [d]$ and $\uparrow [d']$. Define $C' = [d'] \oplus f(C \setminus [d])$. We prove that C' is a bad configuration satisfying $C' \prec_{LTL} C$.

We consider two cases, corresponding to the two possibilities for a terminal of type I to be unsuccessful:

(a) d' < d, and $[d] \setminus [d']$ contains no *I*-event.

In this case we have $[d'] \subset [d]$. By the second condition in the definition of an adequate order, we have $[d'] \prec_{LTL} [d]$. By the third condition of the same definition, we have $C' \prec_{LTL} C$.

It remains to prove that C' is bad. We show that C and C' contain the same number of I-events. Since $[d] \setminus [d']$ contains no I-event, we have $\#_I[d'] = \#_I[d]$. Since isomorphisms preserve labelling, we have $\#_I(C' \setminus [d']) = \#_I(C \setminus [d])$. So $\#_IC' = \#_IC$.

(b) $[d'] \prec_{LTL} [d]$ and $\#_I[d'] \ge \#_I[d]$.

Since $[d'] \prec_{LTL} [d]$, we have $C' \prec_{LTL} C$ by the third condition in the definition of an adequate order. It remains to prove that C' is bad. We show that C' contains at least as many I-events as C. We have $\#_I[d'] \geq \#_I[d]$ by assumption. Since isomorphisms preserve labelling, we also have $\#_I(C' \setminus [d']) = \#_I(C \setminus [d])$. So $\#_IC' \geq \#_IC$.

Soundness for illegal livelocks

We start with some simple observations following directly from the definitions.

Lemma 3 Let *C* be a configuration.

- (1) BL(C) contains at most one L-event. If BL(C) contains one L-event, then this event is the unique maximal event of BL(C).
- (2) All events of AL(C) are invisible.
- (3) If some linearisation of C is an illegal livelock $M_0 \xrightarrow{\sigma} M \xrightarrow{\tau}$, then σ is a linearisation of BL(C).

Proof:

- (1) By the definition of BL, all L-events of BL(C) are maximal events of BL(C). Since L-transitions are never concurrently enabled with any other transition (Lemma 1(d)), BL(C), the set of maximal events of BL(C) either contains no L-events, or it consists of exactly one L-event.
- (2) Follows easily from the definition of AL and Lemma 1(e).
- (3) Since the last transition of σ is a L-transition, C contains one L-event. By
- (1), this is the unique maximal event of BL(C).

The following lemma is also a preliminary.

Lemma 4 Let C_1, C_2 be configurations of the unfolding of a 1-safe net system Σ such that $C_1 \cup C_2$ is a configuration, and $Mark(C_1) = M = Mark(C_2)$. Then $Mark(C_1 \cap C_2) = M$.

Proof:

Let c_1, c_2, c_{12} be the cuts corresponding to C_1, C_2 , and $C_1 \cap C_2$, respectively.

(1) If $p \in M$, then $p \in Mark(C_1 \cap C_2)$.

Since $p \in M$, there exist $b_1 \in c_1$, $b_2 \in c_2$ such that $l(b_1) = p = l(b_2)$. Since Σ is 1-safe, b_1 and b_2 cannot be concurrent. Since $C_1 \cup C_2$ is a configuration, they must be causally related. Assume without loss of generality that $b_1 \leq b_2$. Then $b_1 \in c_{12}$, and so $p \in Mark(C_1 \cap C_2)$.

(2) If $p \in Mark(C_1 \cap C_2)$, then $p \in M$.

Since $p \in Mark(C_1 \cap C_2)$, there exists $b \in c_{12}$ such that l(b) = p. Then $b \in c_1 \cup c_2$, and so $p \in Mark(C_1)$ or $p \in Mark(C_2)$. Since $Mark(C_1) = M = Mark(C_2)$, we have $p \in M$.

We can now prove the soundness of the tableau for illegal livelocks.

Theorem 6 If \mathcal{T} contains a successful terminal of type II, then $\Sigma_{\neg \varphi}$ contains an illegal livelock.

Proof:

Let e be the successful terminal and let e' be its companion. Since e is of type II(b) we have BL([e']) = BL([e]), and so e' is a part-II event. Let $M_0 \xrightarrow{\sigma_1} M_1 \xrightarrow{\sigma_2} M_2 \xrightarrow{\sigma_3} M_3$ be a linearisation of [e] such that σ_1 is a linearisation of BL([e]), and $\sigma_1\sigma_2$ is a linearisation of $[e] \cap [e']$. (Notice that σ_2 is a non-empty sequence.) By Lemma 3(1), the last transition of σ_1 belongs to e. Since e0 (e'#e0), $[e] \cup [e']$ is a configuration and so, by Lemma 4, e1, e2 (e3) and e3 is a linearisation of e4. Since e5 and e6 is a linearisation of e8, e9 and e9 are e9. Since e9 and e9 are contains only invisible transitions (Lemma 3(2)). So e9 and e9 are e9 are in a linearisation of e9 and e9 are e9. So e9 are in a linearisation of e9 and e9 are e9. Since e9 are e9 and e9 are e9 are e9 are e9 are e9 and e9 are e9 are e9 are e9 are e9 are e9 are e9 and e9 are e9 are e9 are e9 are e9 and e9 are e9 and e9 are e9

Completeness for the illegal livelocks

The completeness proof uses the following notion:

Definition 6 A configuration C is a L-configuration if $BL(C) \neq \emptyset$ and AL(C) contains at least K+1 events, where K is the number of reachable markings of $\Sigma_{\neg \varphi}$.

Loosely speaking, the following lemma shows that L-configurations are finite witnesses of the existence of illegal livelocks.

Lemma 5 $\Sigma_{\neg \varphi}$ has an illegal livelock $M_0 \xrightarrow{\sigma} M \xrightarrow{\tau}$ if and only if its unfolding contains a *L*-configuration *C* such that σ is a linearisation of BL(C).

Proof:

 (\Rightarrow) : Let $M_0 \xrightarrow{\sigma} M \xrightarrow{\tau}$ be a livelock of $\Sigma_{\neg \varphi}$, i.e.,

- the last transition of σ belongs to L, and
- τ is an execution containing only invisible transitions.

Let C be an (infinite) configuration of the unfolding of $\Sigma_{\neg \varphi}$ such that $\sigma \tau$ is one of its linearisations. By Lemma 3(3), σ is a linearisation of BL(C). Since C is infinite, AL(C) contains infinitely many events. Let $BL(C) \oplus E$ be an extension of BL(C) such that E contains K+1 events; $BL(C) \oplus E$ is a L-configuration.

(\Leftarrow): Let C be a L-configuration, and let $M_0 \xrightarrow{\sigma_1} M_1$ be a linearisation of BL(C). By Lemma 3(1), the last transition of σ_1 is labelled by a transition of L. We construct an execution $M_1 \xrightarrow{\sigma_2 \sigma_3^\omega}$ of invisible transitions, which implies that $M_0 \xrightarrow{\sigma} M_1 \xrightarrow{\sigma_2 \sigma_3^\omega}$ is an illegal livelock. Since AL(C) contains at least K+1 events, there exist two events $e', e \in AL(C)$ such that Mark(e') = Mark(e). Let $M_0 \xrightarrow{\sigma_1} M_1 \xrightarrow{\sigma_2} M_2 \xrightarrow{\sigma_3} M_3$ be a linearisation of [e] such that $M_0 \xrightarrow{\sigma_1} M_1 \xrightarrow{\sigma_2} M_2$ is a linearisation of $[e] \cap [e']$. By Lemma 4 we have $M_2 = M_3$, and so $M_0 \xrightarrow{\sigma_1} M_1 \xrightarrow{\sigma_2 \sigma_3^\omega}$ is an execution; since, by Lemma 3(2), σ_3 only contains invisible transitions, this execution is an illegal livelock.

Loosely speaking, our next lemma shows that *L*-configurations lead to terminals in the tableau system.

Lemma 6 Every L-configuration contains a successful terminal of type II.

Proof:

Since AL(C) contains at least K+1 events, there exist two events $e', e \in AL(C)$ such that Mark(e') = Mark(e). Since $e', e \in AL(C)$, BL([e']) = BL(C) = BL([e]). Without loss of generality we assume $e' \prec_{LTL} e$ (recall that \prec_{LTL} is a total order). Since $e', e \in C$ we have $\neg(e'\#e)$, and so e is a successful terminal of type II.

Theorem 7 If $\Sigma_{\neg \varphi}$ contains an illegal livelock then \mathcal{T} contains a successful terminal of type II.

Proof:

By Lemma 5 the unfolding of $\Sigma_{\neg \varphi}$ contains some *L*-configuration *C*. By Lemma 6, *C* contains a successful terminal *e* of type II.

We prove the following: either \mathcal{T} contains a type II successful terminal of C, or the unfolding of $\Sigma_{\neg \varphi}$ contains another L-configuration $C' \prec_{LTL} C$. Since \prec_{LTL} is well founded, \mathcal{T} must contain a type II successful terminal.

If \mathcal{T} does not contain any type II successful terminals, then in particular it does not contain e, and so \mathcal{T} must contain an terminal d < e which is not of type II(b).

We construct an L-configuration $C' \prec_{LTL} C$. We consider three possible cases, corresponding to the three possibilities for a terminal to be unsuccessful.

(1) d is a terminal of type I(a) or I(b).

Let d' be the companion of d. Since Mark([d']) = Mark([d]), there is an isomorphism f from $\uparrow[d]$ to $\uparrow[d']$. Define $C' = [d'] \cup f(C \setminus [d])$. Since d is a part-I event (in particular d is not an L-event), we have $BL(C) = [d] \oplus E$ for some nonempty set of events E. It holds that $BL(C') = [d'] \oplus f(E)$ and AL(C') = f(AL(C)). Since E is nonempty, we have $BL(C') \neq \emptyset$. Since AL(C') = f(AL(C)), we have |AL(C')| = |AL(C)|, and so AL(C') contains at least K + 1 events. Since $[d'] \prec_{LTL} [d]$ and \prec_{LTL} is preserved by finite extensions, we have $BL(C') \prec_{LTL} BL(C)$, and so $C' \prec_{LTL} C$.

(2) d is a terminal of type II(a).

Let d' be the companion of d. Since d is a terminal of type II(a), it is a part-II event. By Lemma 1(f), d' is also a part-II event. By Lemma 3(3), $\Sigma_{\neg \varphi}$ has an illegal livelock $M_0 \xrightarrow{\sigma} M \xrightarrow{\sigma_1}$ such that σ is a linearisation of BL(C).

We split σ_1 into two sequences, $\sigma_1 = \sigma_2 \sigma_3$, such that $\sigma \sigma_2$ is a linearisation of [d], and so

$$M_0 \xrightarrow{\sigma} M \xrightarrow{\sigma_2} Mark([d]) \xrightarrow{\sigma_3}$$

Now find a linearisation $\sigma'\sigma'_2$ of [d'] such that $M_0 \xrightarrow{\sigma'} M' \xrightarrow{\sigma'_2} Mark([d'])$. So we have

$$M_0 \xrightarrow{\sigma'} M' \xrightarrow{\sigma'_2} Mark([d']) = Mark([d]) \xrightarrow{\sigma_3}$$

which is an illegal livelock of $\Sigma_{\neg \varphi}$. By Lemma 5, there is a L-configuration C' such that σ' is a linearisation of BL(C'). It remains to prove $C' \prec_{LTL} C$. Since σ' is a prefix of $\sigma'\sigma'_2$, we have $BL(C') \subseteq [d']$. We now have

$$\begin{array}{cccc} BL(C') & = & BL([d']) & (BL(C') \subseteq [d']) \\ \prec_{LTL} & BL([d]) & (d \text{ is of type II(a)}) \\ & = & BL(C) & (BL(C) \subseteq [d]) \end{array}$$

It follows $C' \prec_{LTL} C$ (definition of \prec_{LTL}).

(3) d is a terminal of type II(c).

Let d' be the companion of d. Since Mark([d']) = Mark([d]), there is an isomorphism f from $\uparrow[d]$ to $\uparrow[d']$. Define $C' = [d'] \cup f(C \setminus [d])$.

We first prove BL(C') = BL(C). Since d is a terminal of type II(c), it is a part-II event. By Lemma I(f), d' is also a part-II event. So we have BL(C) = BL([d]) and BL(C') = BL([d']). Since d is of type II(c), BL([d']) = BL([d]), and we are done.

We now show that C' is a L-configuration such that $C' \prec_{LTL} C$. Since C is a L-configuration, $BL(C) \neq \emptyset$, and so, since BL(C') = BL(C), $BL(C') \neq \emptyset$. Since [d] is a terminal of type II(c), we have $|[d']| \geq |[d]|$, and so, since BL([d]) = BL([d']), $|AL(C')| \geq |AL(C)|$. Since C is a L-configuration, $|AL(C)| \geq K+1$. Finally, $C' \prec_{LTL} C$ is proved exactly as in case (2).

Finiteness of the tableau

We will now proceed to prove the following

Theorem 8 \mathcal{T} contains at most K^2 non-terminal events, where K is the number of reachable markings of $\Sigma_{\neg \varphi}$.

Using Lemma 1(f) we get that the reachable markings of $\Sigma_{\neg\varphi}$ can be divided into to disjoint sets, marking reachable by firing no *L*-transitions and markings reachable after firing some *L*-transition. Let K_I and K_{II} respectively denote the number of these markings, and so $K = K_I + K_{II}$.

We first consider the size of part-I.

Lemma 7 \mathcal{T} contains at most K_I^2 non-terminal part-I events.

Proof:

We proceed in three steps.

- (1) Let C be an configuration of \mathcal{T} containing only part-I events. If C contains more than K_I events labelled by transitions of I, then C contains a terminal.
 - Since all events labelled by transitions of I are causally related (see the Lemma 1(c)), C contains a chain $e_1 < \ldots < e_{K_I+1}$ of such events. By the pigeonhole principle, there are events $e_i < e_j$, $1 \le i, j \le K_I + 1$, such that $Mark([e_i]) = Mark([e_j])$. Now e_j is a type I terminal.
- (2) Let M be a reachable marking of $\Sigma_{\neg \varphi}$ without firing any L-transitions. \mathcal{T} contains at most K_I non-terminal part-I events e such that Mark(e) = M.
 - Assume the contrary, and let $e_1 \dots e_{K_I+1}$ be pairwise different non-terminal part-I events such that $Mark(e_i) = M$ for all $1 \le i \le K_I + 1$. By (1), we have $\#_I[e_i] \le K_I$ for all $1 \le i \le K_I + 1$. So there are two indices $i \ne j$ such that $\#_I[e_i] = \#_I[e_j]$. Since \prec_{LTL} is a total order, we have either $[e_i] \prec [e_j]$ or $[e_j] \prec [e_i]$. So by the definition of terminals of type I either e_i or e_j is a type I terminal.

(3) \mathcal{T} contains at most K_I^2 non-terminal part-I events. By (2), \mathcal{T} contains at most K_I non-terminal part-I events for each marking reachable without firing L-transitions, and so there are at most K_I^2 non-terminal part-I events.

We next consider the size of part-II.

Lemma 8 \mathcal{T} contains at most K_{II}^2 non-terminal part-II events.

Proof:

We use the same pattern as above and proceed in three steps.

- (1) Let C be an configuration \mathcal{T} containing some part-II events. If $|AL(C)| > K_{II}$, then C contains a terminal. If $|AL(C)| > K_{II}$, then C contains two part-II events e', e such that $\neg(e'\#e)$ and Mark([e']) = Mark([e]). By the definition of terminals of type II(b), e' or e is a terminal.
- (2) Let M be a reachable marking of $\Sigma_{\neg \varphi}$ after firing some L-transition. T contains at most K_{II} non-terminal part-II events e such that Mark(e) = M.

 Assuming the contrary, let E be a set containing more than K_{II} non-terminal part-II events such that Mark(e) = M for all $e \in E$. By (1), we have $|AL([e])| \leq K_{II}$ for all $e \in E$. By the pigeonhole principle, there are two different events e_1, e_2 such that $|AL([e_1])| = |AL([e_2])|$. We show that e_1 or e_2 is a terminal of type II. There are two possible cases:
 - (a) $BL([e_1]) \neq BL([e_2])$. If $BL([e_1]) \prec_{LTL} BL([e_2])$ then e_2 is a terminal (of type II(a)), otherwise e_1 is a terminal (of type II(a)).
 - (b,c) $BL([e_1]) = BL([e_2])$. Now $BL([e_1]) = BL([e_2])$ and $|AL([e_1])| = |AL([e_2])|$ implies $|[e_1]| = |[e_2]|$. Thus the larger one with respect to \prec_{LTL} is a terminal (of type II(b) or II(c)).

Therefore either e_1 or e_2 is a terminal, a contradiction.

(3) \mathcal{T} contains at most K_{II}^2 non-terminal part-II events. By (2), \mathcal{T} contains at most K_{II} non-terminal part-II events for each marking reachable after firing some L-transition, and so there are at most K_{II}^2 non-terminal part-II events.

Now by Lemmas 7 and 8 we get that \mathcal{T} contains at most $K_I^2 + K_{II}^2 \leq K^2$ non-terminal events.

29

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