A Tool for Verification and Simulation of Population Protocols

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Overview

Population Protocols: models for distributed systems of mobile agents

Can solve many classical distributed tasks:

- Leader election
- Majority voting

Creating new protocols is error-prone



Contribution: A Python library for

- Specification
- Simulation
- Verification





- Models for distributed systems
- Agents have limited computational power
- Agents are passively mobile
- Agents are anonymous







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• Agents are in one of finitely many states







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- Configuration: Multiset of states of agents







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- When agents interact their states change





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- Configuration: Multiset of states of agents
- When agents interact their states change
- Agents have output true/false
- Consensus: All agents have same output

Population Protocols

Definitions

Protocol
$$P = (Q, I, \delta, \omega)$$

Q: a finite set of states

 $I \subseteq Q$: the set of initial states

 $\delta \subseteq Q^2 \times Q^2$: the transition relation

 $\omega:Q \to \{0,1\}$: the output function

Transition $t = a, b \rightarrow a', b'$ is enabled in C if $C = \{a, b, ...\}$ \Rightarrow Applying t to C results in $C' = \{a', b', ...\}$

The Flock-Of-Birds Predicate

- ▶ Birds with normal or elevated temperature
- ► Given N, are there at least N birds with elevated temperature?
- ightharpoonup Example for N = 3

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The Flock-Of-Birds Predicate

linear flock-of-birds protocol

$$N = 3$$

States: 0, 1, 2, 3

Transitions:



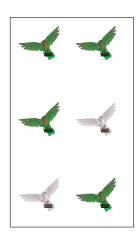
(k) , (j) \rightarrow (N) if $k+j \geq N$

Initial states:



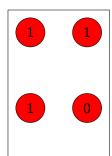
Output Function:

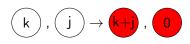




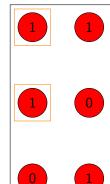


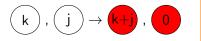
 $(k), (j) \rightarrow (N), (N)$

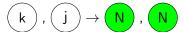


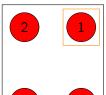


k, $j \rightarrow N$, N



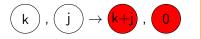


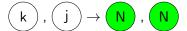


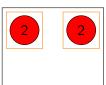






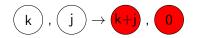


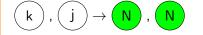










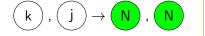


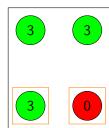


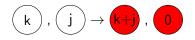




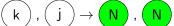








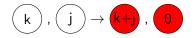
(k), (j

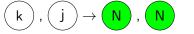


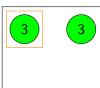






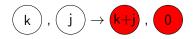


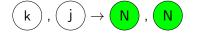








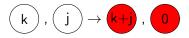












$$\begin{pmatrix} k \end{pmatrix}, \begin{pmatrix} j \end{pmatrix} \rightarrow \begin{pmatrix} N \end{pmatrix}, \begin{pmatrix} N \end{pmatrix}$$

Well Specification and Correctness

Execution: infinite sequence of subsequent configurations from some initial configuration C

Convergence: outputs of agents stabilize to consensus ("lasting consensus")

Fairness: execution is fair if all configurations that are reachable infinitely often appear infinitely often

Well Specification: all fair executions starting at same initial configuration converge to the same value

Fixed-Size Well Specification: well specified up to given size

Computing a predicate $f:I^{\mathbb{N}}\to\{0,1\}$: all fair executions from initial configuration C converge to f(C)

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⇒ Automatically verifying a protocol?

Existing Tools

- bp-ver: fixed-size verification through graph exploration
 Chatzigiannakis, Michail and Spirakis SSS'10
- Verification with PRISM/SPIN
 Clment, Delporte-Gallet, Fauconnier and Sighireanu ICDCS'2011
- ▶ PAT: Model checker with global fairness
 - Sun, Liu, Dong and Chen TASE'2009
- peregrine: parametric verification for a subclass of protocols
 Blondin, Esparza, Jaax, Meyer PODC'2017

A New Library For Population Protocols

Available under gitlab.lrz.de/ga96jib/tool_for_population_protocols

Features:

- Specifying protocols
- Specifying configurations
- Simulating protocols
- Verifying protocols
- Exporting protocols to PRISM/peregrine

A New Library For Population Protocols

```
output_function = lambda x: x == N
transitions = [(k, j, k + j, 0) \text{ if } k + j < N \text{ else } (k, j, k + j, k + j)
    \hookrightarrow N, N) for k in range(N + 1) for j in range(N + 1)]
initial_states = {0, 1}
flock = Protocol(transitions, initial_states,
    → output_function)
C = Population([0, 1, 1, 1, 1])
flock.average_convergence_steps(initial_population = C,
    → num_iterations = 50)
flock.well_specified(size = 10, expected_output = lambda
    \rightarrow x: x.amount(1) >= N
export.export_to_prism(flock, initial_population = C)
```

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Features:

- Specifying protocols
- Specifying configurations
- Simulating protocols
- Verifying protocols
- Exporting protocols to PRISM/peregrine
- **⇒** Tested on existing protocols
- ⇒ Devised a new protocol as a case study

A New Protocol For Flock-Of-Birds

Problem: existing protocols for flock-of-birds need an amount of states linear in N.

Goal: find a protocol that needs less states

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⇒ Prime-Flock-protocol

Example:
$$N = 12 = \underbrace{2}_{p_1} \cdot \underbrace{2}_{p_2} \cdot \underbrace{3}_{p_3}$$

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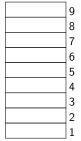
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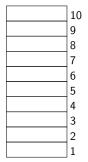
Example:
$$N = 12 = \underbrace{2}_{p_1} \cdot \underbrace{2}_{p_2} \cdot \underbrace{3}_{p_3}$$

	8
	7
	6
	5
	4
	3
	6 4 3 2
	1

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8
7
6
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2
1

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$$N = 12 = \underbrace{2}_{p_1} \cdot \underbrace{2}_{p_2} \cdot \underbrace{3}_{p_3}$$

Existing approach:

Prime-Flock-protocol:

	12
	11
L	10
	9 8
	7
	6
L	5 4 3 2 1
	4
L	3
	2
L	1

 $1 = 1_1$

Example:
$$N = 12 = \underbrace{2}_{p_1} \cdot \underbrace{2}_{p_2} \cdot \underbrace{3}_{p_3}$$

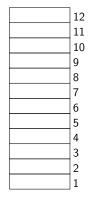
Existing approach:

12
11
10
9
9 8 7
6
5
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3
6 5 4 3 2
1

$$\begin{array}{c|c}
2\\
1=1
\end{array}$$

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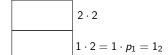
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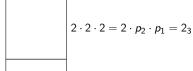
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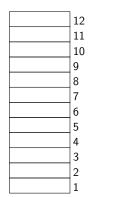
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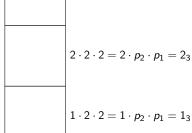
$$1 \cdot 2 \cdot 2 = 1 \cdot p_2 \cdot p_1 = 1_3$$

Example:
$$N = 12 = \underbrace{2}_{p_1} \cdot \underbrace{2}_{p_2} \cdot \underbrace{3}_{p_3}$$

Existing approach:



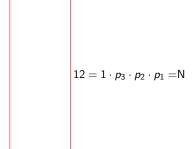
${\sf Prime-Flock-protocol:}$



 $3 \cdot 2 \cdot 2$

Example:
$$N = 12 = \underbrace{2}_{p_1} \cdot \underbrace{2}_{p_2} \cdot \underbrace{3}_{p_3}$$

Existing approach:



```
N = p_1 \cdot p_2 \cdots p_n

States:
1_1, 2_1, \dots, (p_1 - 1)_1
1_2, 2_2, \dots, (p_2 - 1)_2
\vdots
1_n, 2_n, \dots, (p_n - 1)_n

N

Transitions:
```

$$i_k, j_k \rightarrow (i+j)_k, 0$$
 $i+j < p_k$
 $i_k, j_k \rightarrow 1_{k+1}, ((i+j)-p_k)_k$ $i+j \geq p_k$
 $N, x \rightarrow N, N$ $\forall x \in Q$

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1_1, 2_1, \ldots, (p_1-1)_1
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1_n, 2_n, \ldots, (p_n-1)_n
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$$|Q|$$
 in $O(\sum_{i=1}^n p_i)$

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1_n, 2_n, \ldots, (p_n-1)_n
   Transitions:
                 i_k, j_k \rightarrow (i+j)_k, 0
                                                                           i + j < p_k
                 i_k, i_k \to 1_{k+1}, ((i+i) - p_k)_k
                                                                           i+j \geq p_k
                  N, x \rightarrow N, N
                                                                               \forall x \in Q
   |Q| in O(\sum_{i=1}^n p_i)
   \mathsf{Proof} \Rightarrow \mathsf{Thesis}
```

Probability Distributions

How do we choose the next transition in each step?

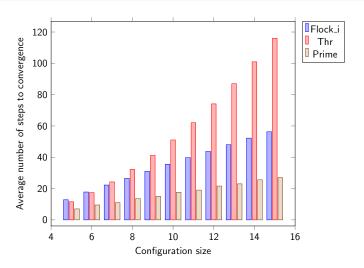
Uniform rules scheduling: Choose uniformly at random among enabled transitions

Uniform pairs scheduling: Choose two agents uniformly at random from configuration, then choose uniformly at random among transitions for the states of these agents

⇒ Compare convergence behaviour of protocols for both

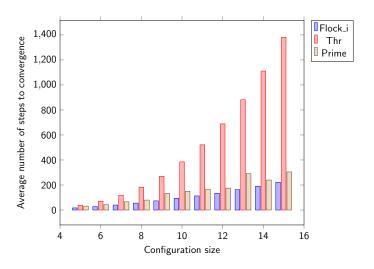
Comparing Protocols For Flock-Of-Birds

Uniform rules scheduling



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Uniform pairs scheduling



Summary

- New Python library for specifying, simulating and verifying population protocols
- ► New protocol computing the flock-of-birds predicate that uses less states than existing protocols

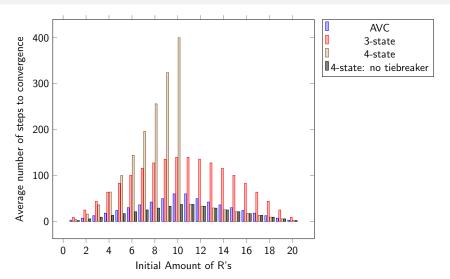
Outlook - future work

- multiple transitions in one step
- export to more model checkers
- optimizing verification
- flock-of-birds: lower bound for states?

Thank you!

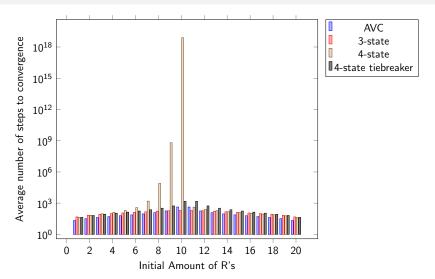
Comparing Protocols For The Majority Predicate

Uniform rules scheduling



Comparing Protocols For The Majority Predicate

Uniform pairs scheduling



```
R: [0..4] init 2;
B: [0..4] init 2;
"0": [0..4] init 0;
"1": [0..4] init 0;
```

Arbitrary Probability Distributions

```
[] R = 2 & B = 2 & "0" = 0 & "1" = 0 ->

1.0: (R'=R-1) & (B'=B-1) & ("0"'="0"+1) & ("1"'="1"+1);

[] R = 1 & B = 1 & "0" = 1 & "1" = 1 ->

0.25: (R'=R-1) & (B'=B-1) & ("0"'="0"+1) & ("1"'="1"+1) +

0.5: ("1"'="1"-1) & ("0"'="0"+1) +

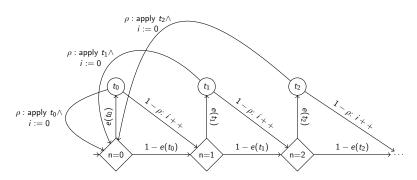
0.25: ("0"'="0"-1) & ("1"'="1"+1)

[] R = 0 & B = 0 & "0" = 2 & "1" = 2 ->

1.0: ("0"'="0"+1) & ("1"'="1"-1);
```

Nondeterministic Endocing for Uniform Distributions

Deterministic Endocing for Uniform Distributions



$$e(t_x)=1$$
 if t_x is enabled, else 0 $ho=(i+1)/T$, where $T=\sum_x e(t_x)$